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APPLICATION OF ROTORCRAFT FLIGHT SIMULATION PROGRAM (C81) TO PREDICT ROTOR PERFORMANCE AND BENDING MOMENTS FOR A MODEL FOUR-BLADED ARTICULATED ROTOR SYSTEM

F. D. Freeman, et al

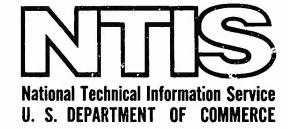
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This report has been reviewed by the Eustis Directorate, U. S. Army Air Mobility At Research and Development Laboratory and is considered to be technically sound. The purpose of this program was to verify the capability of the Rotorcraft Flight Simulation Program (C-81) to predict rotor performance and load through correlation with model rotor data. Results are inconclusive due to problems apparently related to threedimensional and/or unsteady effects, which are especially significant for model scale rotors and which are not fully understood in the state of the art.

The program was conducted under the technical management of Edward E. Austin of the Technology Applications Division.

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Four sets of model H-34 helicopter rotor blades were built and tested by the Sikorsky Aircraft Corporation. Rotorcraft Flight Simulation Program with Aeroelastic Rotor Representation, Program C81, was used to predict rotor performance and blade bending moments for comparison with the test results. Performance predictions made using the steady-state two-dimensional airfoil data			
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characteristics at much lower rotor lift levels than recorded in the tunnel test. Application of unsteady aerodynamic and yawed flow effects did not sufficiently improve the performance correlation. The lift and stall characteristics of the model rotor in the tunnel were found to be very similar to full-scale ($\rm R_{N} = 12 \times 10^{6})$ 0012 airfoil properties.

Accordingly, a modified airfoil table was used to predict bending moments. The modified airfoil table employed a full-scale 0012 lift table, the GFE model drag table with an increment of $C_{\rm D}=0.003$ added to all values, and a null pitching moment table.

Bending moment correlation was made using the modified airfoil tables in the calculations. These comparisons are presented as time histories and as harmonic analyses. Calculated loads show good agreement with measured loads for the fiberglass blade set having -8 degrees of twist. The other blade set computations are less satisfactory. Generally, calculated loads are lower in magnitude than measured loads and do not have the higher harmonic content of the measured bending moments.

A correlation criterion and a sensitivity analysis were developed to analyze the results of the correlation study. The correlation criterion was applied to the performance comparisons. Applications to the loads comparisons were not made because it became evident in the latter stages of the project that the method did not represent load differences in a useful manner.

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DESCRIPTION OF COMPUTER PROGRAM

Rotor performance and loads for this project were calculated by Rotorcraft Flight Simulation with Aeroelastic Rotor Representation, Program C31. This program was delivered to the U. S. 'rmy under Contract DAAJ02-70-C-0063. The program is completely described in Reference (1). Following is a brief summary of the program.

Program C81 is a general-purpose rotorcraft flight simulation program capable of analyzing an entire rotorcraft in level or maneuvering flight. However, for the purposes of this study, only the rotor simulation capability was used. The rotor simulation is divided into a trim procedure and a loads calculation portion. The trim procedure iterates on the independent variables (collective pitch, fore and aft and lateral cyclic pitch, and fore and aft and lateral lapping angles) to balance the forces and moments acting on the rotor. For this project, the program trim procedure was modified to iterate to those control positions necessary to give zero fore and aft and lateral flapping. After a trimmed flight condition is obtained, the rotor loads calculations are performed as described below.

The rotor loads procedure is a fully coupled time-variant aeroelastic analysis based on the modal technique. Modes and natural frequencies must be calculated in a separate program and input into Program C81. The modes and natural frequencies used in this study were generated by a program based on the Myklestad procedure.

For a specified rotor speed, the Myklestad program generates a set of fully coupled modes having beam, chord, and torsional components as a function of control system stiffness; blade twist; beam, chord, and torsional stiffness; weight distribution; beam and chord moments of inertia; neutral axis and center-of-gravity locations at twenty radial stations; centrifugal stiffening; centrifugal restoring torsional moment; and hub impedance.

Rotor airloads are calculated by C81 at 20 radial stations for each azimuth location as a function of the local angle of attack and local Mach number to include the effects of stall and compressibility. The effects of both rigid body and elastic displacements and velocities are included in these calculations. Also included at the user's option are nonsteady aerodynamic and yawed flow effects. Airfoil lift, drag, and pitching moment coefficients may be input as tables of discrete values or in equation form.

Inertia forces due to the unsteady motion of the frame of reference and calculated airloads are summed to form the forcing function portion of the modal equations. The total timevariant response of the blade is then obtained by summing the response of each input mode shape. Bending moments are computed by summing the products at each radial station of modal bending moment coefficients and modal participation factors. The bending moment coefficients for each mode are computed as a function of blade mass, rotor speed, mode shape, and mode natural frequency by considering the moments generated by the inertia forces and centrifugal forces.

Rotor performance and blade bending moment information is presented at the end of each Program C81 simulation. The performance information is given in both dimensional and nondimensional form. Bending moments are presented as sine and cosine harmonic analysis components. A complete time history of any rotor performance and load calculations may be obtained by entering the maneuver portion of the program. This section numerically integrates the equations of motion to give the time history, which may be plotted either as printer plots or as CALCOMP plots.

DESCRIPTION OF BLADE PROPERTIES

The blade dynamic and aerodynamic data were obtained by Sikorsky Aircraft Corporation under Contract DAAJ02-72-C-0026. The complete description of the experimental techniques is described in Reference (2). These data are summarized below.

DYNAMIC PROPERTIES

The model rotor blades examined in this project were scaled from the Sikorsky H-34 helicopter rotor system. The geometric scale factor applied was 6.109. The four blades are described as follows:

- 1. Fiberglass spar, zero twist
- 2. Fiberglass spar, -8° uniform twist
- 3. Fiberglass spar, zero twist with 5° trailing-edge flap (over aft 20% of chord)
- 4. Aluminum spar, zero twist

All blade sets had the same nominal weight and inertia distributions. The aluminum blades, however, were approximately three times stiffer than the fiberglass blades. Blade stiffness, inertia, and geometry information are given in Tables 1 through 4.

The tabulated blade stiffness and inertia properties were apportioned in twenty equal segments to match the input format of Program C81. These equal segment length data are shown in Tables 5, 6, and 7. Calculated frequencies and generalized inertias are given in Table 8. Blade inertia and center of gravity values were apportioned on a pro rata basis. The unequal segment length stiffness values were combined into equal segment length values by using the following relation:

$$\frac{\ell_1 + \ell_2 + \dots + \ell_{n-1} + \ell_n}{\text{EI}_{EO}} = \frac{\ell_1}{\text{EI}_1} + \frac{\ell_2}{\text{EI}_2} + \dots + \frac{\ell_n}{\text{EI}_n}$$
 (1)

where

 I_{EQ} = an equivalent area moment of inertia for a beam composed of n subsequents having different area moments of inertia, I_1 , I_2 , ..., I_n , and lengths I_1 , I_2 , ..., I_n , and lengths

This procedure yields an equivalent beam segment which rotates an amount equal to that of a beam made up of the n subsegments when both beams are subjected to the same moment.

AERODYNAMIC PROPERTIES

Two sets of aerodynamic data are presented for this project. These are the model two-dimensional airfoil data and the modified airfoil data used for loads predictions (explained and presented in the Model Rotor Aerodynamic Investigation section of this report).

The model lift, drag, and pitching moment coefficients are presented in Figures 1, 2, and 3 for the symmetrical (unflapped) blade section and in Figures 4 5, and 6 for the blade section having the 5° trailing-edge flap. The full-scale 0012 lift table characteristics used in the modified airfoil table are presented in the Model Rotor Aerodynamic Investigation section of this report.

PRETEST PREDICTIONS

PRELIMINARY CALCULATIONS

The two baseline conditions for performance calculation were chosen to be (1) μ = 0.30, M = 0.40, and C_L/σ = 0.082, and (2) μ = 0.40, M = 0.438, and C_L/σ = 0.045. These baseline points were selected because they appeared to be representative of the conditions contained in Reference (3).

Computer Program C81 was used to make initial performance calculations. The results obtained are shown in Figure 7, which illustrates that the predicted stall is much below the scheduled $C_L/\sigma=0.082$. As a result of these calculations, the scheduled C_L/σ values were reduced by 40 percent. The baseline conditions were then $C_L/\sigma=0.049$ and $C_L/\sigma=0.027$. Also shown in Figure 7 are calculations made using the full-scale 0012 airfoil tables contained in C81 and measured results for the fiberglass blade with -8 twist. These two items will be discussed later in the text.

VARIATIONS ABOUT BASELINE CONDITIONS

One hundred sixty-two C81 trim cases were completed to match the scheduled wind-tunnel test points. These cases were performed about the baseline trim points for the fiberglass blade with -8° twist to determine the sensitivity of performance and loads to variations (+2°) in mast tilt, collective pitch, longitudinal and lateral cyclic pitch. These cases are analyzed in the Initial Rotor Performance Correlation section of this report. The baselines for the fiberglass, -8° twist blade are given in Figure 8.

Additional cases were calculated for each baseline condition for the three other sets of blades which were not included in the 162 cases. These additional trim cases are presented in Figures 9, 10, and 11.

CORRELATION CRITERION

A correlation criterion must exist to judge comparisons of experimental data and calculated predictions. This section describes the criterion used to quantify the results of this project.

Performance and bending moment data may be compared point to point or statistically, using curve fits to relate results. Each method has its benefits and drawbacks. Point-to-point comparisons yield readily understandable results for each set of points examined, but they do not indicate trends. A statistical representation compacts large amounts of information and describes trends; but, when taken alone, it tends to hide individual deviations. Therefore, use of both procedures is advisable.

A quality factor, abbreviated q, is used with the point-topoint and statistical comparisons. For point-to-point comparisons, a percentage of difference is used, given by

$$q = \frac{|\text{measured - computed}|}{\text{measured}} \times 100\%$$
 (2)

The statistical approach involves a different definition, which is given later in this section. Ranges of q are given in Table 9. These values were picked from experience considering the ranges of accuracy needed by the designer.

The basis of the statistical method is to plot like quantities (having the same independent parameters, μ , M_1 90, $\theta_{3/4}$, and α_m) of measured data versus computed predictions and to fit a first-order least-squared error criterion curve fit through the points. The correlation criterion may then be applied to the parameters describing the fitted line. The line has three properties which describe its relation to the data. These are its slope, intercept, and the scatter of data about the line. If measured data (y) is plotted against computed predictions (x), a line fitted through the points using the least-squared error criterion will have the following form:

$$y' = ax + b \tag{3}$$

where

y' = the predicted value of y

$$a = \frac{\sum xy - n\overline{x}\overline{y}}{\sum x^2 - n\overline{x}^2}$$
 (4)

$$b = \frac{\overline{y} \Sigma x^2 - \overline{x} \Sigma xy}{\Sigma x^2 - n\overline{x}^2}$$
 (5)

and

$$n = the number of samples$$
 (6)

A correlation coefficient may be defined as

$$r^2 = 1 - \frac{S_e^2}{S_y^2} \tag{7}$$

where

$$S_e^2 = \sum \frac{(y-y')^2}{n-1}$$
, the variance of the estimate (9)

$$\overline{y} = \frac{\sum y}{n}$$
, the mean of the data (10)

$$S_y^2 = \sum \frac{(y-\overline{y})^2}{n-1}$$
, the variance of the data about its mean. (11)

The quantity r^2 may be interpreted as the percentage of the variance (S 2) which is contributed by the fitted linear relation for y'. It is, therefore, a statistic which describes the usefulness of the fitted line for estimating purposes.

Perfect correlation, according to the preceding definitions, is represented by a=1, b=0, and r=1. The terms a and r are independent of the magnitude of the variables; however, b is magnitude dependent. Therefore, b is normalized by the average value of the independent variable and subtracted from one so that unity will continue to represent perfect correlation. The term b is replaced by

$$b' = 1 - b/\overline{x} \tag{12}$$

The quality factor may now be defined (in a percentage of error sense) to be

$$q_a = (1-a) \times 100\% \text{ for } a < 1$$

or
$$q_a = (a-1) \times 100\%$$
 for $a > 1$ (13)

$$q_b = (1-b') \times 100\% = b/\bar{x} \times 100\%$$
 (14)

$$q_r = (1 - r) \times 100\%$$
 (15)

The quality factory, q, may then be judged by the stated criteria given in Table 9.

The procedure described here follows Hoel, "Introduction to Mathematica: Statistics" (Reference 4).

INITIAL ROTOR PERFORMANCE CORRELATION

Because of the large quantity of data, and the possibility that the actual wind tunnel test points would not match those used in the previous calculations, statistical techniques were used to analyze the data. The following data were subjected to a multiple correlation analysis:

Independent Variables

Dependent Variables

$$\mu$$
, M , α_{mast} , $\theta_{3/4}$, α_{1} , α_{1} , α_{1} , α_{1} , α_{1} , α_{2} , α_{3} , α_{2} , α_{3} , α_{3} , α_{2} , α_{3} , α

$$C_{L}/\sigma$$
, C_{D}/σ , C_{Y}/σ
 C_{1}/σ , C_{m}/σ , C_{n}/σ

For a specified dependent variable, the multiple correlation analysis picks, in order of descending importance, the independent variables that may be used in a linear combination to express the dependent variable. Within the 162 computer cases run, the rotor lift can be statistically represented by

$$C_{L}/\sigma_{calc} = .00824 + .004 \alpha_{TPP} + .00693 \theta_{3/4}$$
 (16)

The multiple correlation coefficient for the above equation is r = 0.951, which means that (.951) 2 x 100 = 90.5% of all variations of C_L/σ can be represented by variation in α_{TPP} and $\theta_{3/4}$. The standard error is $S_e = 0.009$, which can be interpreted as a confidence limit that the computed $\boldsymbol{C}_{T}/\sigma$

will be within +0.009 of the value predicted by the above equation in 65 percent of the cases and within +2x(0.009) =+0.018 in 95 percent of the cases.

All measured data for the fiberglass -8° twist blade were also subjected to the multiple correlation analysis. The results were

$$C_L/\sigma_{meas} = .01854 + .00456 \alpha_{TPP} + .0066 \theta_{3/4}$$
 (17) with a correlation coefficient of r = 0.911

The calculated and measured lift coefficients may be compared by examination of the above relations. The partial derivatives giving the rate of change of lift with respect to tip path plane attack angle and collective setting are within 12 percent. The difference between the constant terms is

due to the low values of $\mathbf{C}_{\underset{\text{max}}{L_{\text{max}}}}$ in the 2-D wind tunnel data.

The analysis was performed on the calculated and measured power. The results were as follows:

$$G_{P}/\sigma_{meas} = 0.00006 + .00069 \theta_{3/4} + .00010 \alpha_{TPP}$$
 (18)

$$r = 0.928$$

$$C_{P}/\sigma_{calc} = 0.00020 + .00061 \theta_{3/4} + .00015 \alpha_{TPP}$$

$$r = 0.960$$
(19)

It should be recalled that the correlation analysis is based on linear theory and, therefore, any nonlinear relationship among the variables is deleted. Since the multiple correlation analysis is free to select any of nine independent variables, it is significant that collective pitch and tip path angle of attack were always selected as the best predictors of rotor thrust and power. The fact that these selections were made for both the measured and calculated values tends to validate the mathematical model of the rotor.

The statistical representation of the measured and calculated gross rotor performance is shown in Figures 11 and 12. The computed results used in this analysis are tabulated in Table 9. The computer subroutines used in the multiple regression analysis are described in Reference (5).

SENSITIVITY ANALYSIS

An analysis was developed to relate the sensitivity of predicted results to input parameter variations. Twenty-six individual variations of significant input parameters were made for the two baseline correlations ($C_L/\sigma=0.049$ and $C_L/\sigma=0.027$) using the model aerodynamic data. However, as explained in the Performance Comparisons Section of this report, the program could not accurately represent the model rotor tunnel behavior using the model steady aerodynamic data. This fact, coupled with apparent discrepancies in the model two-dimensional data apart from any program considerations, made the sensitivity analysis calculations generally suspect. Consequently, these calculations are not presented in this report. However, the mathematical procedure for the sensitivity study is considered valid and very useful for future studies. Therefore, the analysis is presented here for information only.

If the standard deviation for an input, x_i , is σ_i , then the standard deviation of an output quantity, y, may be written

$$\sigma_{y}^{2} = \sum_{i=1}^{n} \left(\frac{\partial_{y}}{\partial x_{i}} \sigma_{i} \right)^{2} \tag{20}$$

where

$$n = number of input variables, x$$
 (21)

$$\frac{\partial y}{\partial x_i}$$
 = rate of change output, y, with respect to input, x_i . (22)

To employ this method, a value must be assigned to each input parameter standard deviation. These values should be assigned from the results of a large sample test of the values of each quantity. Lacking this information, a judgment must be made to relate the standard deviation to confidence levels (given in plus and minus percent error about a nominal value).

If, after the determination of $\sigma y,$ the computed value and measured value of y are compared and are such that

$$|y - y_{\text{measured}}| < 2\sigma y$$
 (23)

then there is a 95 percent probability that the variation between the measured and computed values is due to input parameter variation.

The method given here follows Bendat and Piersol (Reference 6).

POSTTEST PERFORMANCE CORRELATION

Performance comparisons of calculated and measured results were made for the following cases:

Fiberglass blade, -8° twist, $\delta_{F} = 0^{\circ}$	μ 0.299	^M 1,90 0.408
	0.400	0.435
	0.502	0.467
Fiberglass blade, 0° twist, $\delta_{F} = 0^{\circ}$	0.299	0.408
Fiberglass blade, 0° twist, $^{6}_{F} = 5^{\circ}$	0.299	0.408

Comparisons of measured and calculated results are shown in Figures 14 through 33. All calculated results shown in these figures were made using the model airfoil data. Performance comparisons for the aluminum, 0° twist blade are not shown since the analysis used in this portion of the study is a quasi-static analysis (using steady and 1/rev blade response) which does not yield results different from those for the fiberglass, 0° twist blade. Basic comparisons are presented as plots of lift versus control plane angle of attack, power versus lift, measured lift versus calculated lift, and measured power versus calculated lift versus calculated lift and measured power versus calculated power are not shown for the fiberglass, -8° twist blade at the μ = 0.502, $M_{1.90}$ = 0.467 condition because insufficient measured data were available for a statistical analysis.

Examination of the plots shows that measured and calculated lift values are in close agreement at low collective values. Calculated power is generally lower than measured. As collective pitch increases, the calculated lift shows stall characteristics at a much lower pitch angle than the measured lift. These stall characteristics are best compared in the power versus lift plots. These figures show calculated stall to be extremely abrupt. For instance, in Figure 15 a maximum calculated lift coefficient of $C_{\rm L}/\sigma=0.07$ has been reached while calculated power increases asymptotically. Calculated stall is most severe for the blade set with the 5° trailing-edge flap (Figure 31), as expected. The measured stall characteristic for this case is hardly in evidence, no more so than for the unflapped blade at the same condition (Figure 27). Figures 18 and 19 illustrate the effect of the Program C81 unsteady aerodynamic and yawed flow representations on the calculated lift and power for the fiberglass blade with -8°

twist (compare with Figures 14 and 15). Though these effects increase the calculated lift at high collective settings, stall still occurs much more abruptly than in the measured results. Table 10 presents quantitative comparisons of measured and calculated lift and power and also grades the correlation according to the correlation criteria given in Table 9.

Because the measured data examined in this portion of the study showed such delayed stall characteristics when compared with the calculated results using the model data, further investigation was indicated. This investigation took the form of a brief correlation study for a full-scale rotor system and a consideration of the aerodynamics of model rotors. The results of these studies are given in the next two sections.

FULL-SCALE COMPAF SONS

Program C81 was used to predict performance and bending moments for a full-scale H-34 rotor system. The experimental data for this comparison are published in USAAVLABS Technical Report 68-3 (Reference 3) and NASA TND-4632 (Reference 7). All blade dynamic properties for these comparisons were estimated from the figures and plots given in TR68-3. The aerodynamic properties were those of standard 0012 tables used at Bell Helicopter.

Performance comparisons for various mast tilt angles are given in Figures 34 through 39. Figures 34 through 36 compare measured and calculated lift, drag, and horsepower with collective pitch as the independent parameter, while Figure 37 shows measured and calculated power versus lift. As may be seen, the calculated performance para iters show very good qualitative agreement with the measured data. Lift error is a maximum of 900 lb for the 0° mast tilt case at $^63/4 = 2^\circ$, amounting to 18 percent of the measured, and decreases with increasing collective pitch. Drag error is about 500 lb or approximately 30 percent of measured for the 10° mast tilt case. Maximum power error is approximately 200 hp or about 16 percent of measured. Figure 37 illustrates that the full-scale rotor stall characteristics are predicted very accurately.

Figures 38 and 39 compare experimental lift to calculated lift and experimental power to calculated power. This method of presentation allows application of the correlation method described previously. First-order least-squared error criterion prediction lines for each of these plots are described by

$$C_{L}/\sigma_{meas} = 0.0118 + 0.923 C_{L}/\sigma_{calc}$$
 (24)

with r = 0.989 and C_L/σ = 0.061

and

$$C_{P}/\sigma_{meas} = 0.0000583 + 1.014 C_{P}/\sigma_{calc}$$
 (25)

with r = 0.957 and $C_p/\sigma = 0.00239$.

The quantities a(a'), b(b'), and r (slope, normalized intercept, and correlation coefficient as defined previously) for lift and power may be expressed as

Lift:

$$a = 0.923 (q = 7.8\%)$$
 (26)

$$b' = 1 - \left(\frac{b}{C_L/\sigma}\right) = \left(1 - \frac{0.0118}{0.061}\right) = 0.807 \tag{27}$$

$$(q = 19.3\%)$$

$$r = 0.989 (q = 1.1\%)$$
 (28)

Power:

$$a = 1.014 (q = 1.4\%)$$
 (29)

$$b' = \left(1 - \frac{b}{C_p/\sigma}\right) = \left(1 - \frac{0.0000583}{0.00239}\right) = 0.976$$
 (30)

$$(q = 2.44\%)$$

$$r = 0.957 (q = 4.3\%)$$
 (31)

Application of the correlation criterion stated in Table 9 grades the lift slope correlation as good, lift intercept as poor, and lift correlation coefficient as excellent. Application of the criterion to power grades the power slope as excellent, power intercept as excellent, and power correlation as excellent.

Figures 40 and 41 compare measured and computed bending stresses. The Program C81 beamwise stress predictions are higher in the midspan region than the measured, but are in good agreement inboard of r/R = 0.35 and outboard of r/R = 0.70. However, the predicted chordwise stresses are low in the inboard regions and quite good outboard of approximately r/R = 0.40.

MODEL ROTOR AERODYNAMIC INVESTIGATION

This section presents a brief examination of the performance correlation problems described in the Posttest Performance Correlation section. The model rotor aerodynamics were examined and a modified airfoil developed which produced reasonable performance correlation.

Rotor stall characteristics are compared in Figures 42 and 43. Figure 42 presents measured power, computed power (using model data tables), and measured oscillatory moment (at r/R=0.20) plotted against lift. The case presented is at $c_m=2^\circ$ to represent a forward flight condition. The plotted power figures are modified by removal of induced power and parasite power to isolate aerodynamic effects. These terms are approximated by simple momentum theory and are not exact. They are

Induced power coefficient = $C_{P_i}/\sigma = (C_L/\sigma)^2 \sigma/2\mu$

Parasite power coefficient = $CP_D/\sigma = \mu(C_X/\sigma)$

(where C_χ/σ is the rotor x-force coefficient in the wind axes).

Figure 42 clearly illustrates that measured power and measured torsional moment "break" together, further evidence that the phenomenon observed is stall. The computed power breaks well before the measured power. This observation is considered further evidence that computations made with the model airfoil tables do not represent the rotor as it behaves in the tunnel. Figure 43 is another power versus lift plot which presents comparisons of measured data and predictions computed using Program C81 and Program F-35 (Ref. 8), a Bell Helicopter rotor performance program. Both computations were made using the model airfoil data tables to check the programs against each other. As may be seen, both programs compute essentially the same stall characteristics.

The results described above, the stall characteristics observed in the Posttest Ferformance Correlation, and the full-scale comparisons all suggest that the performance correlation problems were caused by the stall characteristics of the model airfoil data. It is well known that the Reynolds number and the Mach number can have significant effects on blade aerodynamic coefficients. The 2-D airfoil tests performed by Sikorsky were designed specifically to obtain the necessary steady-state data to be used in the flight simulation program. These data are presented in Figures 1, 2, and 3. Of particular interest is the maximum lift coefficient $C_{L_{\mbox{max}}}$ as a function of Mach number shown in Figure 44. Also shown for comparison are values of

Clmax from synthesized airfoil tables developed from a Bell in-house hovering rotor test and a Sikorsky hovering rotor test (Reference 9). The Bell test was conducted with a two-bladed 2.25 in. chord, 14 in. radius blade. Three twist combinations and three tip Mach numbers were examined and two-dimensional data were developed that correlated the measured performance for all three rotors at all three Mach numbers. This approach has been used by NACA (Reference 10) to synthesize airfoil data from test results. Both sets of synthesized data contain significantly higher maximum lift coefficient values when compared to the model two-dimensional data. The conclusion must be that the model data is unreasonably low or that unusual effects caused the synthesized data to be unexpectedly high.

The model two-dimensional airfoil data was used to predict performance at μ = 0.299, M_{1,90} = 0.408 and α_m = 0° as shown in Figure 7. When the model data are used, stall occurs at approximately CL/ σ = 0.075. These values are considerably below the measured lift values shown for this condition. If full-scale 0012 airfoil data are used, the stall point is increased to 0.106. Comparison between the measured and full-scale lift values indicates that the full-scale data more nearly approximates the behavior of the rotor in the tunnel.

The exact reason for the discrepancy between measured and calculated results is not well understood; however, it may be related to "centrifugal pumping". Centrifugal pumping refers to the tendency for the centrifugal force to push the turbulent boundary layer, which occurs with blade stall, out of the blade. As the turbulent volume is removed, the flow reattaches to the airfoil and thus the stall conditions are removed. The effect may be more significant for model rotors than for full-scale rotors because of the increased centrifugal force field.

Since the model behavior in the tunnel seemed to be best described by full-scale rotor aerodynamic characteristics, a modified airfoil table was assembled to permit bending moment calculations to be made. The table used for the three blades without the trailing edge flap contained a full-scale $(R_N=12\times 10^6)$ lift table, the model drag table with an increment added uniformly to all values ($\Delta C_D=0.003$), and a null pitching moment table. Figure 45 presents the lift characteristics of the full-scale 0012 tables used in the modified tables. Drag characteristics may be obtained from the model drag properties shown in Figure 2 by adding the increment. Figures 46 through 50 present representative effects of the modified airfoil on performance calculations. Different increments were used for the flapped airfoil. These were $\Delta C_L=0.15$ added to the full-scale lift table and $\Delta C_D=0.005$ added to the model drag table.

The fitted lines relating the measured and calculated lift and power in Figures 49 and 50 have the following values for a, b', and r:

Lift:

a = 0.944 (q = 5.6%)
b' = 1 -
$$\frac{b}{\overline{C}_L/\sigma}$$
 = 1 - $\frac{0.00179}{0.0608}$ = 0.971 (q = 2.94%)
r = 0.952 (q = 4.8%)

Power:

a = 0.884 (q = 11.6%)
b' = 1 -
$$\frac{b}{\overline{C_P}/\sigma}$$
 = 1 - $\frac{0.000229}{.0026}$ = 0.912 (q = 8.81%)
r = 0.992 (q = 0.8%)

Applying the standards presented in Table 9, the lift correlation is graded as good, excellent, and excellent for its slope, intercept, and correlation coefficient. Similarly, power correlation is graded as fair, good, and excellent on its slope, intercept, and correlation coefficient.

The modified airfoil was used because it allowed the calculation of reasonable performance parameters. A general technique for adjusting two-dimensional model airfoil data to represent actual operating airfoil characteristics has yet to be developed.

POSTTEST ROTOR BENDING MOMENT CORRELATION

Load comparisons were made by computing blade response at certain specified conditions for all four blade sets. The conditions were selected to present a range of lift and μ , $M_{1,90}$ combinations. The cases examined were designated in the Sikorsky wind-tunnel test as Conditions 25, 44, and 68. Because each condition number represents slightly different operating conditions for each blade, the values of lift and power coefficients corresponding to each blade set are listed in Table 11. This table also shows the computed lift and power for each condition and blade.

Load computations were made using the modified airfoil table discussed in the Model Rotor Aerodynamic Investigation section of this report. For each blade set and condition, the computed lift and first harmonic flapping components were brought as close as practicable to the measured lift and flapping. A collective sweep using a quasi-static analysis (steady and first harmonic blade response only) was made to obtain the value of lift required by the target condition. The Program C81 quasistatic procedure will automatically iterate to zero first harmonic flapping component values. However, when a fully elastic computation is made, the values of lift and flapping angles computed in the quasi-static analysis are changed slightly due to aeroelastic effects (principally changes in blade angle of attack due to local blade velocity). These changes required a succession of simulations to obtain the desired lift and flapping angles. Consequently, the computed values do not exactly match the measured. Also, because the modified airfoil characteristics do not represent the model behavior adequately in all regimes, there is frequently a mismatch between computed and measured power.

A choice of rotor blade elastic modes was necessitated by a Program C81 input limit of six modes. Properties of the modes used are shown in Table 8. Computations for the fiberglass blades were made using one rigid-body beamwise mode, one rigidbody chordwise mode, two elastic beamwise modes, and two elastic chordwise modes. For these blades, the selection of the second elastic chordwise mode at approximately 7.5/rev precluded the use of an elastic beamwise mode existing at approximately 6.7/rev. This choice was made to provide a possibility of higher frequency chordwise response. Computations for the aluminum blades were made using the first existing six modes. Torsion modes were omitted for all calculations because the modified airfoil had no pitching moment table. Modes were calculated for a rotor speed of 730 rpm and a root collective pitch of 12°. The boundary conditions applied for mode shape calculations were those of a pinned out-of-plane hinge and a pinned in-plane hinge located at r = 3 inches. The effect of

the inplane lead-lag damper was represented in Program C81 by a damping force, proportional to implane velocity, applied at r/R = 0.10. Based on the damper rate of 17 in.-1b-sec/rad, the Program C81 damper input was 37.5 lb-sec/ft.

Measured and calculated beam and chord bending moments are compared by time histories and by harmonics at five radial stations (r/R = 0.20, r/R = 0.35, r/R = 0.45, r/R = 0.65, and r/R = 0.86). Figures 51 through 74 present the time histories for the twelve cases examined. These are followed by Figures 75 through 98 which present the harmonic analyses of the same The harmonics are given in magnitude and phase form as explained below. Tables 12 through 35 present the measured and calculated bending moments as sine and cosine harmonic components.

Measured and calculated load harmonics are presented in Figures 75 through 98 as magnitudes and phases plotted against radial station. A load, M, may be represented as Fourier series sine and cosine components in the form

$$M(n\Omega t,r) = \sum_{n=0}^{\infty} (A_n \sin n\Omega t + B_n \cos n\Omega t)$$
 (32)

where

M = load magnitude

n = harmonic number

 Ω = rotor speed

t = time

r = blade radial station

 $A_n = A_n(r)$, the sine component of the load at radial station r $B_n = B_n(r)$, the cosine component of the load at radial station r.

The above relation may also be written as a magnitude and phase in the form

$$M(n\Omega t,r) = \sum_{n=0}^{\infty} C_n \cos (n\Omega t - \phi_n)$$
where
$$C_n^2 = A_n^2 + B_n^2$$

$$\phi_n = \tan^{-1} (A_n/B_n)$$
(33)

Of the twelve cases examined, calculations using the -8° twist blade produced the best results. Examination of Figures 57 and 58 shows oscillatory magnitudes to be quite good for Condition 25. The beam traces for this condition show good magnitude and phase relationships for the entire span. Chorwise loads are good from r/R = 0.35 to r/R = 0.80. However, there is a decided difference in magnitude at the 20-percent This effect is very evident in the plots of the chord radius. load harmonics (Figure 82), where good correlation is seen for 1/rev loads from r/R = 0.35 to r/R = 0.80, and for the 2/revand 3/rev chord load components for the entire span. noticeable difference is seen in the 1/rev chord loads at r/R = 0.20, where the calculated load is approximately 50 percent of the measured. Calculated beam and chord load magnitudes for Condition 44 are low. Phase relationships are good for the l/rev beam bending moments over the entire span and improve for the 2/rev loads toward the tip. Once again, a large jump in chord 1/rev load is observed at the 20-percent radius. Condition 44 measured chordwise moments show a very high 4/rev harmonic content which is not calculated and also not seen in either Condition 25 or Condition 68 for this Oscillatory magnitudes for Condition 68 are low over the entire span for both beam and chord loads. Calculated beam harmonics are low at all frequencies. Calculated chord 1/rev magnitude again shows a very large discrepancy at the 20 percent radius but shows continuing improvement in magnitude and phase with blade radial station. Calculated chord 2/rev load is low at the 20% radius, but shows almost perfect magnitude correlation from r/R = 0.45 to the blade tip. Calculated chord 3/rev and 4/rev magnitudes are low over the entire span.

Calculated loads for the fiberglass blade with 0° twist are lower than measured for all three conditions. The measured loads also exhibit high harmonic content not seen in the calculated loads. The measured chordwise loads for Conditions 25 and 68 show large excursions in the fourth quadrant of the rotor azimuth which are indicative of stall. These are not accompanied by a calculated stall prediction.

Calculated loads for the remaining two-blade sets, the fiberglass blade with the trailing-edge flap and the untwisted aluminum blade, are considerably lower than the measured loads. Generally calculated loads do not show the higher harmonic content of the measured loads, and calculated stall indications are absent. Calculated loads are characterized by the absence of higher harmonic content and, excepting the fiberglass, -8° twist blade at Condition 25, generally low magnitudes. Measured 1/rev chordwise loads seem to be always increasing in the inboard direction, toward the hinge. This tendency would seem to indicate some moment carryover at the lead-lag hinge. The high harmonic content of the measured loads may indicate the presence of blade interaction effects which are not presently modeled in Program C81.

EFFECT OF CYCLIC RESOLUTION

Another factor which may influence the bending moment correlation is the effects of the cyclic pitch in the resolution angle between the shaft reference system and the blade reference system. Referring to the description of the mathematical model, it can be seen that the blade bending moments are formed by summing the bending moments produced by each mode. At the beginning of each computer run, the input mode shapes are used to calculate the in-plane and out-of-plane bending moment coefficients for each mode. During the time variant aeroelastic rotor analysis, the response of each mode or the participation factor is obtained from the numerical integration of the equations of motion.

These participation factors are multiplied by the previously mentioned in-plane and out-of-plane bending moments. The bending moments are then resolved through the steady geometric pitch angle (collective pitch plus structural twist) to obtain the beam and chord bending moments which have been presented in this report. Thus the cyclic pitch is not included in the resolution angle. Later versions of C81 have been modified to include the cyclic pitch angle in the resolution angle.

Figures 99 and 100 illustrate the effect of the cyclic resolution angle on loads. The calculations shown in these figures were made using a version of Program C81 which incorporates the cyclic pitch angle in the angle of resolution. The results shown are typical for beam and chord bending moments. The most noticeable effect is a general increase of beamwise moments in the midspan and outer regions of the blade.

EFFECT OF UNSTEADY AERODYNAMICS AND YAWED FLOW

The Program C81 unsteady aerodynamics were employed to compute the bending moments presented in Figures 101 and 102 for the fiberglass blade with 0° twist at Condition 25. These figures should be compared with Figures 51 and 52, which present computed results without the unsteady aerodynamics. Load magnitudes are not affected significantly in either the beam or

chord moments. The effect does produce a damping effect which is seen as a lagging phase shift (moving the calculated loads toward the measured).

Unsteady aerodynamics and the yawed flow simulation were used to produce the representative time history trace shown in Figure 103. The effects do not modify the load amplitudes appreciably. However, the introduction of the yawed flow representation does tend to shift the calculated phase in the leading direction, cancelling the phase shift of the unsteady aerodynamics effect.

EFFECT OF TORSIONAL MOMENT CALCULATIONS

The effect of incorporating a torsional mode shape and a pitching moment table is presented in Figure 104 for the fiberglass blade with -8° of twist at Condition 44. The inclusion of the 7.36/rev torsional mode required the removal of a chordwise mode at 7.56/rev due to the Program C81 input limit of six modes. The pitching moment table used was the model 0012 table. Figure 104 shows that this effect does not appreciably affect results. This figure is representative of the order-of-magnitude difference seen at all radial stations.

EFFECT OF IN-PLANE SPRING

Since the calculated 1/rev chordwise moments at r/R = 0.20 were consistently lower than the measured values, the possibility of excessive moment carryover at the lead-lag hinge was considered. The Sikorsky data package for this program states that possibly 15 percent of the in-plane lead-lag damper value could be considered as a spring component. Assuming 1/rev as the basis for calculating this spring component gives a value of approximately 0.3 ft-lb/deg. Modes and natural frequencies incorporating this in-plane spring value were used to compute the representative time history trace shown in Figure 105. The effect of the spring is to shift the mean value of the moments to a slightly higher level. The higher 1/rev chordwise moments may also be due to moment carryover by the lead-lag hinge bearings.

AERODYNAMIC REPRESENTATION

Correlation problems encountered are believed to be due mainly to an inadequate aerodynamic representation. The modified airfoil used for load predictions apparently did not represent the airfoil well in lift and drag and contained no pitching moment table since there was no method for determining moment coefficient values.

MEASURED DATA

Some problems were observed in the data used for comparison in this project. Figures 106 and 107 show representative time histories of measured model beamwise and chordwise moments. The chordwise moments contain strong noninteger per/rev components which may affect comparisons. The beamwise moment time history is more consistent but still contains components which may be significant at high frequencies. Though non-harmonic response may occur naturally due to various causes, this behavior is believed to be primarily related to inplane moments generated by the rotor drive system. Though the time histories presented herein are averages of measurements made for 40 revolutions, the illustrated behavior may still significantly affect results. The nature of the data indicates that measured results should be analyzed to detect and identify noninteger per/rev responses.

CONCLUSIONS

- 1. The Rotorcraft Flight Simulation Program (C81) can predict performance and bending moments for full-scale rotors.
- 2. Since the Rotorcraft Flight Simulation has been shown to correlate well for a similar, but full-scale, rotor system, the problems experienced are likely due to unsteady and/or Reynolds number and/or other scale effects which are not accounted for in the program.
- 3. The measured model rotor performance is not compatible with the model two-dimensional aerodynamic coefficients.
- 4. Mathematical modeling techniques, derived for full-scale rotor aerodynamics, may not be valid for model rotors.
- 5. The sensitivity analysis which was performed is not valid due to limitations in the input data and/or the computer program.
- 6. Simple harmonic analysis of measured data may lead to erroneous conclusions because of its inability to detect the noninteger, or transient, components.
- 7. The correlation criterion developed for rotor performance behavior is not applicable to model rotor bending moment correlation.
- 8. The difficulties associated with model rotors should not preclude the careful use and orderly development of the analysis.

RECOMMENDATIONS

- A similar program should be repeated using a full-scale rotor system.
- Measured and computed results should be analyzed using auto- and cross-correlation techniques.
- The wind-tunnel test conditions should be statistically designed to ensure the maximum usable data.
- 4. Further basic research should be conducted to understand the aerodynamics of model rotors.

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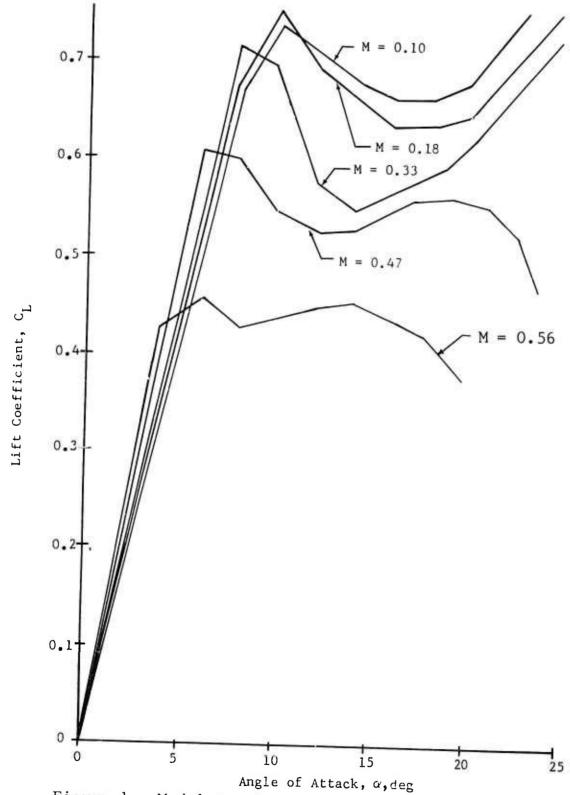


Figure 1. Model Aerodynamic Lift Coefficient vs. Angle of Attack.

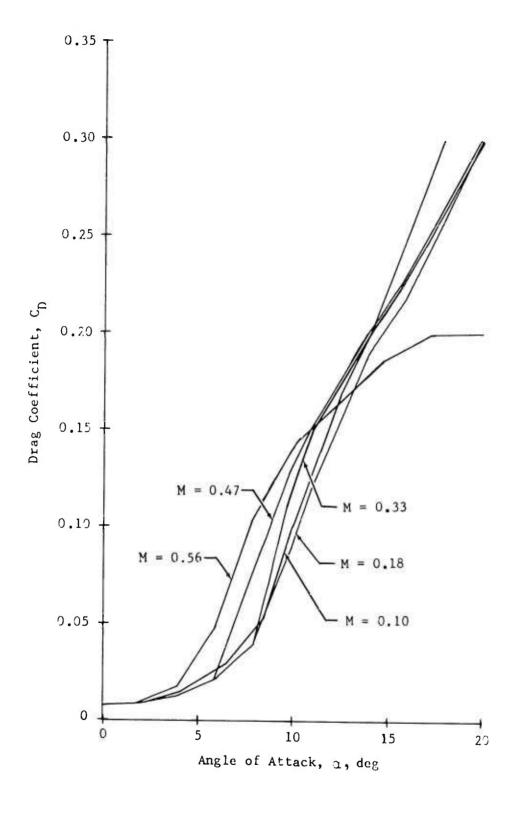


Figure 2. Model Airfoil Drag Coefficient vs. Angle of Attack.

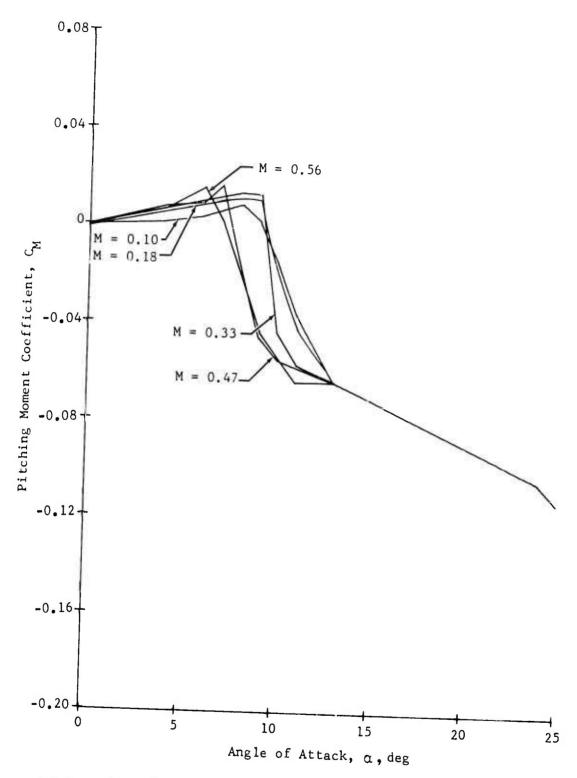


Figure 3. Model Airfoil Pitching Moment Coefficient vs. Angle of Attack.

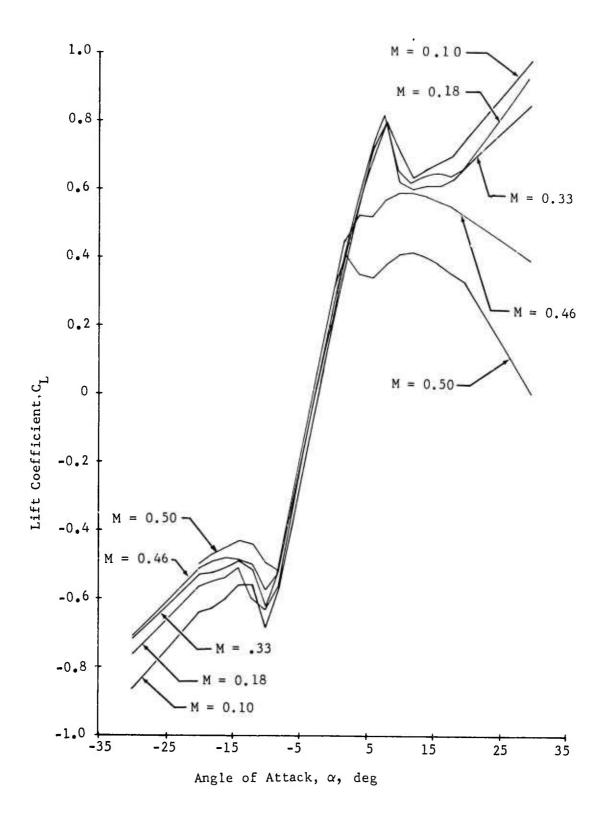


Figure 4. Model Aerodynamic Lift Coefficient vs. Angle of Attack for Flapped Airfoil.

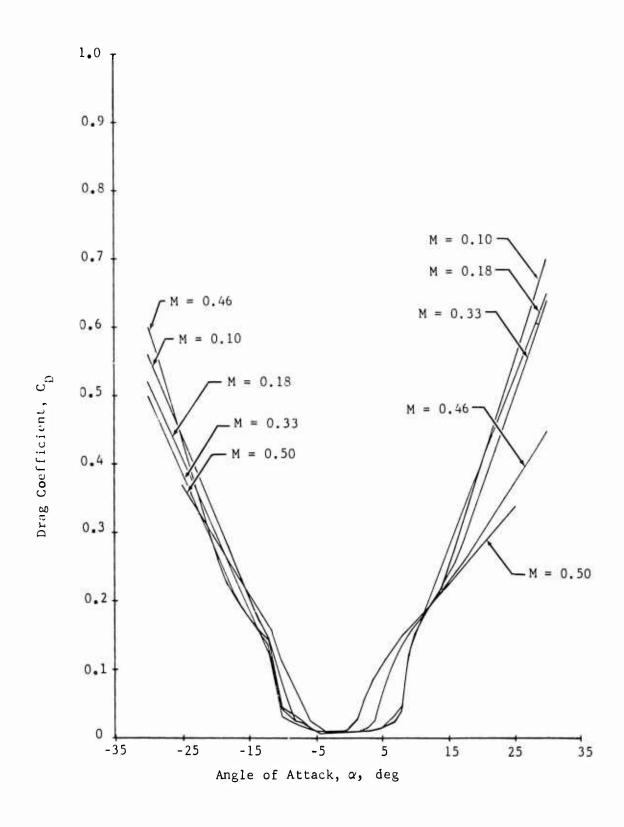


Figure 5. Model Aerodynamic Drag Coefficient vs. Angle of Attack for Flapped Airfoil.

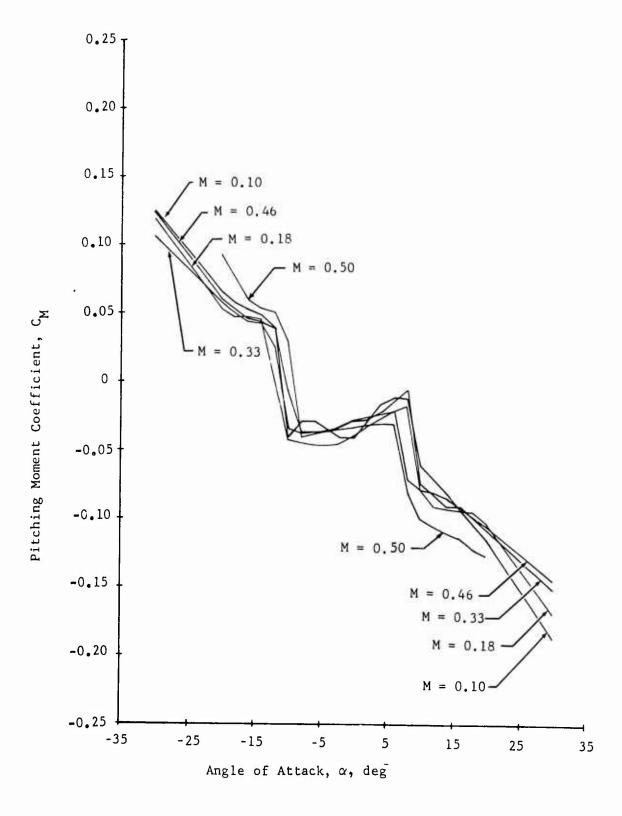


Figure 6. Model Aerodynamic Pitching Moment Coefficient vs. Angle of Attack for Flapped Airfoil.

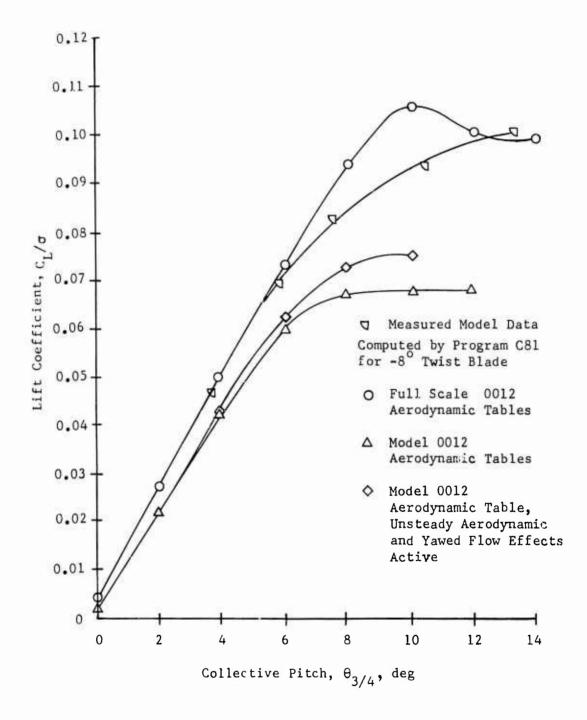


Figure 7. Lift vs. Collective Pitch for Full-Scale and Model Data Tables, $\mu=0.299$, $M_{1,90}=0.408$, $a_{\rm m}=0^{\circ}$.

RELL HELICOPIER COMPANY
ROTGRCRAFT FLIGHT SIMULATION PROGRAM ANAJ7213
COMPUTED 06/27/73

73062606 VARIATIONS STARTING FROM BASELINE CT/SIGMA=0.027 MODEL ROTOR SET 'A', FIBERGLASS WITH 8 DEG WASHOUT TWIST NU CYCLIC DETUNING, CT/SIGMA = 0.027 VARIATIONS

PROGRAM OPTIONS	DES 6	A ANG D.O DEG	•	2.0	AERO NEF		HANGE DFF				DIMENSTONAL		34.17 LAS	0.43 1.85	-0.39 LPS	-2.04 FT-LBS	0.41 FT-LAS	10.60 FT-LBS	1.48 HP		35 (IN-LAS)	DSC /MAX AZ/MIN AZ	170.	.011	-	.011	110.
PROCE	SECH TURNI ON	MAX YAW FLOW ANG	AERONYNAMICS	TORSION	NON STEANY AERO	FLAP ITFRATION	FP FOUFNCY CHANGE	FLASTIC PYLON		SHAFT AXIS SYSTEM	ONLESS	FIXED-WING	0.2913470	0.0076170	-0.3031253	-0.0018391	0.0003703	0.0095500	0.0479513		TORSION LUADS (IN-LAS)	MEAN DSC					
PARAMETERS	82.90 KTS	0.3983	0.440	000 :	2.50 DEG	-2.58 DFG	-6.01 DFG	351.3 FT/SEC	•	SHAFT A	DIMENSIONLESS	HFL ICCPTER	0.0284179	0.0007674	-0.0003157	-0.0003715	0.0000748	0.0019292	0.0019292			R/R	• 20	.35	• 45	•65	.80
TUNNEL PARAM		ADVANCE RATIO	ANV TIP MACH NO	SIGMA PRIME	MAST TILT ANGLE	TPP ANG OF ATTACK	CNT PL ANG OF ATTACK	ROTOR TIP SPEED	S AND MOMENTS + + +				THRUST	H FORCE	Y FONCE	RULL MOMENT	PITCH MOMENT	YAW MOMENT	POWER	ROTOR LOADS * * * * *	LOADS (IN-LBS)	OSC /MAX AZ/MIN AZ	70. /	2.53 / 70. / 350.	•	/ 60.	/ 60. /
ROTOR PARAMETERS	734.00 RPM	0.0625	JS 4.57 FT	2.69 IN	0.0 086			0.0 DEG	* * * * * FURCES		DIMENSIONAL		34.18 LAS	-0.57 LBS	-0.38 LBS	-2.50 FT-LBS	0.41 FT-LBS	10.50 FT-LBS		* * * *	CHORD	MEAN	1.93	1.96	1.82	1.15	0.48
ROTOR	ROTO	SULIDITY			PRECONE		THIST			WIND AXIS SYSTEM	INLESS	FIXED-WING	0.2814113	-0.0046625	-0.0031253	-0.0022540	0.0003703	0.0094607			N-L BS)	DSC /MAX AZ/MIN AZ	0. / 120.	0. / 120.	0, / 110.	250. / 100.	
VT ROL S	10.300	3.511	-0.657	3.572	0.0	-0.078 DEG	0.137 DEG			(A ONIN	OTHENSTONESSS	HEL ICUPTER	0.0234244	-0.0004709	-0.0003157	-0.0004553	0.0000749	0.0019112			BEAM LOADS (IN-LBS)	1/ OSC /1	2.42 /	2.04 /	2.28 /		2.37 /
ROTOR CONTROLS	COLLECTIVE PITCH	F/A CYCLIC PITCH	LAT CYCLIC PITCH	OT CYC FEATHER	DELIA 3	: / A FLAP ANGLE	LAT FLAP ANGLE	TOTAL FLAP ANGLE					IFT FORCE	DRAG FORCE	AT FORCE	ROLL NOMENT	PITCH MOMENT	YAW MOMENT				R/R MEAN	.20 0.57	.35 -0.04			

Figure 8. Baseline Case Fiberglass Blade with -8° Twist, μ = 0.398, $M_{1,90}$ = 0.440, C_{L}/σ = 0.027.

BELL HELICOPTER COMPANY
ROTORCRAFT FLIGHT SIMULATION PROGRAM ANAJ7213
COMPUTED 06/27/73

73062605 VARIATIONS STARTING FROM BASELINE CT/SIGHA=0.049 MODEL ROTOR SET 'A',FIBERGLASS WITH 8 DEG WASHOUT TWIST ND CYCLIC DETUNING

110NS 6	0.0 DEG	TABLE	NO	CFF	NO.	OFF	ŋFF			DIMENSIONAL		61.59 LBS	0.10 LBS	.84 LBS	-2.10 FT-LBS	.42 FT-LBS	12.38 FT-L8S	1.73 HP		N-LBS)	OSC /MAX AZ/MIN AZ	0. / 250.		`	170. / 250.	•
PROGRAM OPTIONS	MAX YAW FLOW ANG	AFRODYNAMICS	TORSION	NON STEADY AERO	FLAP ITERATION	FREQUENCY CHANGE	ELASTIC PYLON		F											TORSION LOADS (IN-LBS)	OSC /MAX	1.35 / 17	1.31 / 170.		\	
CN	MAX	AFR	TOR	NON	FLA	FRE	EL A		SHAFT AXIS SYSTEM	DIMENSIONLESS	FIXED-WING	6.9037533	0.0015230	-0.0123887	-0.0033772	0.0006705	0.0198744	0.1332148		TORS	MEAN	1.55	1.51	1.45	1.28	
ETERS 62.10 KTS	0.2984	0.408	1.000	0.0 DEG	-0.08 DFG		351.3 FT/SEC	*	SHAFT A	DIMENSI	HEL ICOPTER	0.0512240	0.0000863	-0.0007022	-0.0003828	0.0000760	0.0022529	0.0022529			R/R	.20	•35	•45	• 65	
FUNNEL PARAMETERS 62.	ADVANCE RATIO	ADV TIP MACH NO	SIGMA PRIME	MAST TILT ANGLE	TPP ANG OF ATTACK	CNT PL ANG OF ATTACK	ROTOR TIP SPEED	AND MOMENTS + + +				THRUST	H FORCE	Y FORCE	ROLL MOMENT	PITCH MOMENT	YAW MOMENT	POWER	ROTOR LOADS * * * * *	LOA05 (IN-LBS)	OSC /MAX AZ/MIN AZ		/ 10. /	/ 10. /	1 .01 /	
AMETERS 734.00 RPM	0.0625	4.57 FT	2.69 IN	0.0 DEG	4.885 DEG		0.0 DEG	* * * * * FORCES		DIMENSIONAL		51.59 LBS	0.10 LBS	-0.84 LBS	-2.10 FT-LBS	0.42 FT-LBS	12.38 FT-LBS		* * * * * RO	CHORD			1.96			
ROTOR PARAMETERS ROTOR SPEED 734.00	SOLIDITY	BLADE RADIUS	CHORD	PRECONE	CONING		TIP SWEEP	•	WIND AXIS SYSTEM	JNLESS	FIXED-WING	0.9037533	0.0015230	-0.0123887	-0.003:772	0.0006705	0.0198744			[N-LBS]	/MAX AZ/MIN AZ	210. / 110.	7 220. / 110.	250. / 100.	•	
TRULS 10.687 DEG	3.749	١	3.976	0.0	-0.081 DEG	0.108 DEG			WIND A	DIMENSIONLESS	HEL ICOPTER	0.0512240	0.0000863	-0.0037322	-0.0003828	0.00000.0	0.0022529			BEAM LOADS (IN-LBS)	050	2.11 /	1.78 /		2.72 /	
COLLECTIVE PITCH 10.	TYCLIC PITCH	LAT CYCLIC PITCH	TYC FEATHER	1 3	FIA FLAP ANGLE	LAT FLAP ANGLE	TOTAL FLAP ANGLE				_	LIFT FORCE	FORCE	FORCE	HOMENT	1 MOMENT	HOMENT			6	KEAN	1.62	0.52	-0.09	-1.23	
COLLE	F/A	LAT	TOT	DELTA 3	F/A F	LAT F	TOTAL					LIFT	DRAG	LAT	ROLL	PITCH	YAW				R/R	.20	.35	.45	.65	

Concluded: $\mu = 0.298$, $M_{1,90} = 0.408$, $C_{L}/\sigma = 0.049$. . Figure 8.

73062E04"

MUDEL ROTOR: FIBERGLASS WITH ZERG THIST

NU CYCLIC DETUNING, CT/SIGMA = .027 AND .049 LOADS

PROGRAM OPTIONS NO INPUT MODES 6 MAX YAW FLOW ANG 0.0 DEG AFRODYAMICS TABLE 11981UY NJN STEADY AERO OFF FLAP ITERATION ON RECUUENCY CHANGE OFF ELASTIC PYLGN OFF		LANCING TAIL		-0.15 0.20 12.30 1.72	05C /HA% AZ/MIN AZ 0.71 / 150. / 120. 0.67 / 150. / 120. 0.66 / 150. / 120. 0.58 / 130. / 120. 0.51 / 180. / 120.
		SHAFT AXIS SYSTEM CIMPYSIONLESS	F1xF9-W1vG 0.2704294 0.0025323	-0.0001200 6.0001796 0.0110837	TOPSION M-24 0.65 0.65 0.63 0.55 0.63 0.55 0.64 0.55
PARAMETERS 82.40 KTS 0.3943 0.440 1.003 2.50 PEG X -2.50 PFG FACK -6.24 PFG 351.3 FT/SEC	*	SHAFT	HFLICHPTER 0.0273152 0.0302558 -0.0093373	-0.0000273 0.0000363 0.0022391 0.0022391	6
TUNNEL PARAM FORWARD SPETD ADVANCE PATIO ADV TIP PACH NO SIGWA PRIME MAST TILT ANGLE TPP ANG OF ATTACK CNT PL ANG OF ATTACK RUIGR TIP SPEED	S AND MUMENTS + + + +		THRUST H FORCE Y FORCE	ROLL MOMENT PITCH MOMENT YAW MOMENT POWER	LCAUS (IN-LMS) CSG /MAX 42/4IN AZ CSG /MAX 42/4IN AZ CSG /MAX 42/4IN AZ CSG /MAX 60, / 10, 1.39 / 60, / 10, 1.39 / 60, / 10,
ROTOR PARAMETERS R SPEED 734-00 RPW BITY 0.6425 E RADIUS 4.57 FT 2.69 IN CNF 0.0 DFG HG 4.221 DFG SWEEP 0.0 DFG	* * * * * FURCES	PIMERSICHAL	32.83 LBS -1.13 LBS -0.41 LBS	-6.69 FT-L9S 6.20 FT-L9S 12.29 FT-LRS	* * * * * 50 CHORD L NEV! 1.55 1.11 0.43 0.31
RUTE SRL I PLAD CHIN PPFG CONT	MATAVA ATAA EMIM	IONLESS FIXED-HING	0.2707924 -0.0092(60 -0.0033390	-0.006c183 0.6001796 0.6110673	0.95 (19-185) 0.0
TVE PITCH 4.930 0EG LIC PITCH 3.733 neG LIC PITCH 3.733 neG LIC PITCH -1.214 0EG FEATHER 3.930 0EG 0.90 0EG P ANGLE -0.952 0FG/ P ANGLE 0.957 0EG	2 C X C X	DIMENSIONLESS HELICOPTER FIXED	0.0273003	-0.0001249 0.0003863 0.0002387	PEAN L
ROTOR CCNTO CCLLECTIVE PITCH F/A CYCLIC PITCH LAT CYCLIC PITCH TOT CYC FCATHER DELTA 3 F/A FLAP ANGLE LAT FLAP ANGLE TOTAL FLAP ANGLE			LIFT FORCE DRAG FORCE LAT FORCE	9 OLL MOMENT PITCH MOMENT YAW MOMENT	878 -20 -20 -35 -35 -45 -45 -65 -65 -65 -65 -65

Baseline Case Fiberglass Blade with 0° Twist, μ = 0.398, $\rm M_{1,90}$ = $\rm \tilde{0}.440,~C_{L}/\sigma$ = 0.027. Figure 9.

HELL HELLGGPTFP CEMPANY ROTORCPAFT FLIGHT SIMULATION PAGGRAM ANAJ7213 COMPUTED 06/79/73

10 73062804 MODEL PSTOR: FINERGLASS WITH ZERO TWIST NO CYCLIC DETUNING, CI/SIGNA = .027 AND .049 LOADS

71CNS 6 0.0 DEG 17ABLE DK OFF ON OFF	01MENSICNAL 60.12 LBS -0.31 LPS -1.07 LBS	-0.64 FT-LBS 0.33 FT-LBS 13.61 FT-LBS 1.90 HP	LOADS (IN-LBS) 0.5C /MAX AZ/MIN AZ 0.92 / 180. / 260. 0.77 / 180. / 260. 0.68 / 180. / 260. 0.59 / 180. / 260.
PROGRAM OPTIONS WAX YAW FLOW ANG 0. AEKONYAWICS TAB TORSINN OW NIN STEAD ARD OF FLAM ITERATION ON FREQUENCY CHANGE OFF	0 8 ~ 2		TORSION LOADS (IN-LBS) N 0.5C /MAX AZ/MI O.32 / 180. / 2 O.68 / 180. / 2 2 0.68 / 180. / 2 2 0.59 / 180. / 2
NO TOPUT MAX YAW AERODYJA TORSIUN NIN STEN FLAP ITE FREQUENC	SHAFT AXIS SYSTEM DIMENSIONLFS GPTER FIXFO-WING 69993 0.0321238 02542 -0.7044957 08913 -0.0157262	-0.0313216 0.0005325 0.0218566 0.1465010	TORSIG HFAN 1.00 0.17 0.93 0.82
67-10 KTS 0.2084 0.408 1.000 0.00 DEG -0.03 DEG -3.75 DEG 351.3 FT/SEC	* * SHAFT DIMENS HELLGGPTER 0.0449983 -0.0008913	-0.0001158 C.00005604 0.0024776 0.0024776	8
FORWARD SPEED ADVANCE RATIC BOY TIP MACH NO SIGMA PRIME HAST TILL ANGLE TPP ANG OF ATTACK CNT PL ANG OF ATTACK CNT PL ANG OF ATTACK -0.1	AND MOMENTS THRUST H FAPO Y FORC	POLL YOVENT PITCH MOVENT YAW WOMENT POWFR	ROTOR LOADS * * * * * * * * * * * * * * * * * * *
ROTOR PARAMETERS R SPEED 734.00 RPH OITY 0.0625 F RADIUS 4.57 FT 2.69 IN ONE 0.0 DG NG 5.717 DEG NG 0.0 DFG SWEEP 0.0 DEG	* * * * * FORCES DIMENSIGNAL 60.12 LNS -0.31 LNS -1.07 LNS	-0.64 FT-L4S 0.33 FT-L8S 13.61 FT-L8S	CHORD MFAN HFAN 1.69 1.11 0.79 C.23 0.01
SOLI SOLI CHOR PARC CONI	#INC AXIS SYSTEM IMPOSITESS PTER FIXED-WING 2943 -0.0044857 8913 -0.0157262	-0.0013216 0.0005325 0.0218566	0ACS (14-LHS) 0SC / MAX AZ/MIN AZ 1.39 0. / 70. 0.57 / 260. / 80. 1.29 / 270. / 180. 1.25 / 270. / 180.
5.044 056 3.747 055 -1.539 FEG 4.114 EEG 0.03 0EG 7 0.054 EEG 7	HELICOPTER FIXED 0.049993 C.98972542 -0.0003913 -0.01	-0.0001158 0.0000504 0.0024776	BEAM LOACS (14-LHS) 10.0 / Ax AZ/ 10.09 / 0.7 10.29 / 260: / 10.29 / 270: / 10.29 / 270: /
POTOP CONTROLS CGLLECTIVE PITCH 5. F/A CYCLIC PITCH 3. LAT CYCLIC PITCH -1. TOT CYC FEATHER 4. DELTA 3 F/A FLAP ANGLE -0. LAT FLAP ANGLE 0.	H DRAG F PCE LAT FURCE	HOMENT MOMENT MOMENT	BE MEAN 2.64 1.69 1.35 0.60
CGLLE F/A C LAT C TOT C DELTA F/A F LAT F	LIFT DRAG LAT	ROLL PITCH YAW	77. 20. 35. 45. 80.

Concluded: $\mu = 0.298$, $M_{1,90} = 0.408$, $C_{L}/\sigma = 0.049$. Figure 9.

FUTURCHAE' FLIGHT SIMILATION PROGRAM ANAJ7213
CCMPUTER 06/29/73

10 73062801 FIHERGLASS ELO,NO TWIST,TWAILING FORE FLAP FIGHRGLASS RLADE WITH NO TWIST NJ CYCLIC DETUNING

PROGRAM OPTIONS		LOW ANG 0.0 DEG	ICS TABLE	20	Y AFO OFF			YLON 17FF			TAMUNESTONAL		32.78 LAS	0.50 LRS	-0.33 185	-0.71 FT-LBS	-2.00 FT-LBS	10.47 FT-L8S	1.46 нр		TORSION LOADS (IN-LAS)	05C /*AX AZ/#IN AZ	4.39 / 283. / 100.	4.27 / 230. / 103.	/ 280. /	\	15 / 280. / 100.
PR()(SECUL AND IN ANDES	MAX YAM FLUW ANG	AFRODANAMICS	10851	USA STEADY AROU	FLAP ITERATION	FDF JUFNCY CHANGE	ELASTIC PYLON		SHAFT AXIS SYSTEM	DILISS	FIXCD-WING	0.2599128	9.3343359	-0.0026874	-0.116376	-0.00000129	0.3394299	0.0473479		TORSION L	200					-3.62 3.
	32.70 KTS	0.3043	0.440	1.030	2.50 DEG-	-2.62 DFG	- 3.12 DrG	351.3 FT/SEC	*	SHAFT A	\$ \$ 1701 \$ 5 3 A L J	HFL1COPIFA	0.1272:30	72140000	-0.0302714	-0.0001289	-0.0000000-	0.0017050	0.0019050			9/0	.20	• 3.5	54.	39.	08.
TUNNEL PARAMETERS	FORWARD SPLED	ANVANCE PATIO	ANV TIP MACH NO	Siday palac	MAST TILT ANGLE	TPP ANG OF ATTACK	CNT PL ANG OF ATTACK	RATOR TIP SPFED	AND PCPEUTS				THOUST	J3#0, H	Y FORCE	ROLL MOMENT	PITCH MAMENT	YAW MOMENT	POWER	ROTCH LCAGS nower	LPADS (IN-LHS)	OSC /MAX ALIMIN AZ	1.05 / 70. / 350.		_	/ 73. /	1.12 / 60. / 3.
OTOR PARAMFTERS	734.37 PPM	C. C62>	4.57 FT	2.69 14	C.O DEG	3.537 DEG	0.0	C.O DEG	* * * * * FURCES		TVND ISN 31.1 C		32.77 195	-0.93 LAS	-0.33 LHS	-1.16 FT-LBS	-0.00 FI-L+S	1C.43 FI-LAS		8 * * * * 8	CHORD L	Nuis	1.52	1.19	0.98		0.10
ROTOR PA	COTUR SPEED	SOL 1917Y	ALADE RADIUS	CHORD	PFECONE	CONTNE	12151	TIP SWEEP	•	AIND AXIS SYSTEM	, L . S . 3	DE IM-CBX I	C. 2044340	-0.0076914	-0.9020874	-0.010493	-0.0333029	0.0393931			4-LPS)	OSC /MAX AZ/MIN AZ		0. / 70.	0. / 40.	250. / 93.	250. / 130.
TROLS	3.270 MEG		-1.097	2.337	0.0	_				X UNIT	55 - TNL 15N_ 1.16	HELICOPTER 6			-0.0032714	-0.0002113					REAM LINASS (IN-LAS)	JAI JSU	1.96 /	1.59 /	1.58 /		1.18 /
401CO CONTROLS	COLLECTIVE PITCH	CYCLIC PITCH	LAT CYCLIC PITCH	TOT CYC FEATHER	14.3	F/A FLAP ANGLE	AT FLAP ANGLE	TOTAL FLAP ANGLE							LAT FURCE	MOMENT	404ENT	MOKENT			rac.	MEA'			0.71		-0.15
	COLL	FIA	LAT	TOT	DELTA 3	F/A	LAT	TOTA					LIFT	DRAC	LAT	ROLL	PI TCH	MYA				R/R	.20	.35	.45	.0.	.80

Baseline Gase Fiberglass Blade with 0° Twist and Trailing Edge Flap, μ = 0.398, $M_{1,90}$ = 0.440, C_{L}/σ = 0.027. Figure 10.

A CONTRACTOR OF THE PROPERTY OF THE PARTY OF

EQUARCEART FLIGHT STRUCTER COMPANY ROLLNESS STRUCTER PROGRAM ANAUTZI3 COMPUTED 06/20/73

73052801 FIRERGLASS BLD, NO THIST, TRAILING EDGE FLAP FIRERGLASS BLADE WITH NO THIST NO CYCLIC DETUNING

2

LS ROTOR PARAMETEUS TOUR FORMARD SPERO 3.2.33.0956 ROTOR SPERO 734.03.994 FORMARD SPERO	FIDA SPER	NFL PARAMETERS	TERS 62.10 KTS /	PROGRAM OPTIONS	PTIONS 6
SOL 101 TY 0.0625	ADVANCE E	ATIO	0.2584	MAX YAW FLOW ANG	4G 0.0 DEG
US 4.57 FT	APV TIP	MACH NO	0.408	AFPINYNAMICS	-
CHOFO 2.69 IN	SIGNA DO	1 ME	1.000	TORSION	NO O
PPFCUVE 0.0 DEG	MAST TIL	MAST TILT ANGLE	0.0 OFG /	NON STEADY AERO) OFF
CC41NG 4.502 DEG /	TPP ANG	TPP ANG UF ATTACK	-0.07 DFG	FLAP ITERATION	NO
/ TWIST 0.0 0EG	CNT PL	CNT PL ANG OF ATTACK	-2.83 DEG	FREQUENCY CHANSE	JE OFF
TIP SWEEP 0.0 NEG	ROTOR T	ROTOR TIP SPFED	351.3 FT/SEC	ELASTIC PYLON	05 F
MON GND AND MON		MOMFNIS * * * *			
			SHAFT AX	SHAFT AXIS SYSTEM	
18NUISNAMIO SSATISTISMANIO			SSAJUCISMINIO		DIMENSIGNAL
HELICOPTEM FIXED-WING			HEL ICOPTER	5×1×-	
0.265,0425		THRUST	0.0423310	0.4650625	58.95 LBS
0.0002116 0.0437693 0.26 L45		H FORCE	0.0002136	0.0037693	0.26 LBS
-0.0003298 -0.5146394 -1.50 LRS		Y FUNCE	-0.3338298	-0.0146394	-1.00 LBS
-0.0001933 -0.0017048 -1.06 FT-LMS		ROLL MOMENT	-0.0001933	-0.0017048	-1.06 FT-LBS
		PITCH MOMENT	0.0000530	0.0334678	0.29 FT-LBS
0.0144661		TNEWDR WAY	0.0016359	0.0144661	9.01 FT-LBS
		POWER	0.0016399	0.0969641	1.26 нр
TOVUL # # # # # BOLUK FOVU		* * * * * * SUVOT			
		(1N-LBS)		TORSION LOADS (IN-LAS)	IN-LAS)
OSC /HAX AZ/MIN AZ MEAN OSC /MA	SC /MA	ZW NIM/ZW XW/			OSC /MAX AZ/MIN AZ
0. 1.35 1.41 /		70. / 250.	- 20	3.13 /	100. / 90.
/ 0. / 90. 1.05	.30 /	70. / 250.		3.05 /	_
1.53 / 253. / 90. 0.36 2.61 /	1 19.	70. / 253.		`	300. / 90.
/ 260. /	.26 /	`	- 65	2.58 /	300. / 90.
/ 276. / 170.	101	70. / 250.	1 08.	7.25 /	,

 $\mu = 0.298$, $M_{1,90} = 0.408$, $C_{L}/\sigma = 0.049$. Figure 10. Concluded:

ACTURCRAFT FLIGHT STWOLATION PROGRAM ANAJ7213
COMPHIED 34.729773

73062803 ALUMINUM HLD , CHLECTIVE SWEEP: 327 1ST-FOLLOWED 3Y .049
NO CYCLIC DETUNING

PROSFAM OPTIONS NO INPUT MOTS MAX YEW FLEW ANS 0.0 DEG AFROJYNAMICS TORSIGN NON STEADY AFD OFF FLAP ITERATION FREQUENCY CHANGE OFF FLASTIC PYLON GFF	15 \$YSTEW NLFS FIXTO-WING 0.2665714 0.02662714 0.032480 -0.032480 -0.032480 -0.034 LBS -0.032480 -0.036480 -0.034 LBS -0.036480 -0.036480 1.69 HP	TORSION LDADS (IN-LBS) 0.5C / Max aZ/MIN AZ 0.44 0.72 / 180. / 250. 0.43 0.70 / 180. / 250. 0.42 0.67 / 180. / 250. 0.37 0.59 / 190. / 250. 0.32 0.51 / 180. / 250.
FTERS 82.90 ATS 82.90 ATS 0.44) 1.000 2.50 DEG -3.20 AFG -6.17 DEG 351.3 FT/SEC	## \$ \$414T AX15 \$YSTEM	4 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6
FOLKACKS SPECTS PARAMETERS ASSUMED SPECTS ASSUMED SPECTS OF 25 ASSUMED S	THRUST FOACE Y FOACE Y FOACE Y FOACE Y FOACE FOACE YAA YAA YAA YAA YAA YAA YAA	JTPR LOADS * * * * * * * * * * * * * * * * * * *
4010R PARAMETERS 4 SPEC) 774,00 APM 01TY 0.0525 5 SADIUS 4.57 FT 7 0.0 0.0 NO 0.0 0.0 NG 4.100 DEG 17 0.0 NG 7.100 DEG 18 0.0 NG 7.100 DEG 18 0.0 NG 7.100 DEG 18 0.0	01 VFNST CRAL 32.32 LHS -1.05 LHS -0.39 LNS -0.49 FT-LNS 9.31 TT-LNS 12.04 FT-LNS	# # # # ROTOR CHORD LDINS EFAN NG 7-11 1-31 1-22 2-34 0-39 1-90 0-06 0-95
2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	145NST 1415, SYSTEM 145NST 144, SYSTEM 175NST 144, SYSTEM 175NST 146, CONTRACTOR 175NST 146, CONTRACTOR 175NST 146, CONTRACTOR 175NST 166, CONTRACTOR 175NST 166	145.5 (IN-Lús) 2-10 / 2-10 / 2-10 2-20 / 0- / 70- 2-16 / 0- / 70- 2-16 / 0- / 70- 2-47 / 2-0- / 140- 1-92 / 260- / 190-
CH 4.03) 666 CH 3.803 076 CH 3.803 076 CH 3.973 076 0.0 DFG -0.735 076 0.0 076 0.0 076	#FLICOPTE FIXES OF STATES	HA MA L
ROTCR CONTROLS COLLECTIVE PITCA 4. F/A CYCLIC PITCA 3. LAT CYCLIC PITCA 3. TOT CYC FEATHER 3. DELTA 3 PANGLE -0. F/A FLAP ANGLE -0. LAT FLAP ANGLE 0.	LIFT FORCE DRAG FORCE LAT FORCE ROLL WON- IT PITCH MONENT YAW MOMENT	8/8 -20 -30 -4.76 -35 -45 -45 -45 -65 -865 -865 -865 -865 -865

Figure 11. Baseline Case Aluminum Blade with 0° Twist, $\mu = 0.398$, $M_{1,90} = 0.440$, $G_{\rm L}/\sigma = 0.027$.

NUTOACRAFT FLIGHT SIMULATION PROGRAM ANAJ7213 COMPUTED - 36729773

73062931 ALUMINUM BLD . COLLECTIVE SWEEP:.327 1ST-FOLLOWED dY .049 ALUMINUM HLADE MITH ZFRO FMIST NO CYCLIC DETUNING

SHOTTON CPTIONS	10ES 6	IN ANG 0.0 DEG	-	Z C	AERG OFF	TOW NOT	u:				DIMENSIONAL		£9.43 L6S	-7.16 LAS	-1.34 LAS	-0.69 FT-LAS	0.42 FT-LRS	12.74 FT-LES	1.91 HP		(Sa1-41) SCV61	DSC /MAX AZ/4IN AZ	/ 130. / 260.		/ 180. /	
ASUBG	NO INPUT MODES	MAX YAW FLUW ANG	AFRODYNAMICS	TORSION	VON STEADY AERG	FLAP ITFRATION	FREGUENCY CHANGE	FLASTIC PYLON		SHAFT AXIS SYSTEM	SYLESS	FIXED-WING	0.8632100	-0.0073949	-0.0152640	-0.0011144	0.0006682	0.0207716	0.1392282		TORSION LOA		0.87 0.93			
ETFRS	62.10 KTS	0.2934	0.408	1.000	0.0		-3.62 056			SHAFT A)	DIMENSIONLESS	HFL LCOPTER	0.3487241	-0.0001360	-0.0003652	-C.0001263	0.0000757	0.0023546	0.0923546			4/4	.23	35	.45	
TUNNEL PARAMETERS		ADVANCE HATIN	ADV TIP MACH NO	SIGAA PRIME	MAST TILT ANGLE	TPP AND UF ATTACK	CNI PL ANG 11F ATTACK	POTOR TIP SPRED	AND MOMENTS				THRUST	H FULCE	Y FORCE	ROIL MOMENT	PITCH MOMENT	INSTON MYA	POWER	ROTOR LOADS .* * * * *	LUANS (:N-LMS)	OSC /MAX AZ/MIN AZ		3.34 / 40. / 243.	3.31 / 40. / 240.	
OTUR PARAMETERS	734.00 RPM	0.0625		N1 69.2	0.0 066	5.452 DEG	0.0	0.0 DEG	* * * * * FORCES		DIMENSIONAL		58.83 LRS	-0.16 LAS	-1.04 LBS	-0.49 FT-LBS	7.42 FT-LAS	12.94 FT-' S		* * * * *	_		2.33	1.72	1.30	
9 OTUR PA	ROTOR SPEED	Si'L IOI TY	HLADE RADIUS	CHURD	PPECIVE	007170	TELSI	TIP SWEED	•	WIND AXIS, SYSTEM	MLFS\$	FIXED-WING	C.8622139	-0.6773539	-0.0152640	-2.0011144	J.00066R2	0.0207716			V-L PS)	OSC /MIX AZ/MIN AZ		`	260: / 90.	
21081	5.044 DFG	3.620	1	3.784	0.0 UEG	-1.35A DEG	0.0 OFG	~		KV GNIR	SS & Two I Stan I U	HEL ICOPTER			-0.3038692	-0.0001263	0.0000157	0.0023546			REAM LOADS (IN-LAS)		2.63 /	2.79 /	-	
ROTES CENTROLS	CCLLECTIVE PITCH	F/A CYCLIC PITCH	YCLIC PITCH	YC FEATHER	E .	FIA FLAP ANGLE	LAT FLAP ANGLE	TOTAL FLAP ANGLE				_		DRAG FURCE -		MOMENT	INDICE I	MOMENT			1	V-A B P.	5.19	3.87	3.25	
	COLLE	F/A (LAT	TOT (DELTA 3	FIA F	LAT F	TOTAL					LIFT	JRAG	LAT	ROLL	PITCH	YAW				R/R	.20	.35	645	

Concluded: $\mu = 0.298$, $M_{1,90} = 0.408$, $C_{L}/\sigma = 0.049$. Figure 11.

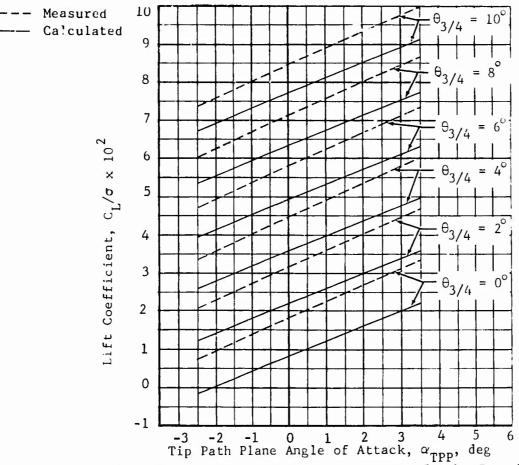


Figure 12. Comparison of Regression Analysis Results for Measured and Calculated Lift.

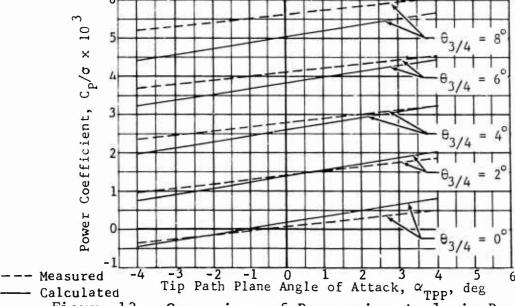
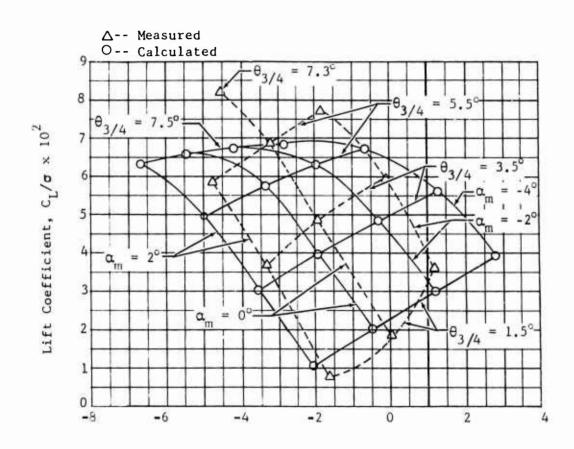


Figure 13. Comparison of Regression Analysis Results for Measured and Calculated Power.



Control Plane Angle of Attack, $\alpha_{\mathrm{CP}}^{}$, deg

Figure 14. Lift Coefficient vs. Control Plane Angle of Attack, Fiberglass Blade, -8° Twist, μ =0.299, M_{1,90}=0.408 Model Aerodynamic Data Without Unsteady Terms.

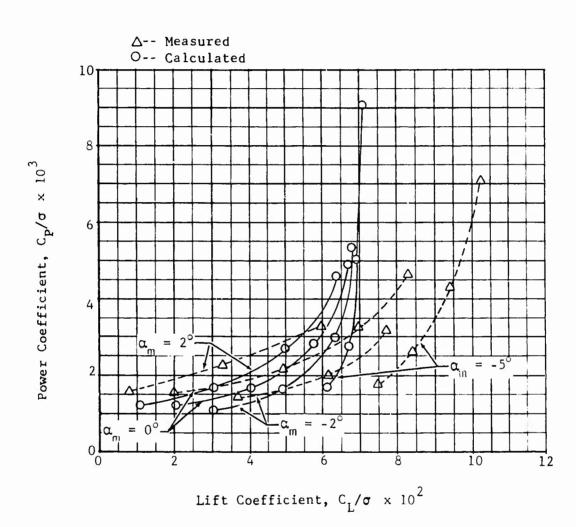


Figure 15. Power Coefficient vs. Lift Coefficient, Fiberglass Blade, -8° Twist, μ =0.299, M₁,90=0.408 Model Aerodynamic Data Without Unsteady Terms.

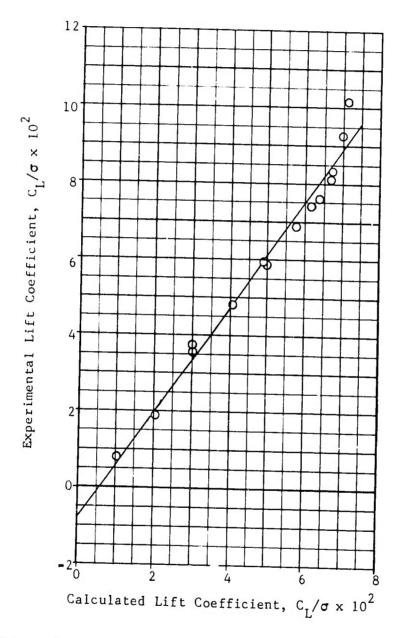


Figure 16. Experimental Lift Coefficient vs. Calculated Lift Coefficient, Fiberglass Blade, -8 Twist, μ =0.299, $M_{1,90}$ =0.408 Model Aerodynamic Data Without Unsteady Terms.

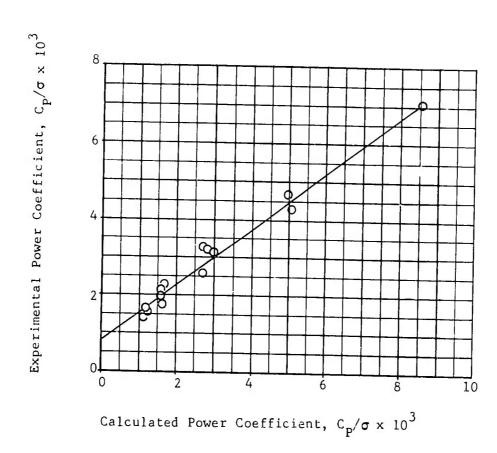


Figure 17. Experimental Power Coefficient vs. Calculated Power Coefficient, Fiberglass Blade, -8 Twist, μ =0.299, M1,90=0.408 Model Aerodynamic Data Without Unsteady Terms.

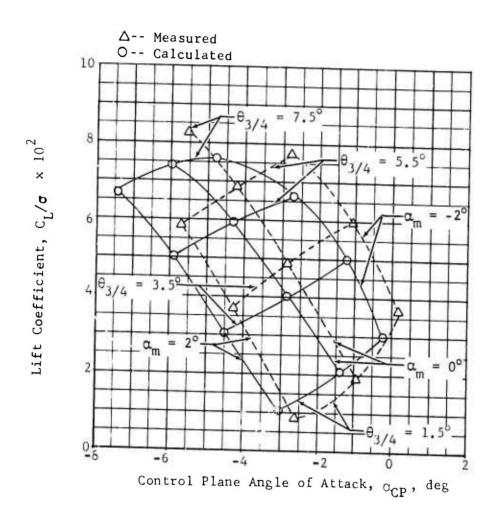


Figure 18. Lift Coefficient vs. Control Plane Angle of Attack, Fiberglass Blade, -8° Twist, μ =0.299, $M_{1,90}$ =0.408 Model Aerodynamic Data With Unsteady Terms.

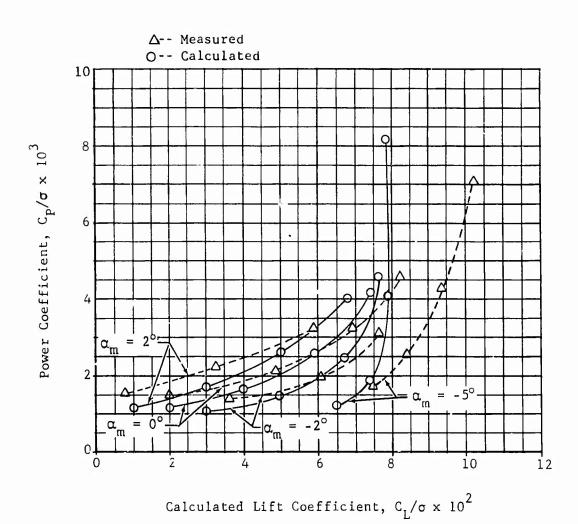
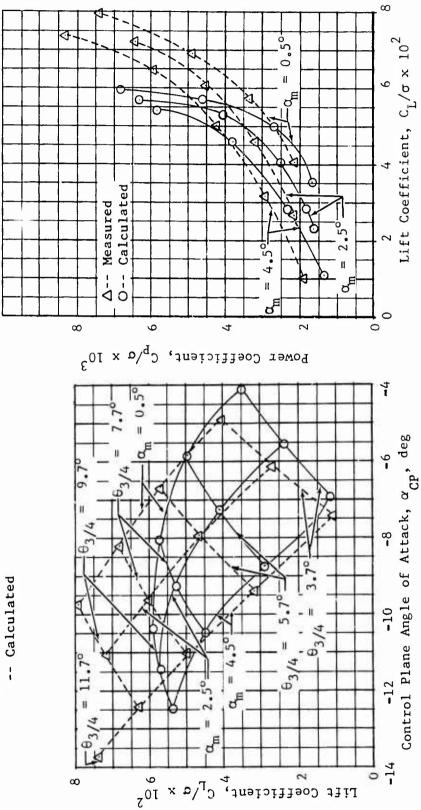


Figure 19. Power Coefficient vs. Lift Coefficient, Fiberglass Blade, $-8^{\rm O}$ Twist, μ =0.299, M₁,90=0.408 Model Aerodynamic Data With Unsteady Terms.

Δ-- Measured -- Calculated



Power Coefficient vs. Lift Coefficient, Fiberglass Blade, -8 Twist, μ = 0.400, M_{1,90} = 0.435 Figure 21. Lift Coefficient vs. Control Plane Angle-of-Attack, Fiberglass Blade, -8 Twist, $\mu = 0.400$, $M_{1,90} = 0.435$ Figure 20.

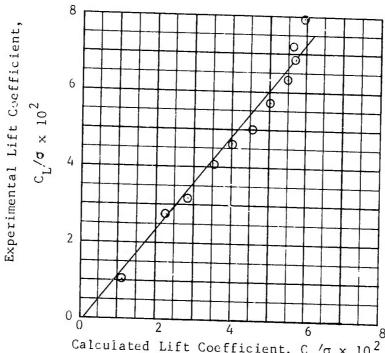


Figure 22. Experimental Lift Coefficient vs. Calculated Lift Coefficient vs. Calculated Lift Coefficient, Fiberglass Blade, -8 Twist, μ = 0.400, $M_{1,90} = 0.435$.

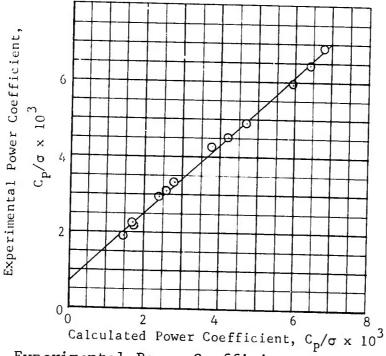


Figure 23. Experimental Power Coefficient vs. Calculated Power Coefficient, Fiberglass Blade, -8° Twist, μ = 0.400, $M_{1,90}$ = 0.435

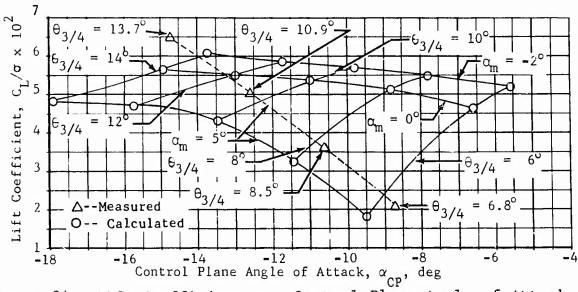


Figure 24. Lift Coefficient vs. Control Plane Angle of Attack, Fiberglass Blade, -8° Twist, $\mu = 0.502$, $M_{1,90} = 0.467$.

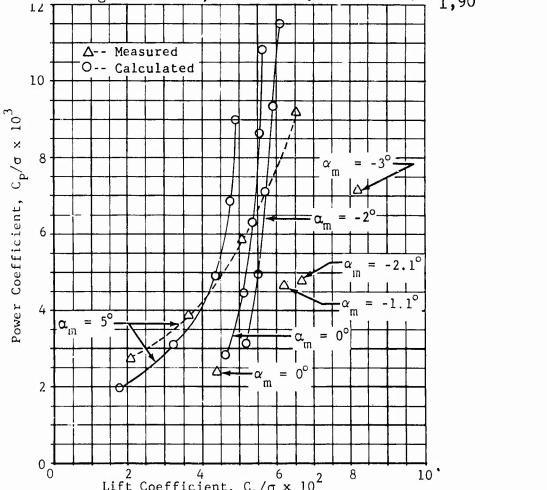


Figure 25. Power Coefficient vs. Lift Coefficient, Fiberglass Blade, -8° Twist, $\mu = 0.502$, $M_{1,90} = 0.467$.

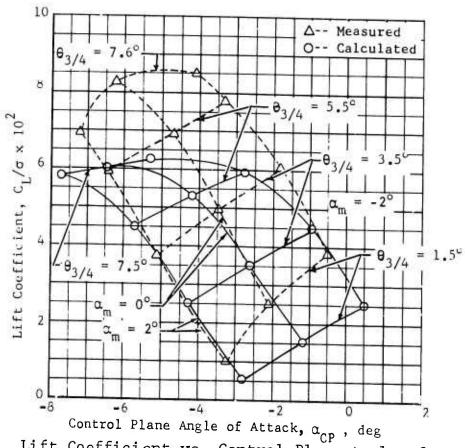


Figure 26. Lift Coefficient vs. Control Plane Angle of Attack, Fiberglass Blade, 0° Twist, μ = 0.299, M_{1,90} = 0.408.

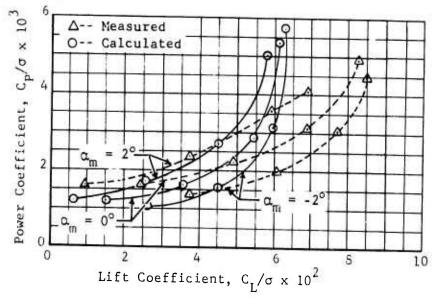


Figure 27. Power Coefficient vs. Lift Coefficient, Fiberglass Blade, 0° Twist, μ = 0.299, $M_{1,90}$ = 0.408.

Experimental Lift Coefficient, $c_{
m L}/\sigma imes 10^2$

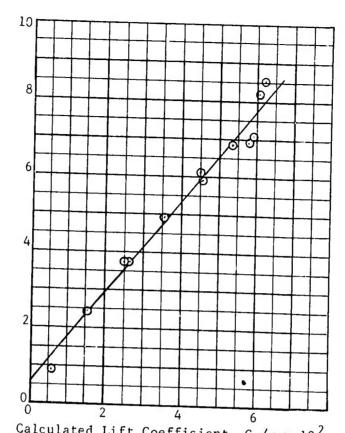


Figure 28. Experimental Lift Coefficient vs. Calculated Lift Coefficient vs. Calculated Lift Coefficient, Fiberglass Blade, 0° Twist, μ = 0.299, $M_{1,90} = 0.408$.

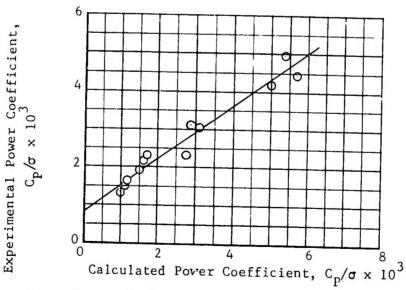


Figure 29. Experimental Power Coefficient vs. Calculated Power Coefficient, Fiberglass Blade, 0° Twist, μ = 0.299, $M_{1,90}$ = 0.408.

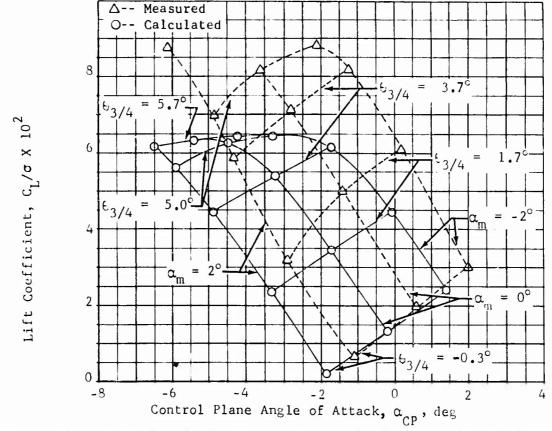


Figure 30. Lift Coefficient vs. Control Plane Angle of Attack, Fiberglass Blade, 0 Twist, $\delta_F = 5^{\circ}$, $\mu = 0.299$, $M_{1,90} = 0.408$.

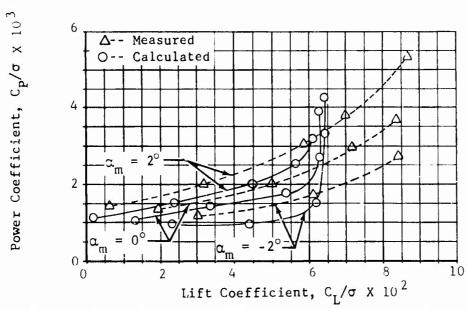


Figure 31. Power Coefficient vs. Lift Coefficient for Collective Pitch Sweep, Fiberglass Blade, 0° Twist, $\delta_F = 5^\circ$, $\mu = 0.299$, $M_{1,90} = 0.408$.

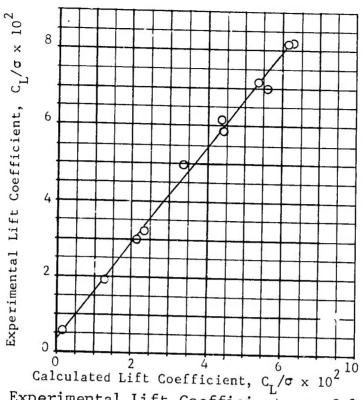
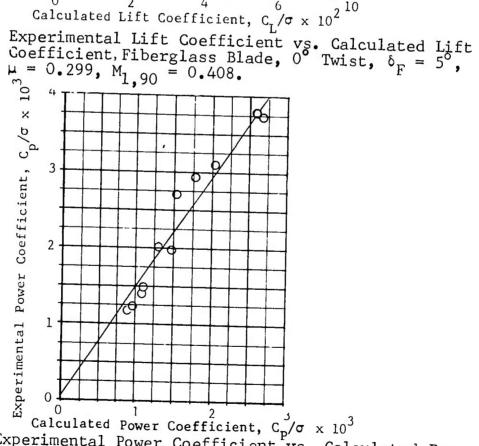
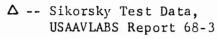


Figure 32.



Calculated Power Coefficient, $C_p/\sigma \times 10^3$ Experimental Power Coefficient vs. Calculated Power Coefficient, Fiberglass Blade, 0 Twist, $\delta_F = 5^\circ$ $\mu = 0.299$, $M_{1,90} = 0.408$. Figure 33.



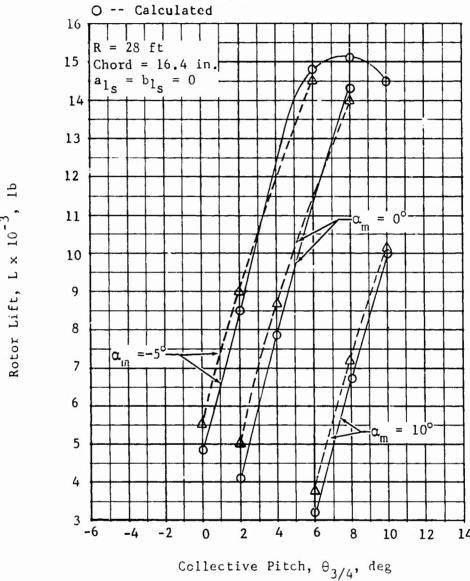


Figure 34. Rotor Lift vs. Collective Pitch for Full-Scale Rotor, -8° Twist, $\mu = 0.300$, $M_{1,90} = 0.740$.

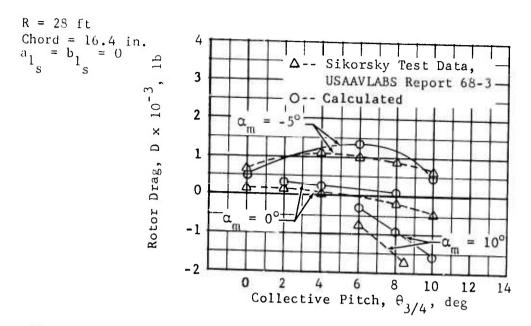


Figure 35. Rotor Drag vs. Collective Pitch for Full-Scale Rotor, -8° Twist, μ = 0.300, $M_{1,90}$ = 0.740.

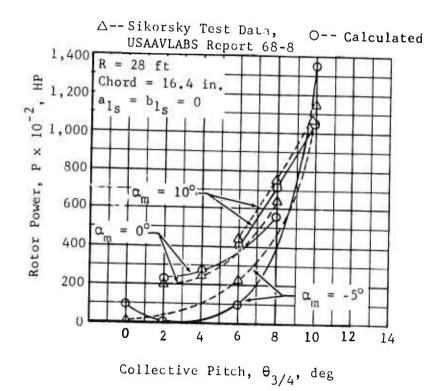


Figure 36. Rotor Power vs. Collective Pitch for Full-Scale Rotor, -8° Twist, μ = 0.300, $M_{1,90}$ = 0.740.

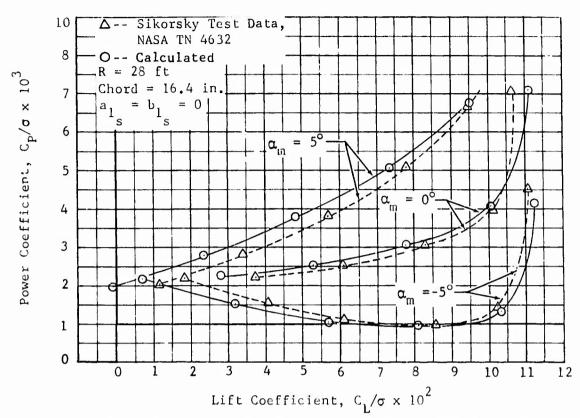


Figure 37. Power Coefficient vs. Lift Coefficient for Full-Scale Rotor, -8° Twist, μ = 0.300, $M_{1,90}$ = 0.740.

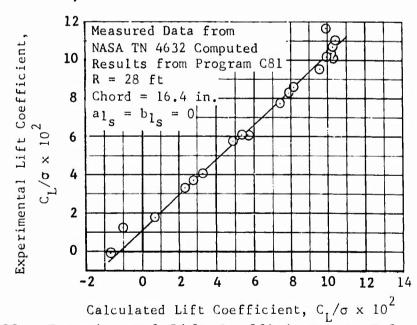


Figure 38. Experimental Lift Coefficient vs. Calculated Coefficient for Full-Scale Rotor, -8° Twist, μ = 0.300, $M_{1,90}$ = 0.740.

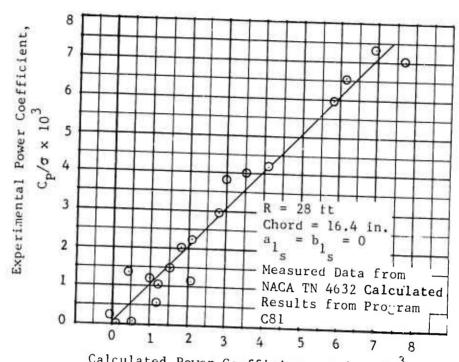
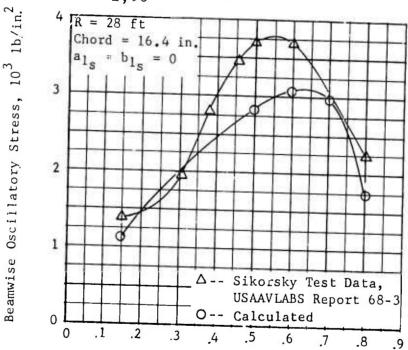


Figure 39. Experimental Power Coefficient, $C_p/\sigma \times 10^3$ Coefficient for Full-Scale Rotor, -8 Twist, $\mu = 0.300$, $M_{1,90} = 0.740$.



Radial Station, r/R

Figure 40. Flapwise Vibratory Stress for Full-Scale Rotor, -8° Twist, $\mu = 0.300$, $M_{1,90} = 0.740$.

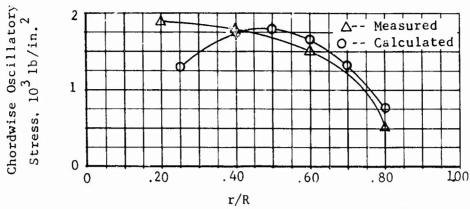


Figure 41. Chordwise Vibrator Stress for Full-Scale Rotor, -8° Twist, $\mu = 0.300$, $M_{1,90} = 0.740$.

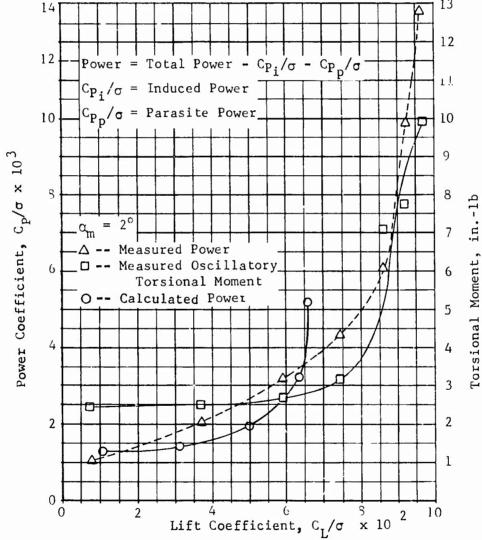


Figure 42. Stall Characteristics of Model Rotor, Fiberglass Blade, -8° Twist, μ = 0.299, $M_{1,90}$ = 0.408.

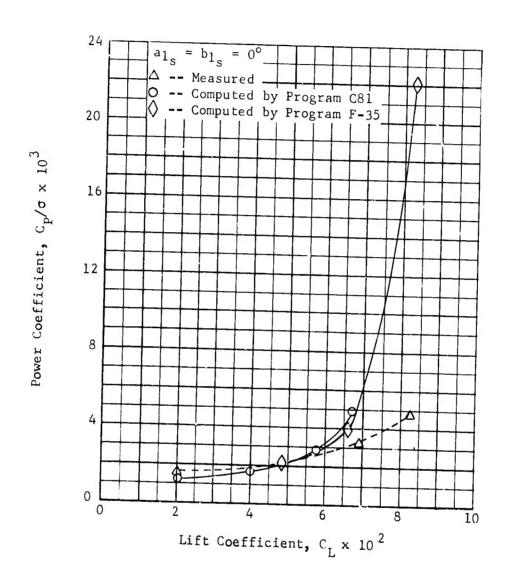


Figure 43. Rotor Power Coefficient vs. Rotor Lift Coefficient, Fiberglass Blade, -8° Twist, $\mu = 0.299$, $M_{1,90} = 0.408$.

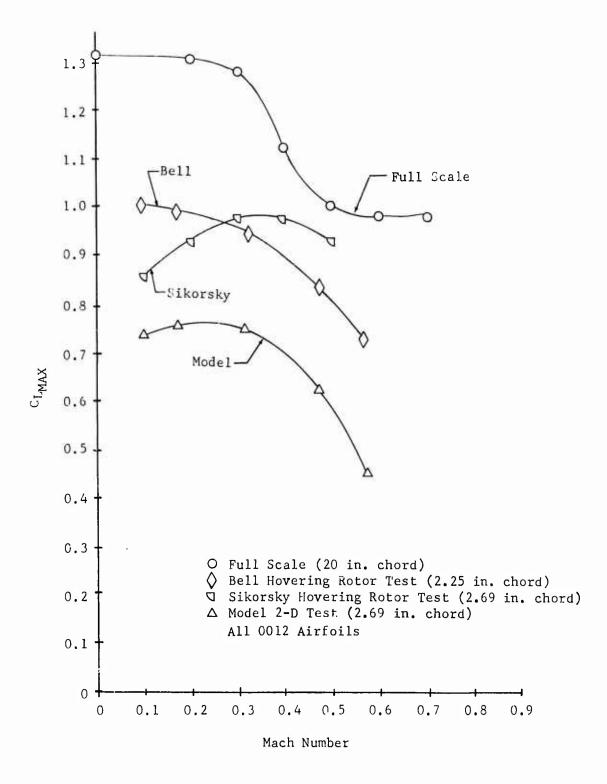


Figure 44. Effect of Mach Number on $\text{C}_{L_{\mbox{\scriptsize MAX}}}$ for a 0012 Airfoil.

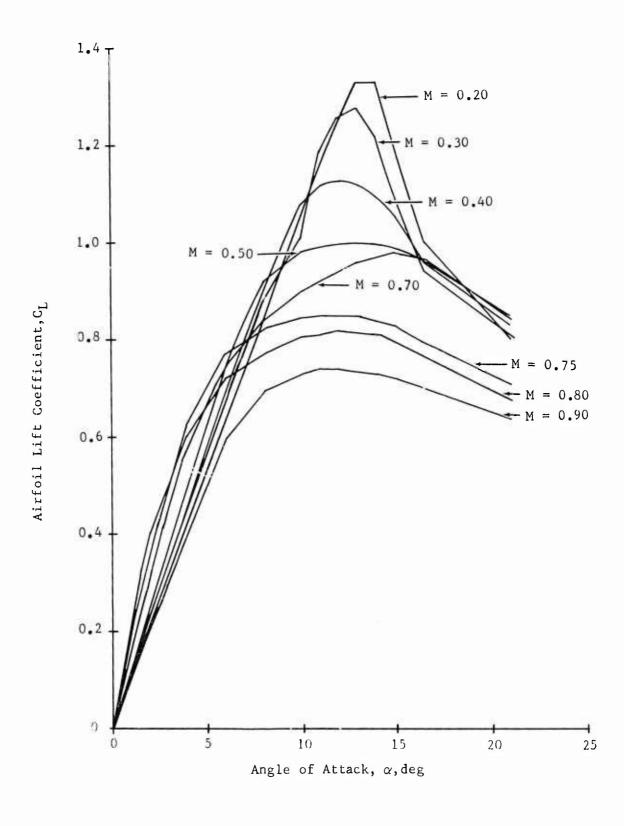


Figure 45. Full-Scale 0012 Airfoil Lift Coefficient vs. Angle of Attack.

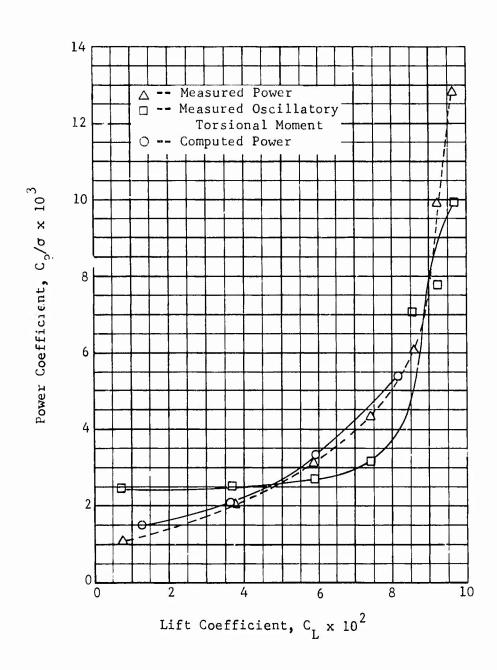


Figure 46. Stall Characteristics of Model Rotor Using Modified Airfoil Data Tables, -8 Twist, $\mu = 0.299$, $M_{1,90} = 0.408$.

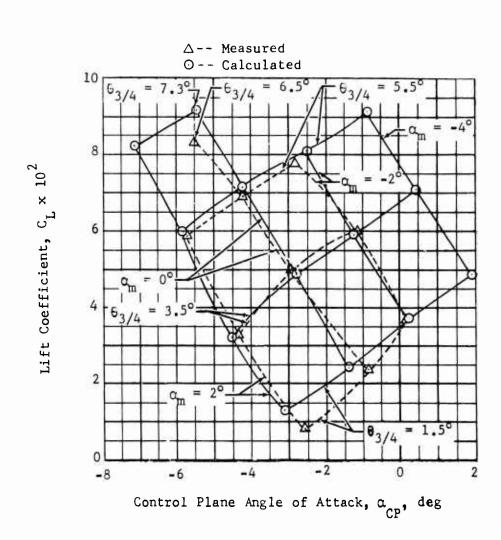


Figure 47. Rotor Lift Coefficient vs. Control Plane Angle of Attack Using Modified Airfoil Data Tables, -8° Twist, μ = 0.299, $M_{1.90}$ = 0.408.

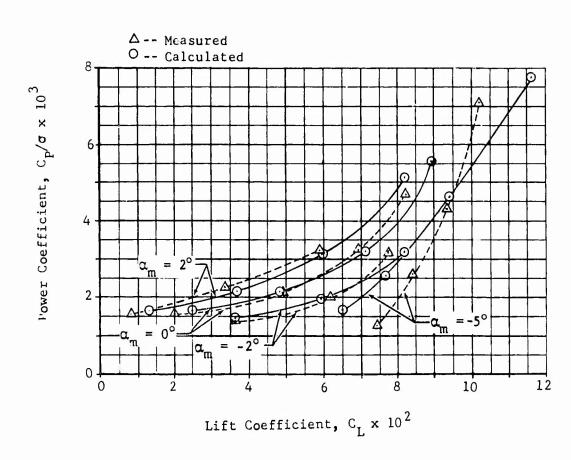


Figure 48. Rotor Power Coefficient vs. Rotor Lift Coefficient, Modified Airfoil Data Tables, Fiberglass Blade, -8 Twist, $\mu = 0.299$, $M_{1,90} = 0.408$.

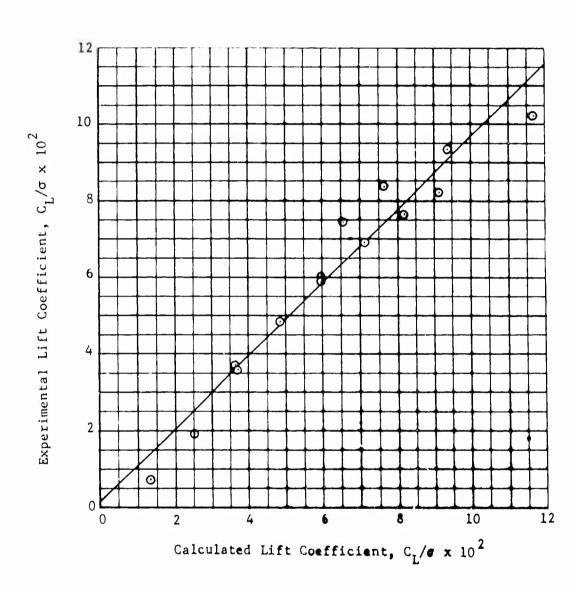


Figure 49. Experimental Lift Coefficient vs. Calculated . Lift Coefficient Using Modified Airfoil Data Tables, Fiberglass Blade, -8 Twist, μ = 0.299, $M_{1,90}$ = 0.408.

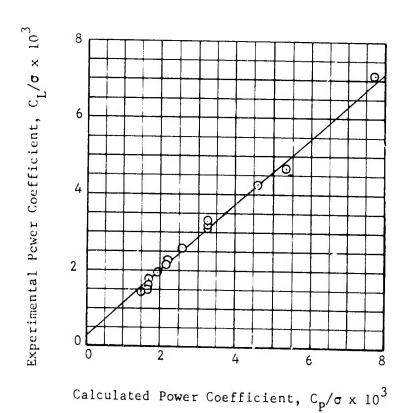
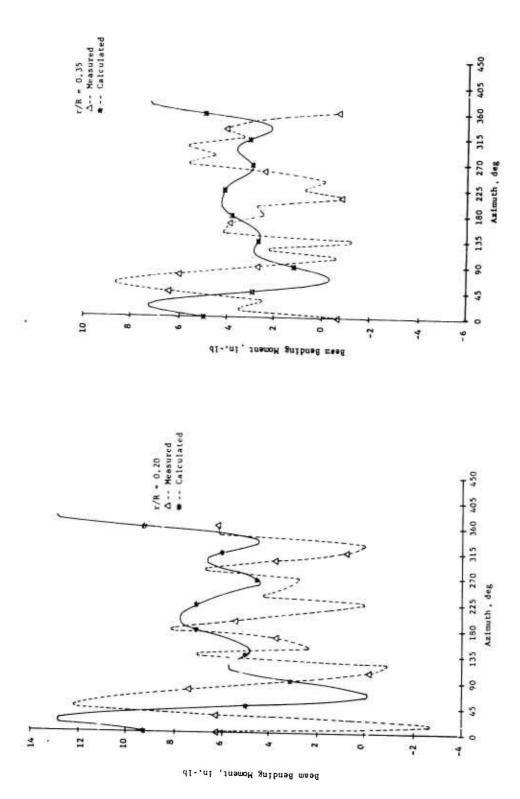
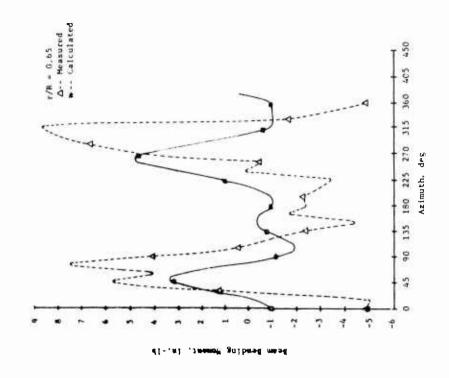


Figure 50. Experimental Power Coefficient vs. Calculated Power Coefficient Using Modified Airfoil Tables, Fiberglass Blade, -8° Twist, μ = 0.299, $M_{1,90}$ = 0.408.



Measured and Calculated Beam Bending Moment Time Histories, Fiberglass Blade, 0 Twist μ = 0.399, M_1 , 90 = 0.434, α_m = 0.5 (Cond. 25). Figure 51.



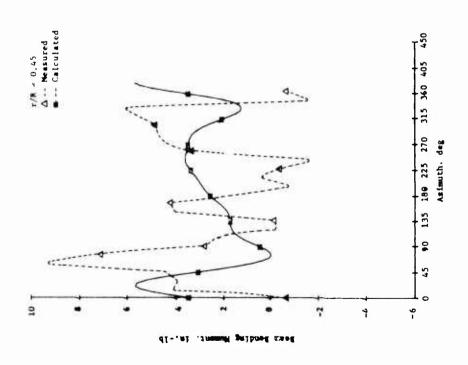


Figure 51. Continued.

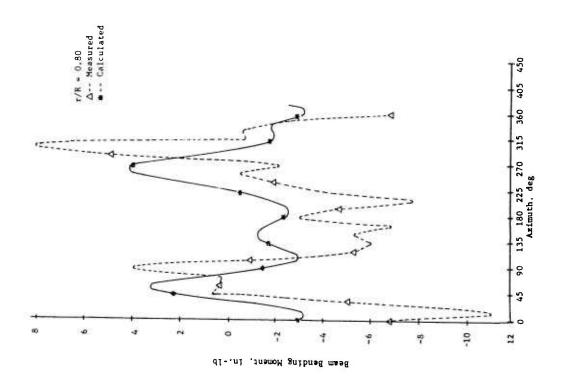
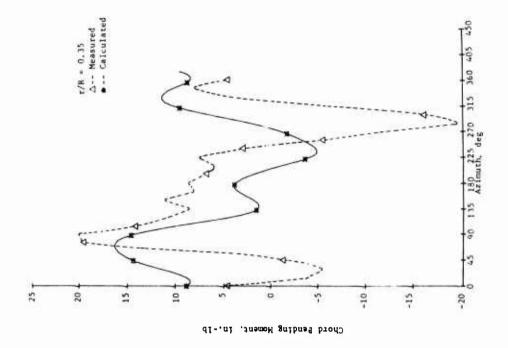
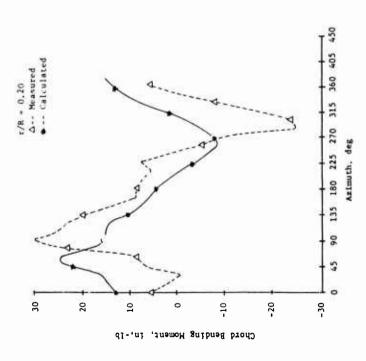
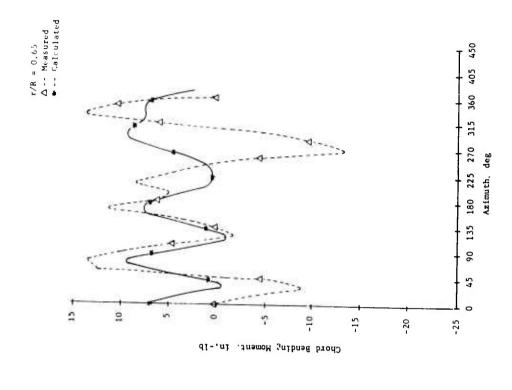


Figure 51. Concluded.





Measured and Calculated Chord Bending Moment Time Histories, Fiberglass Blade, 0 Twist $\mu=0.399,\ M_1,\ 90=0.434,\ \alpha_m=0.5$ (Cond. 25). Figure 52.



r/R = 0, 45 A-- Measured *-- Calculated

20

12

10

Figure 52. Continued.

0 45

-25

Chord Bending Moment, in.-lb

-10

-15

-20

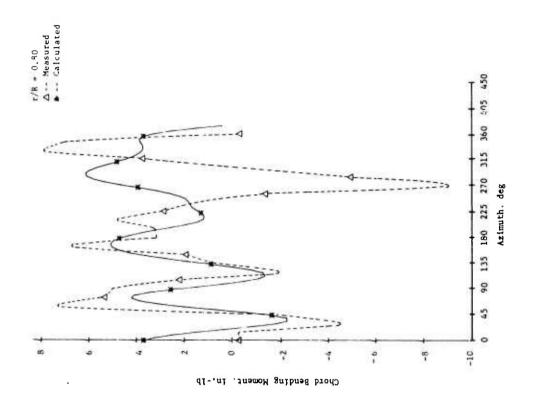


Figure 52. Concluded.

r/R = 0.35 .3-- Measured *-- Calculated 135 180 225 270 315 360 435 450 Azimuth. deg 06 5.4 Beam Bending Moment, r/R = 0.20 Δ-- Measured *-- Calculated 180 225 270 315 360 405 450 Azimuth, deg 135 6 57 9

Measured and Calculated Beam Bending Moment Time Histories, Fiberglass Blade, 0 Twist μ = 0.502, $M_{1,90}$ = 0.467, α_{m} = 5 (Cond. 44). Figure 53.

Beem Bending Moment, in. - 1b

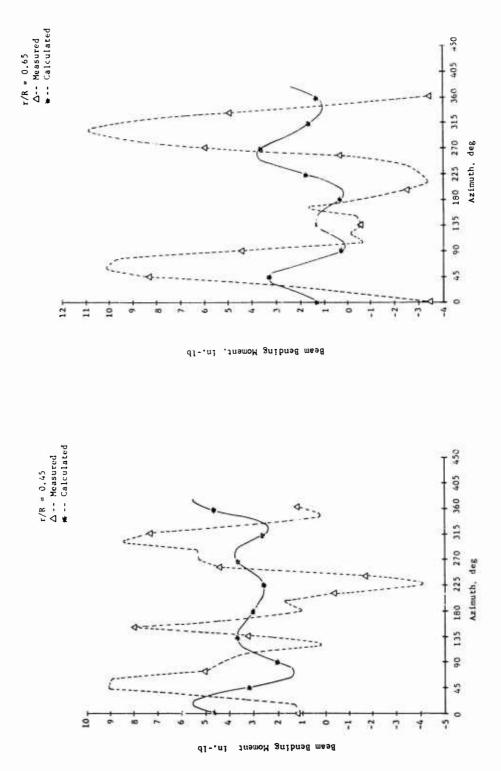


Figure 53. Continued.

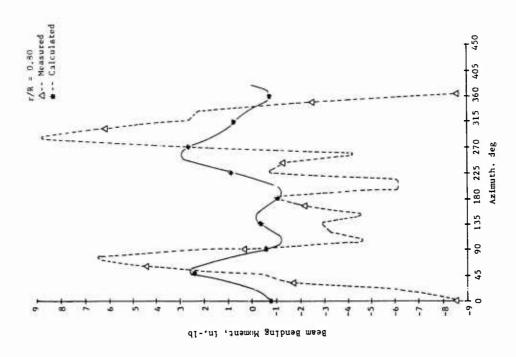
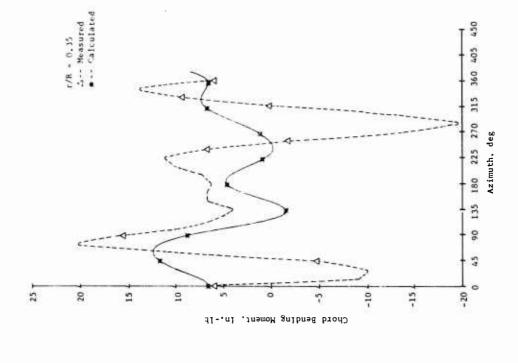
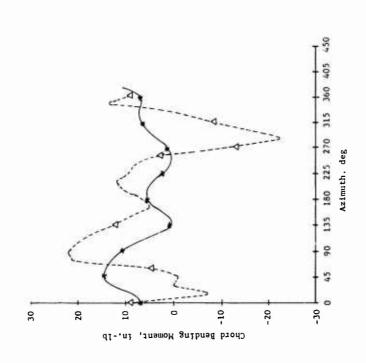


Figure 53. Concluded.



r/R = 0.20 Δ-- Measured *-- Calculated



Measured and Calculated Chord Bending Moment Time Histories, Fiberglass Blade, 0 Twist, $\mu=0.502,\ M_1,90=0.467,\ \alpha_m=5$ (Cond. 44). Figure 54.

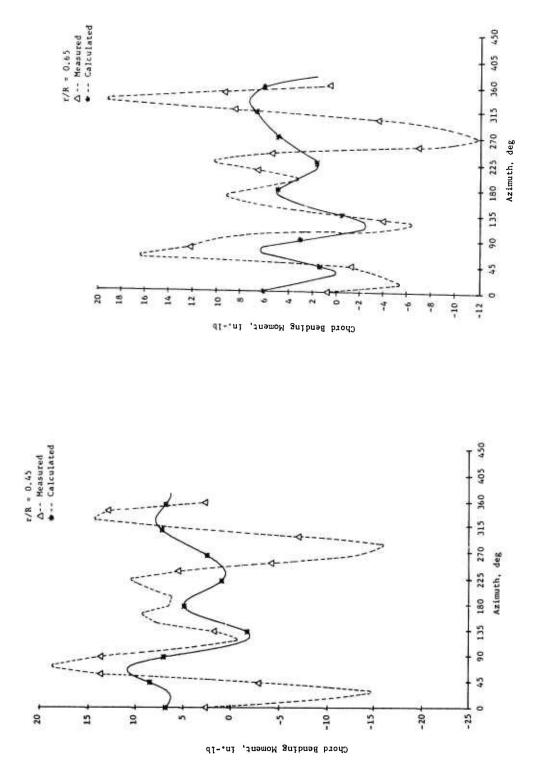


Figure 54. Continued.



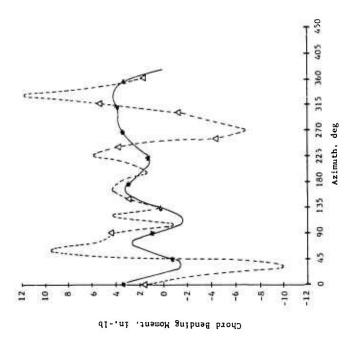
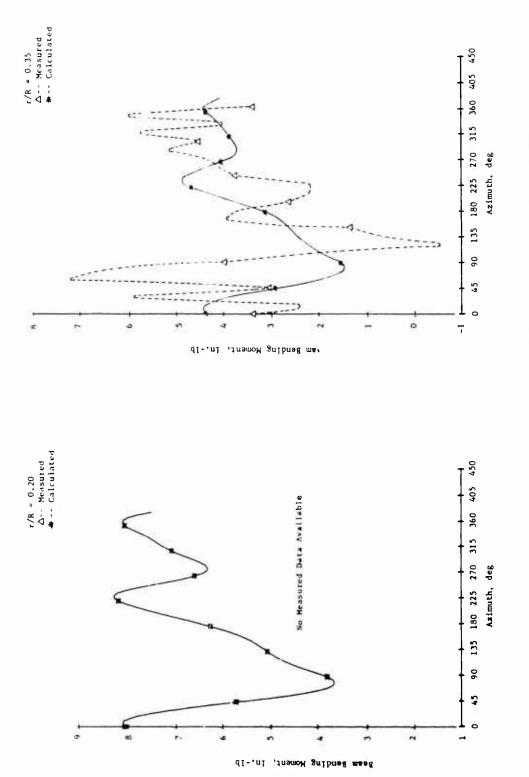


Figure 54. Concluded



Measured and Calculated Beam Bending Moment Time Histories, Fiberglass Blade, 0 Twist, μ = 0.299, $M_{1,90}$ = 0.408, α = 0 (Cond. 68). Figure 55.

r/R = 0.65 △-- Measured * -- Calculated 90 135 180 225 270 315 360 405 450 Azimuth. deg 45 4 Beam Bending Moment, In.-1b r/R = 0,45 Δ-- Measured *-- Calculated 135 180 225 270 315 360 405 450 Azimuth, deg 96 57 0 di-.ni..inemoM gaibned maed

Figure 55. Continued.

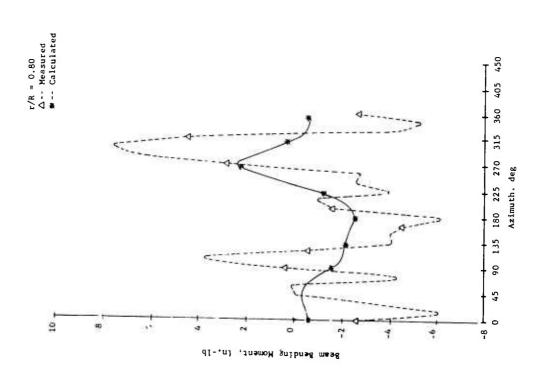
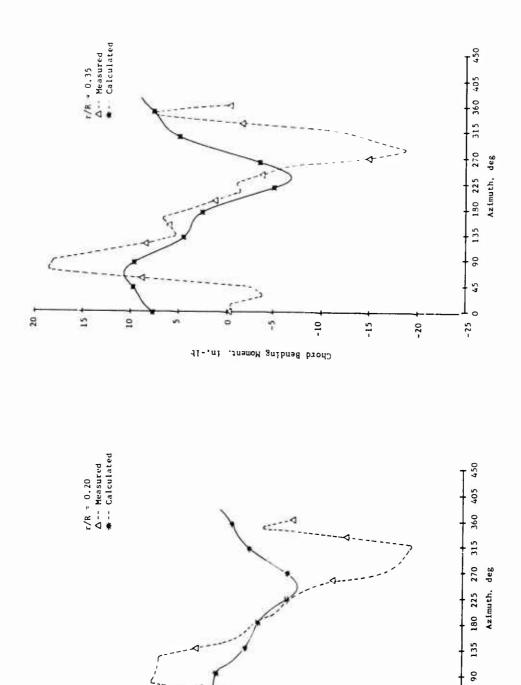


Figure 55. Concluded



Measured and Calculated Chord Bending Moment Time Histories, Fiberglass Blade, 0 Twist, μ = 0.299, $M_{1,90}$ = 0.408, $\alpha_{\rm m}$ = 0 (Cond. 68). Figure 56.

45

0

-40

-30

Chord Bending Moment, in.-lb

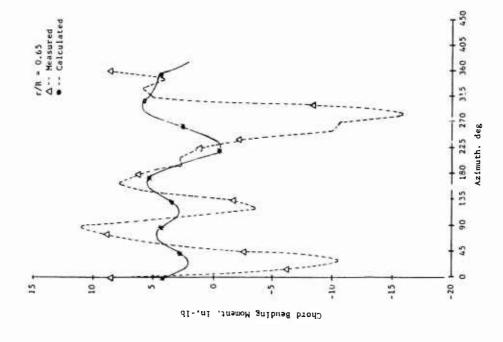
-10

-20

30 ⊤

20

2



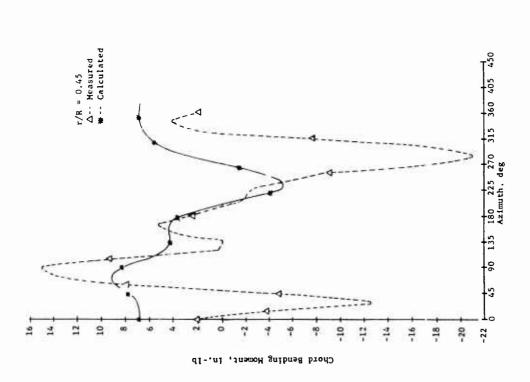


Figure 56. Continued.

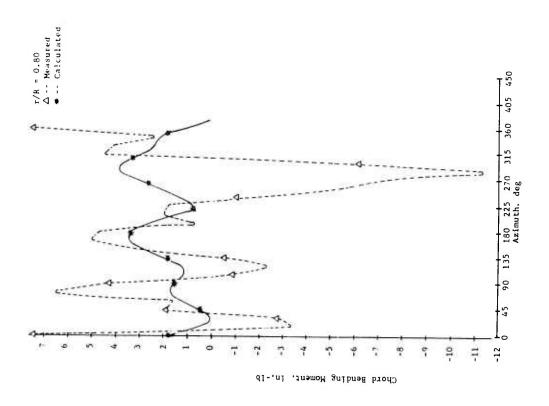
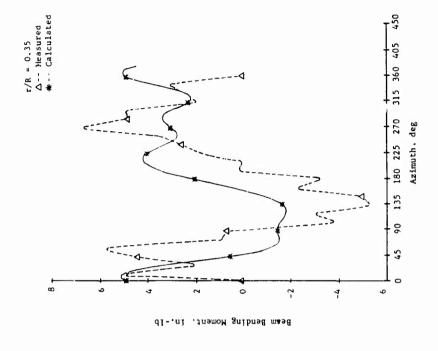
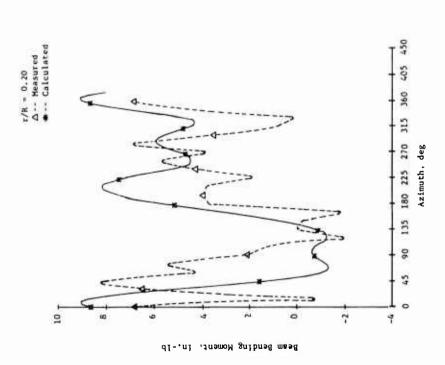
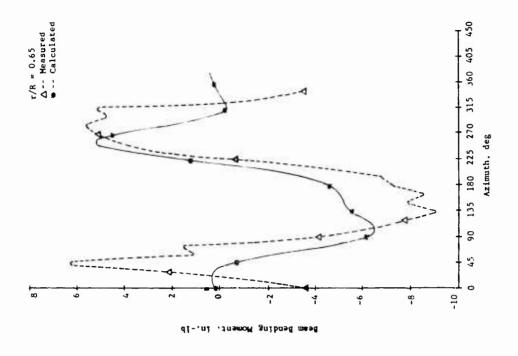


Figure 56. Concluded.





Measured and Calculated Beam Bending Moment Time Histories, Fiberglass Blade, -8 Twist, μ = 0.399, $M_{1,90}$ = 0.434, $\alpha_{\rm m}$ = 0.5 (Cond. 25). Figure 57.



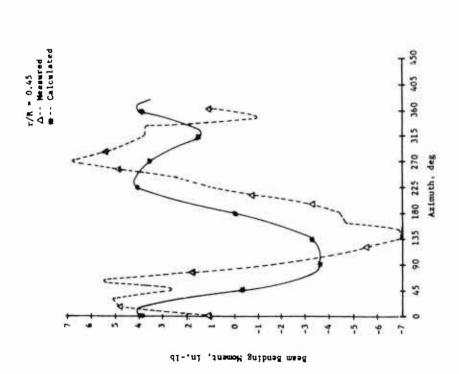


Figure 57. Continued.

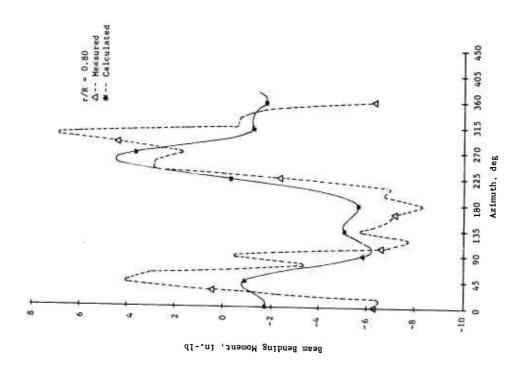
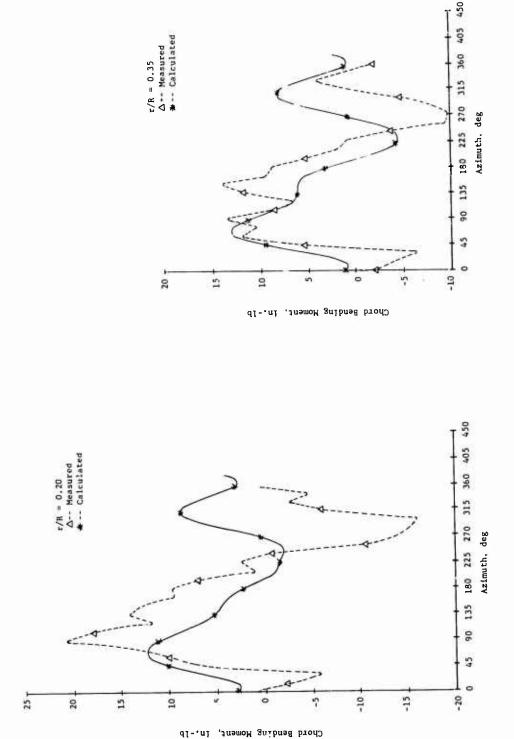
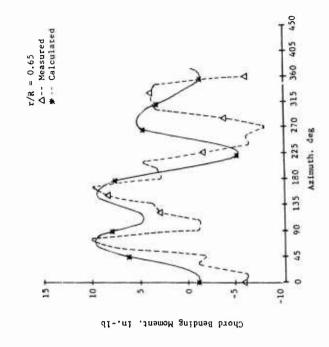


Figure 57. Concluded.



Measured and Calculated Chord Bending Moment Time Histories, Fiberglass Blade, $^{-8}$ Twist, μ = 0.399, $M_{1,90}$ = 0.434, $\alpha_{\rm m}$ = 0.5 (Cond. 25). Figure 58.



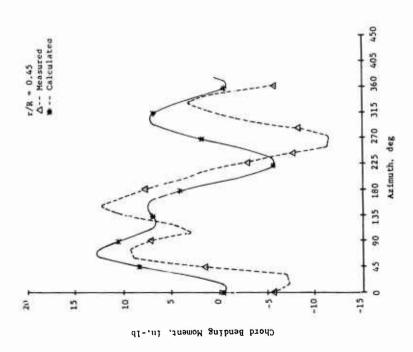


Figure 58. Continued.

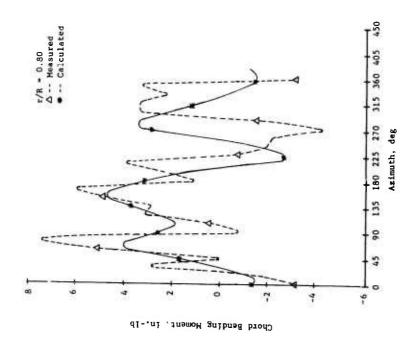
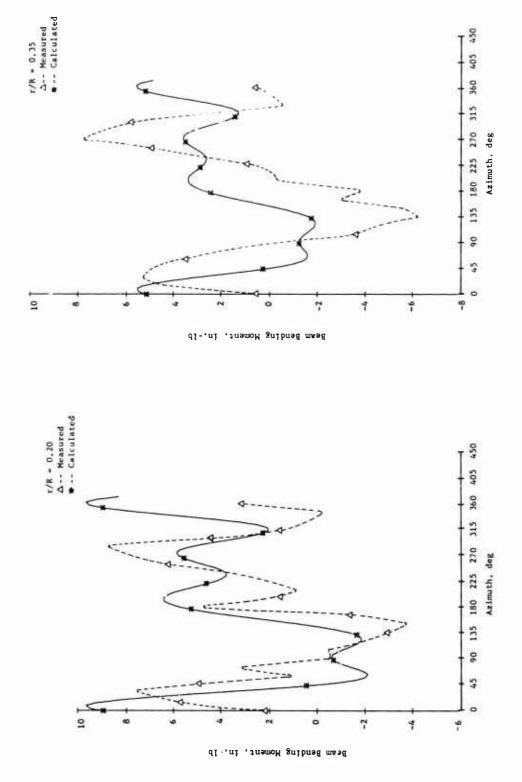
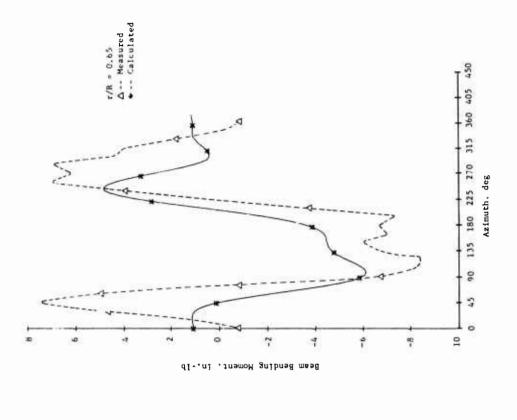


Figure 58. Concluded.



Measured and Calculated Beam Bending Moment Time Histories, Fiberglass Blade, -8° Twist, $\mu = 0.502$, $M_{1,90} = 0.467$, $\alpha_{\rm m} = 5^{\circ}$ (Cond. 44). Figure 59.



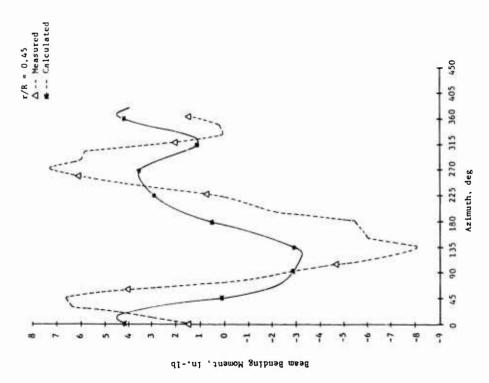


Figure 59. Continued.

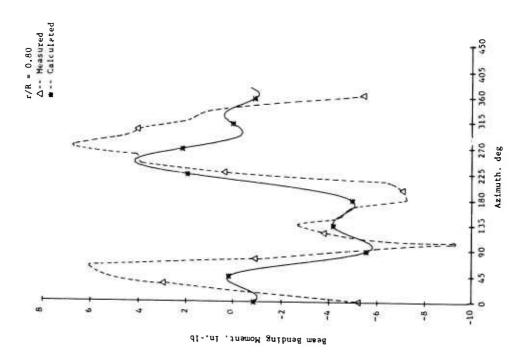
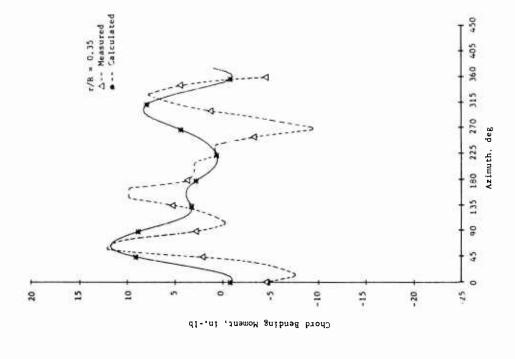
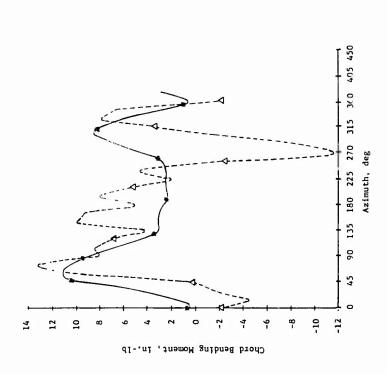


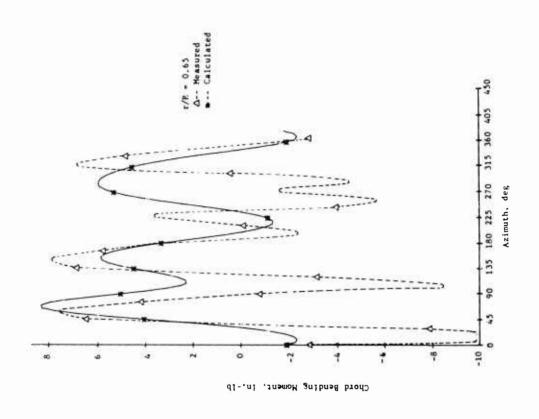
Figure 59. Concluded.



r/R = 0.20 Δ-- Measured * -- Calculated



Measured and Calculated Chord Bending Moment Time Histories, Fiberglass Blade, -8° Twist, μ = 0.502, $M_{1,90}$ = 0.467, $\alpha_{\rm m}$ = 5°(Cond. 14). Figure 60.



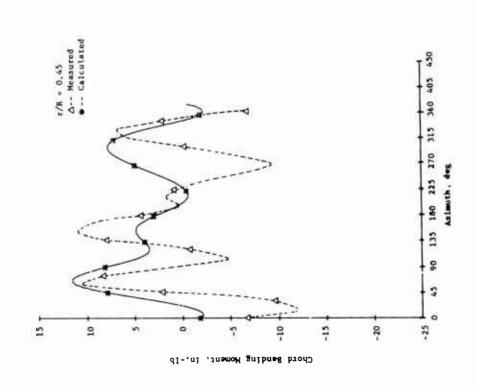


Figure 60. Continued.

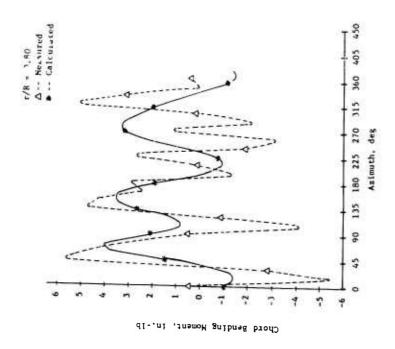
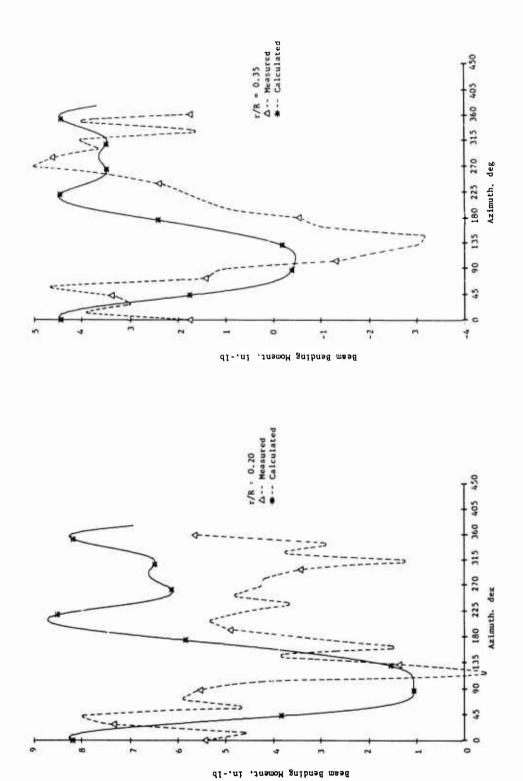
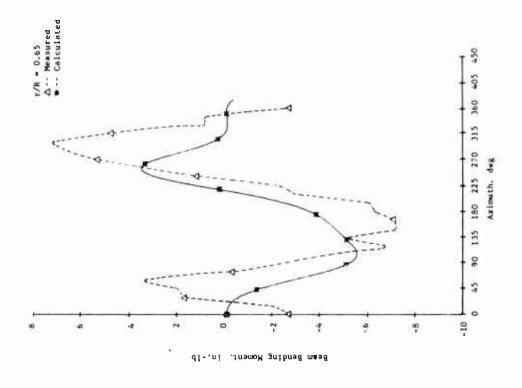


Figure 60. Concluded.



Measured and Calculated Beam Bending Moment Time Histories, Fiberglass Blade, -8° Twist, $\mu = 0.299$, $M_{1,90} = 0.408$, $\alpha_{\rm m} = 0$ (Cond. 68). Figure 61.



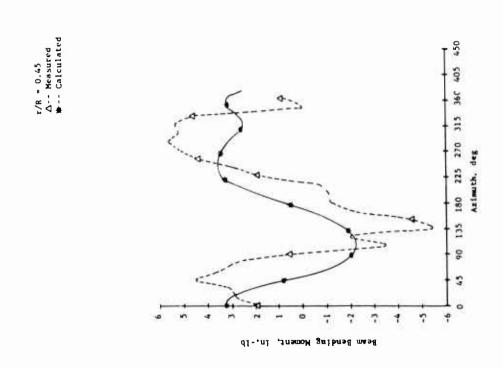


Figure 61. Continued.

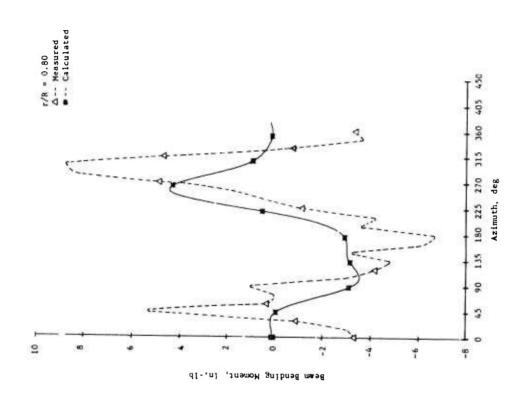
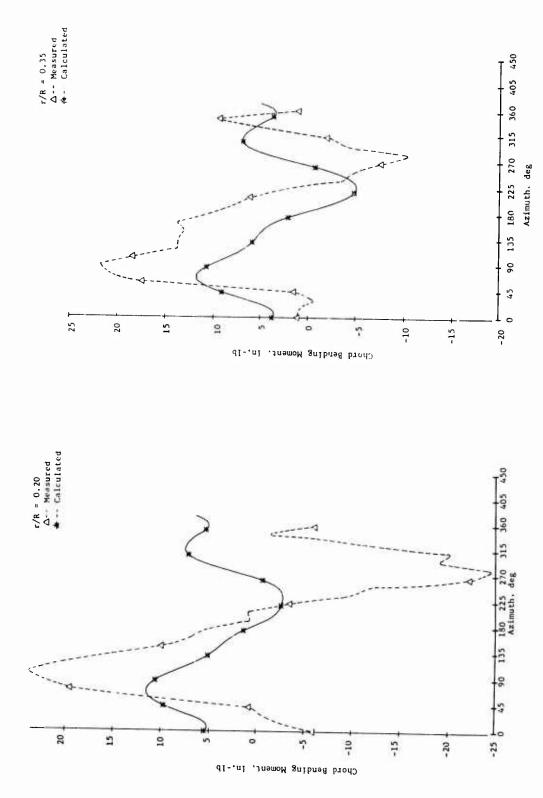
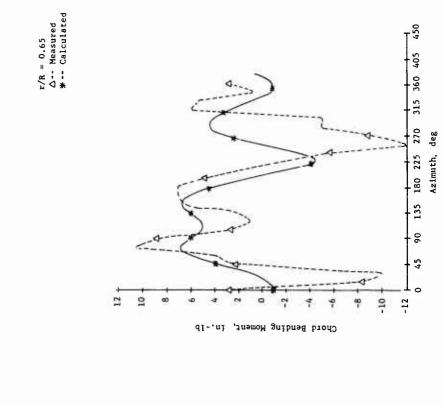
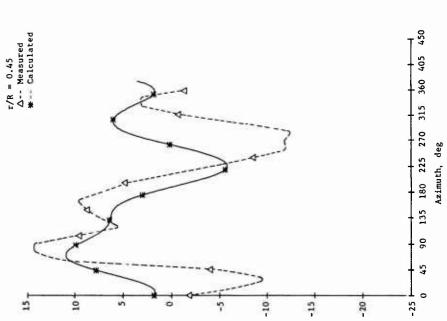


Figure 61. Concluded.



Measured and Calculated Chord Bending Moment Time Histories, Fiberglass Blade, -8 Twist. μ = 0.299, $M_{1,30}$ = 0.408, $\alpha_{\rm m}$ = 0°(Cond. 68). Figure 62.





Chord Bending Moment, in.-lb

Figure 62. Continued.

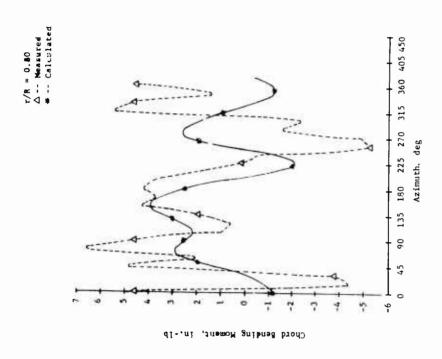
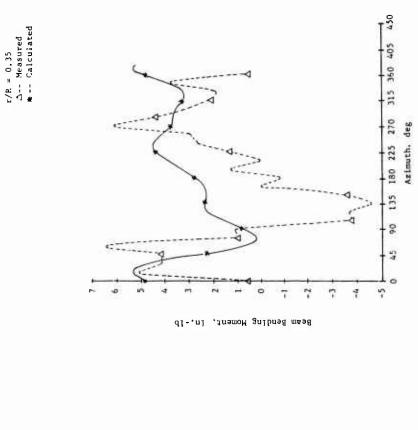
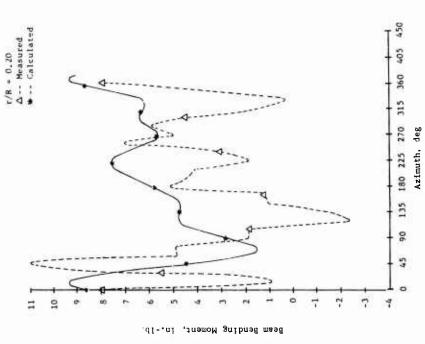


Figure 62. Concluded.





Measured and Calculated Beam Bending Moment Time Histories, Fiberglass Blade, 0 Twist, $\delta_{\rm F}=5$ $\mu=0.399,~M_{1,90}=0.434,~\alpha_{\rm m}=0.5$ (Cond. 25). Figure 63.

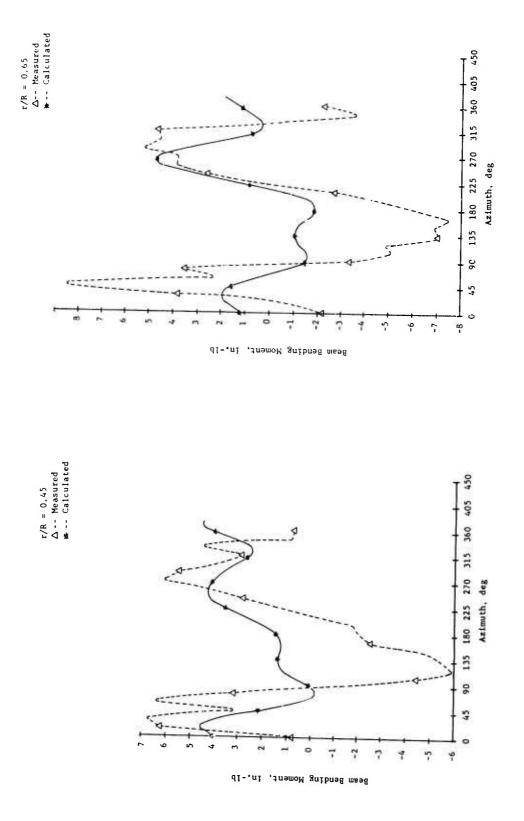


Figure 63. Continued.

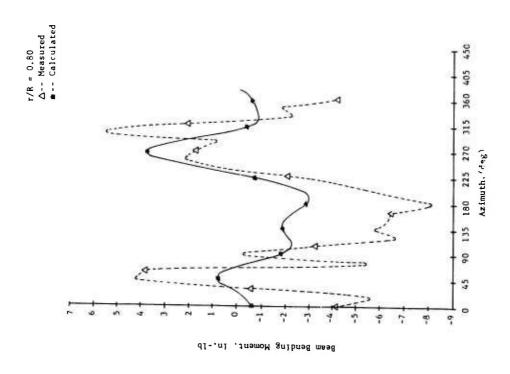
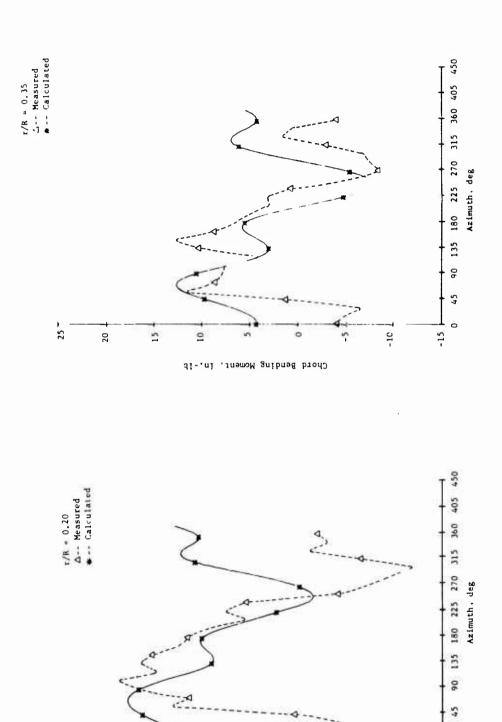


Figure 63. Concluded.



Measured and Calculated Chord Bending Moment Time Histories, Fiberglass Blade, 0 Twist, $\delta_{\tilde{h}} = 5$ $\mu = 0.399$, M_{1,90} = 0.434, $\alpha_{m} = 0.5$ (Conf. 25). Figure 64.

Chord Bending Moment, in.-lb

20 +

15+

10

0

-20

-15

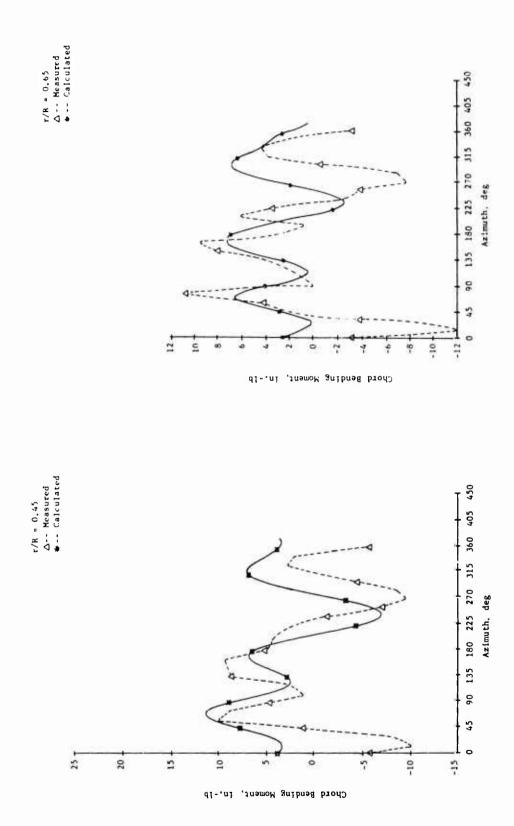


Figure 64. Continued.

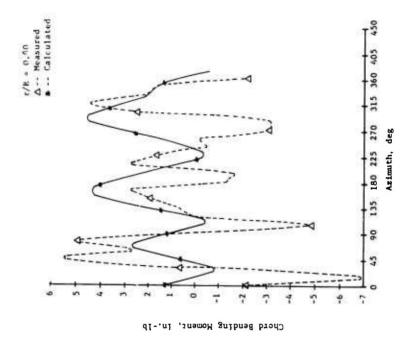
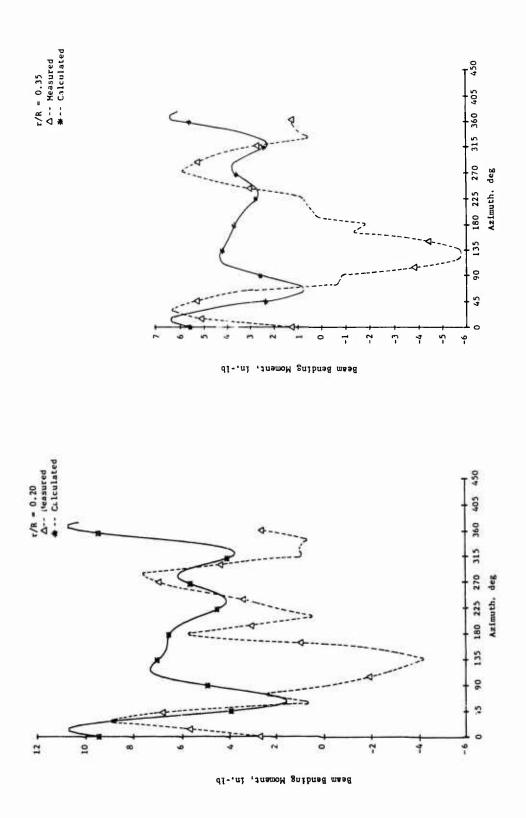
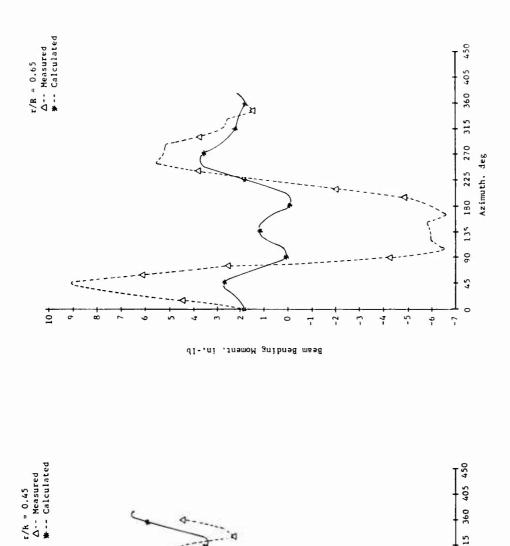
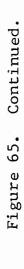


Figure 64. Concluded.



Measured and Calculated Beam Bending Moment Time Histories, Fiberglass Blade, 0 Twist, $\delta_F = 5^\circ$ $\mu = 0.502$, $M_{1,90} = 0.467$, $\alpha_m = 5$ (Cond. 44). Figure 65.





90

45

Azimuth, deg

Beam Bending Moment, in.-1b

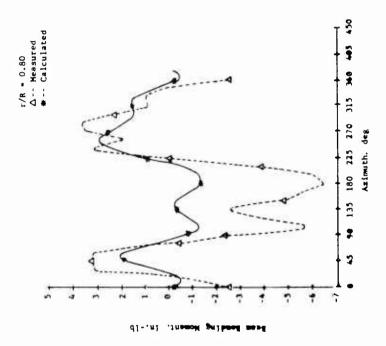


Figure 65. Concluded.

r/R = 0.35 Δ-- Medsured *- Calculated 20 + 15 10 Chord Bending Moment, in. - 1b r/R = 0.20 Δ-- Measured γ -- Calculated 15 7 91

Measured and Calculated Chord Bending Moment Time Histories, Fiberglass Blade, 0 Twist, $\delta_{\rm F}=5$ $\mu = 0.502$, $M_{1,90} = 0.467$, $\alpha_{\rm m}$ Figure 66.

135

-10

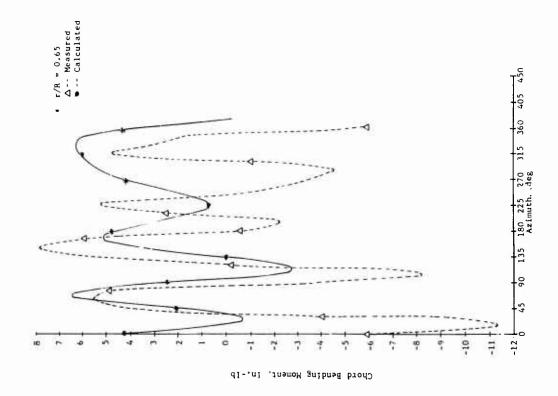
90 135

÷

Azimuth, deg

Azimuth, deg

Chord bending Moment, in.-lb



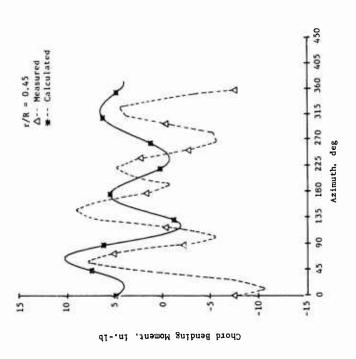


Figure 66.

Continued.

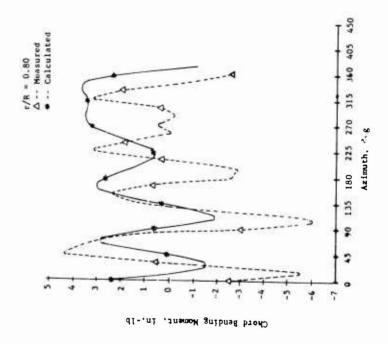
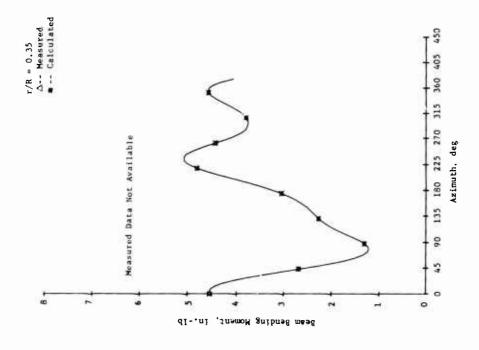
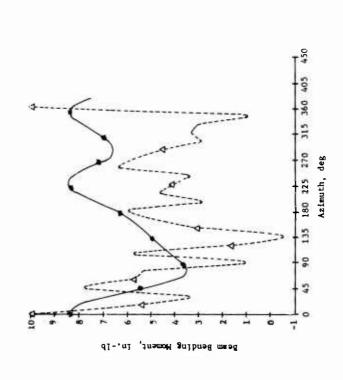


Figure 66. Concluded.



r/R = 0.20 Δ-- Measured *-- Calculated



Measured and Calculated Beam Bending Moment Time Histories, Fiberglass Blade, 0 Twist, $\delta_E = 5^\circ$ $\mu = 0.299$, $M_{1,90} = 0.408$, $\alpha_{\rm m} = 0^\circ$ (Cond. 68). Figure 67.

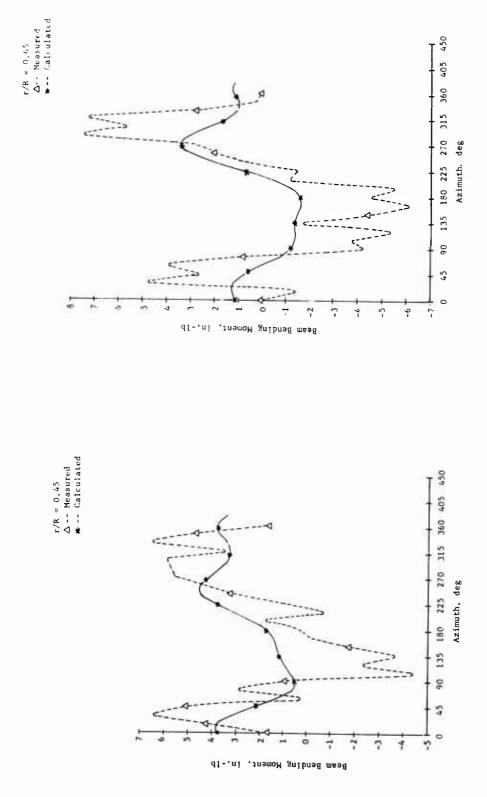


Figure 67. Continued.

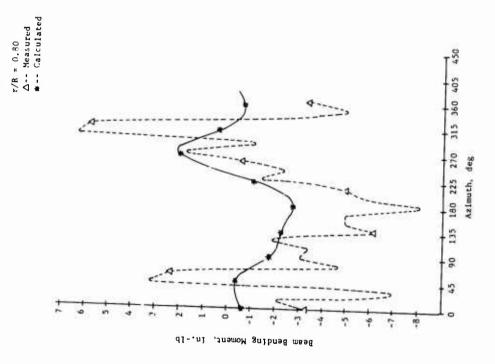
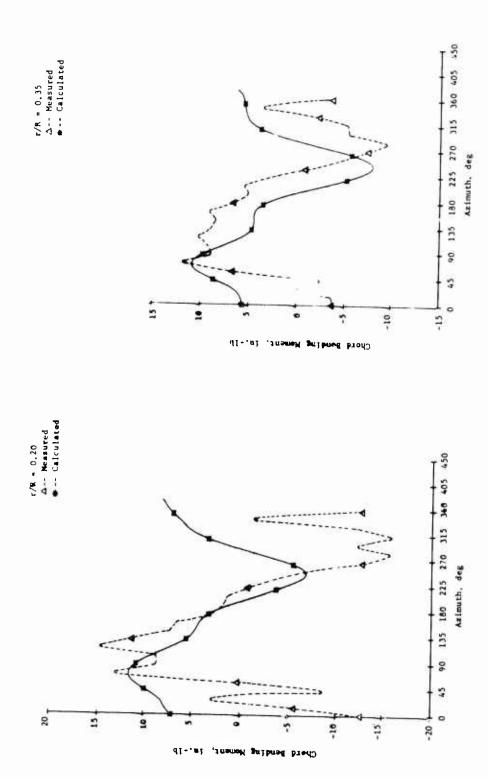
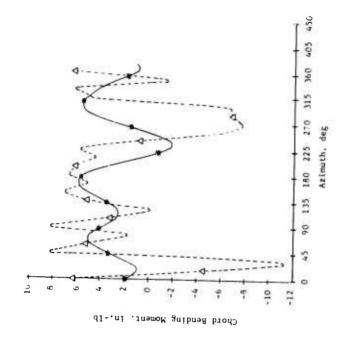


Figure 67. Concluded.



Measured and Calculated Chord Bending Moment Time Histories, Fiberglass Blade, C Twist, $\delta_F = 5^\circ$ $\mu = 0.299$, $M_{1,90} = 0.408$, $\alpha_{\rm m} = 0^\circ ({\rm Cond.~68})$. Figure 68.



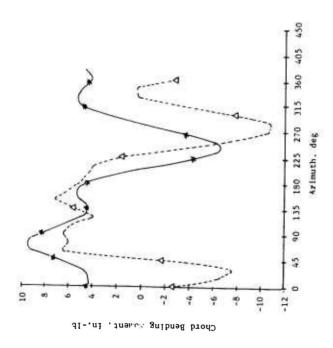


Figure 68. Continued.

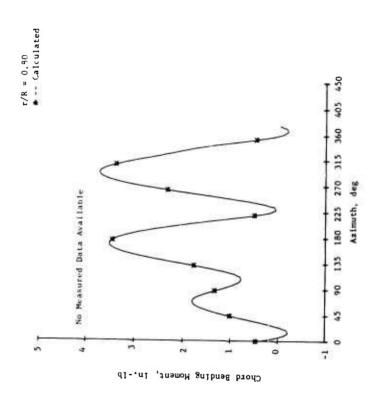
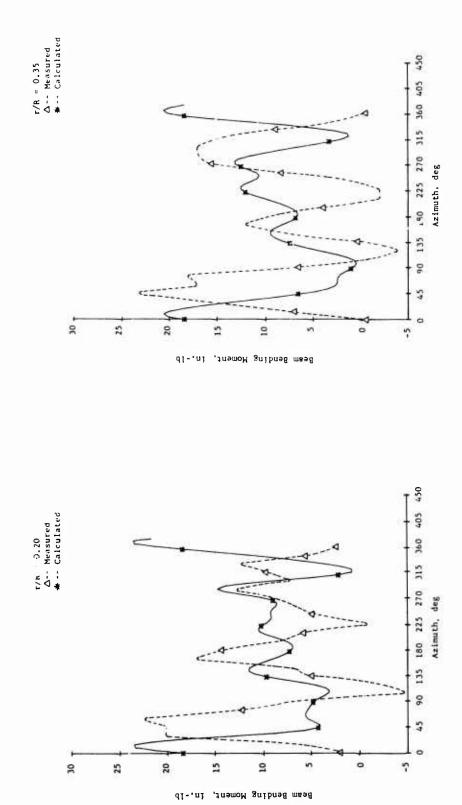
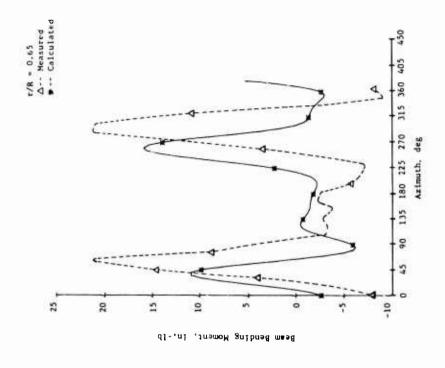


Figure 68. Concluded.



Measured and Calculated Beam Bending Moment Time Histories, Aluminum Blade, 0° Twist, $\mu = 0.399$, $M_{1,90} = 0.434$, $\alpha_{\rm m} = 0.5^{\circ}$ (Cond. 25). Figure 69.



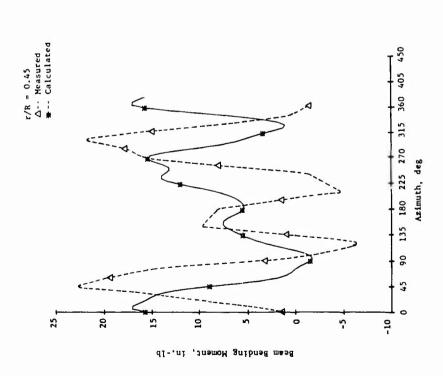


Figure 69. Continued.

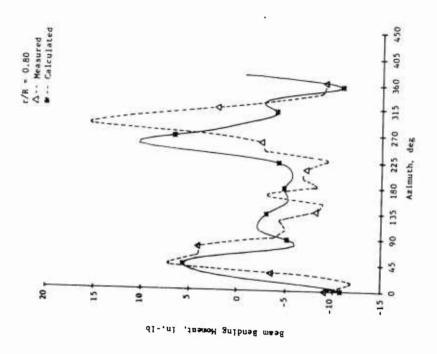
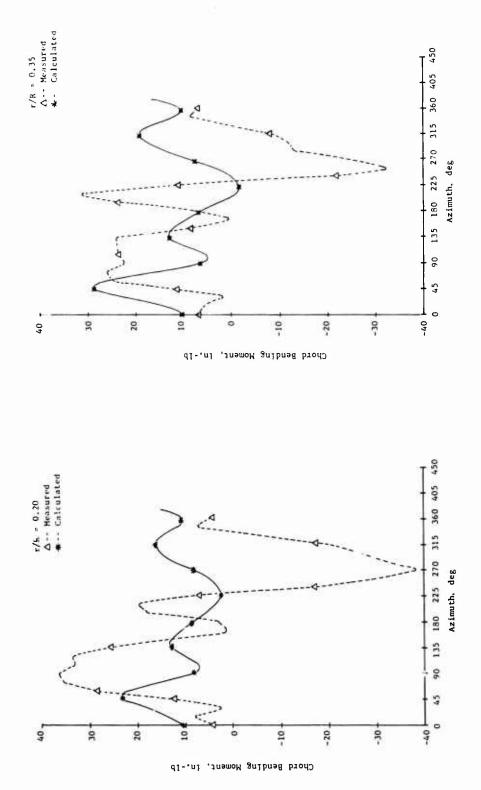
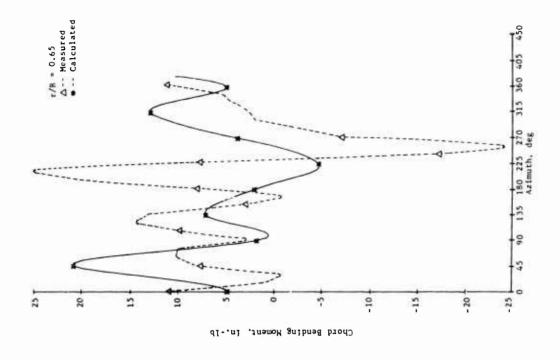


Figure 69. Concluded.



Measured and Calculated Chord Bending Moment Time Histories, Aluminum Blade, 0 Twist, $\mu=0.399,\ M_1,90=0.434,\ \alpha_m=0.5$ (Cond. 25). Figure 70.



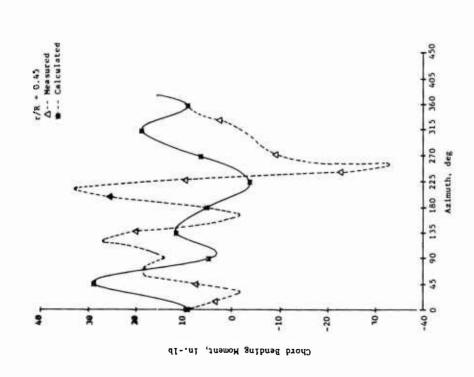


Figure 70. Continued.

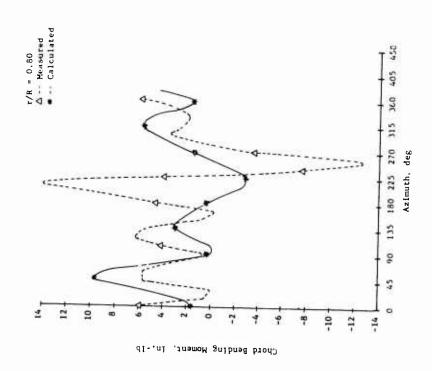
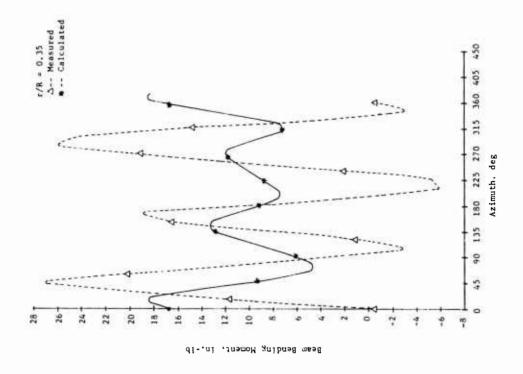
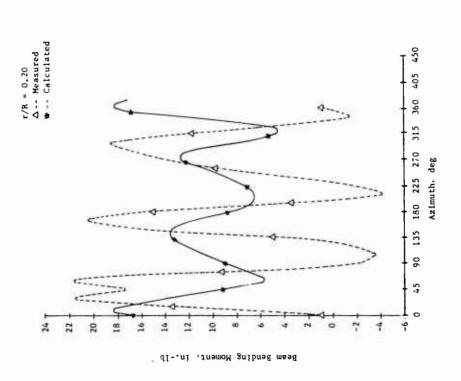
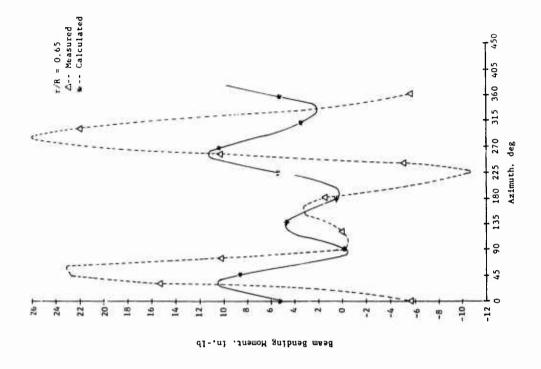


Figure 70. Concluded.





Measured and Calculated Beam Bending Moment Time Histories, Aluminum Blade, 0° Twist, $\mu = 0.502$, $M_{1,90} = 0.467$, $\alpha_{\rm m} = 5^{\circ}$ (Cond. 44). Figure 71.



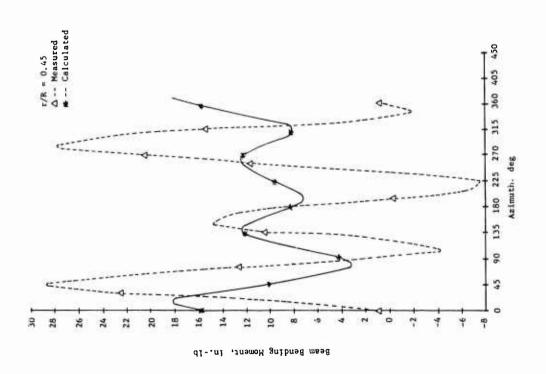


Figure 71. Continued.

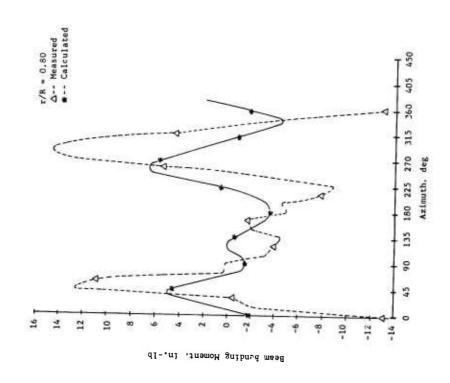
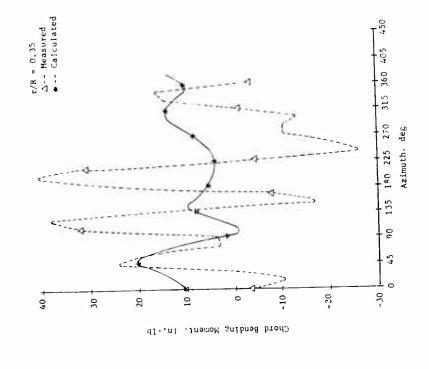
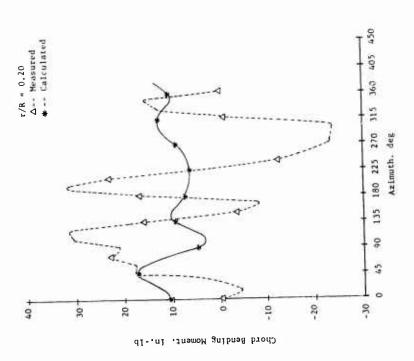
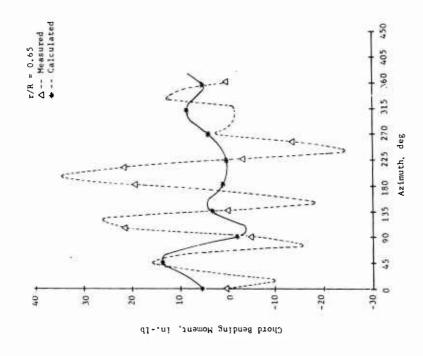


Figure 71. Concluded.





Measured and Calculated Chord Bending Moment Time Histories, Aluminum Blade, 0 Twist, $\mu=0.502$, $M_{1,90}=0.467$, $\alpha_{m}=5$ (Cond. 44). Figure 72.



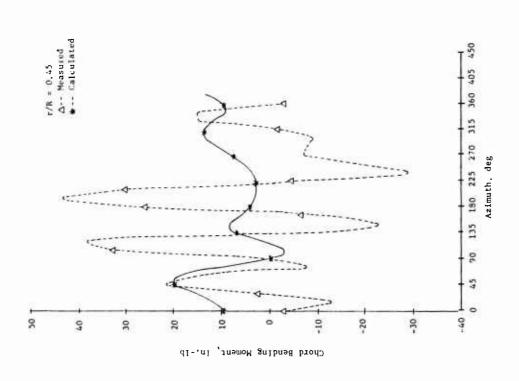


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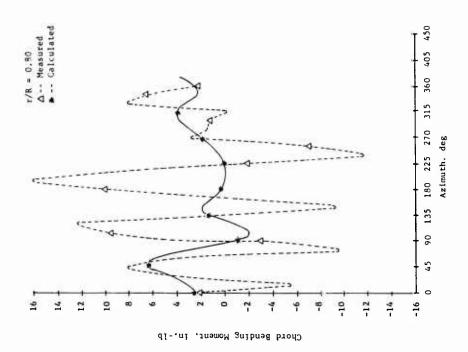
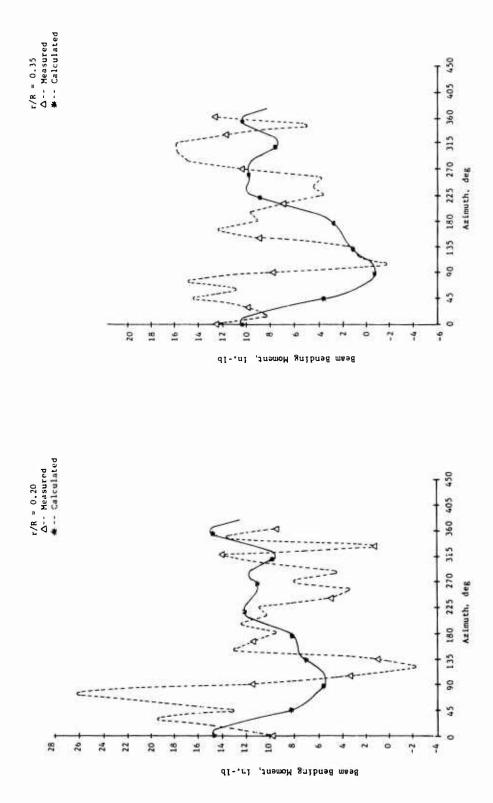
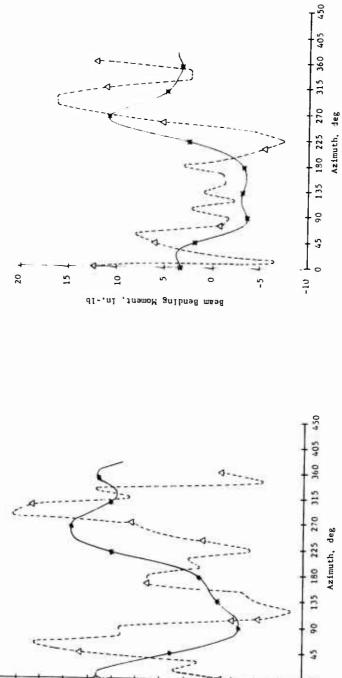


Figure 72. Concluded.



Measured and Calculated Beam Bending Moment Time Histories, Aluminum Blade, 0 Twist, $\mu=0.299,\ M_{1,90}=0.408,\ \alpha_{m}=0\ (\text{Cond. 68}).$ Figure 73.

r/R = 0.65 Δ-- Measured * -- Calculated 20 + 15 10 r/R = 0.45 Δ-- Measured *-- Calculated



Continued. Figure 73.

9 Beam Bending Moment, in.-lb

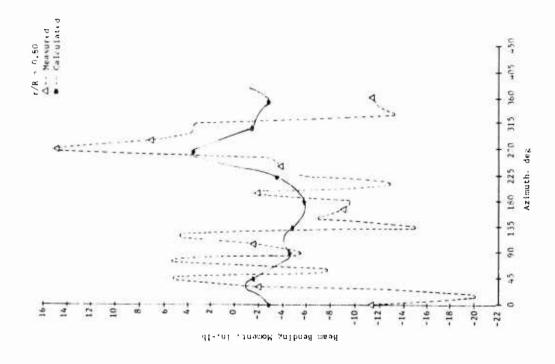
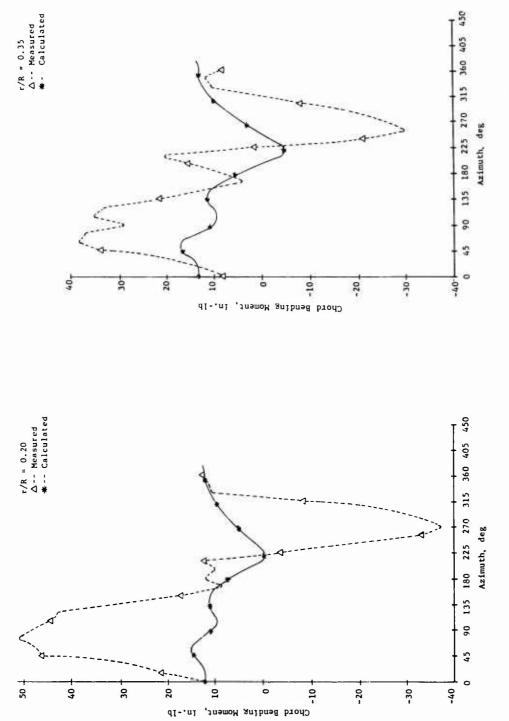
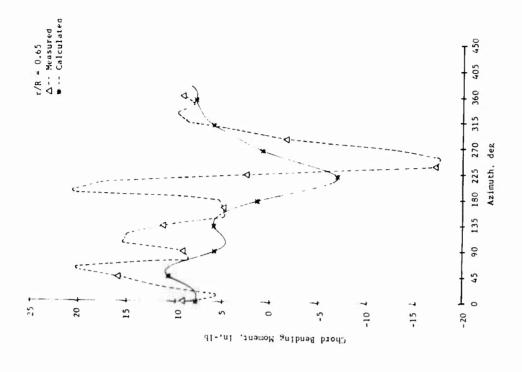


Figure 73. Concluded.



Measured and Calculated Chord Bending Moment Time Histories, Alumir.um Blade, 0 Twist, μ = 0.299, $M_{1,90}$ = 0.408, $\alpha_{\rm m}$ = 0 (Cond. 68). Figure 74.



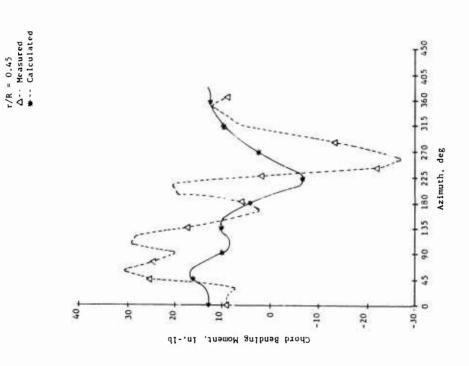


Figure 74. Continued.



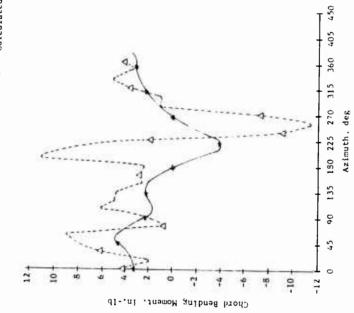
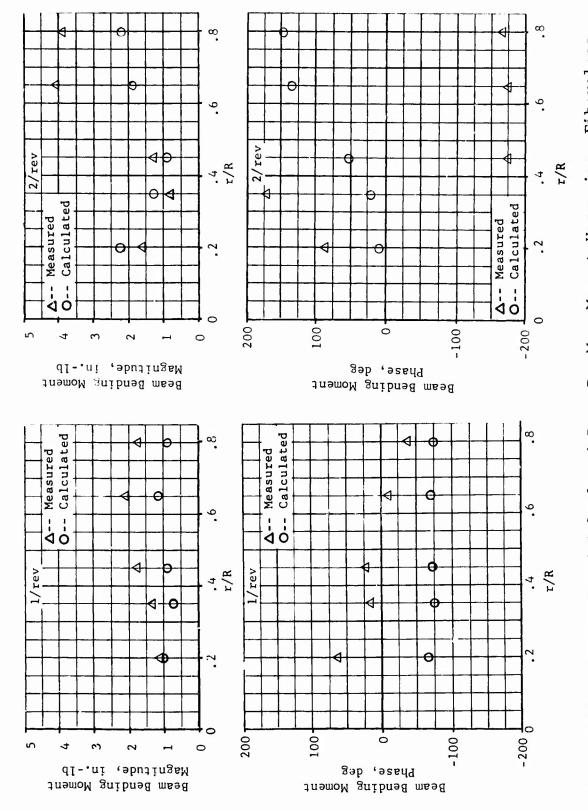


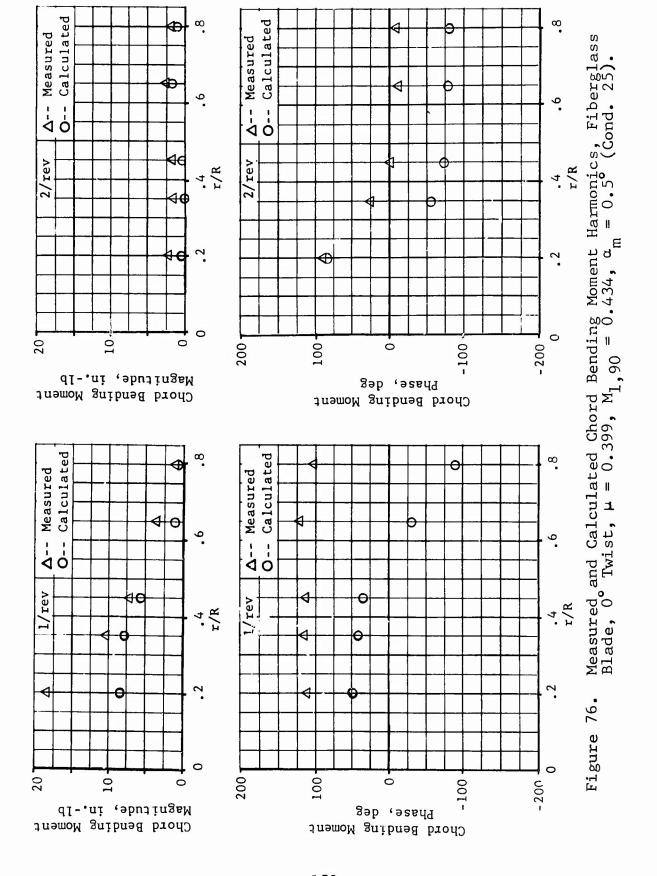
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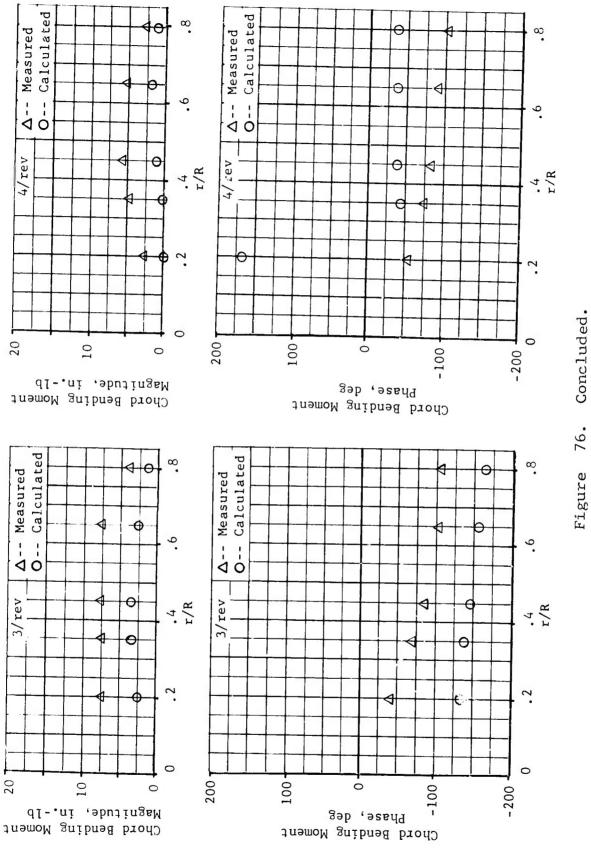


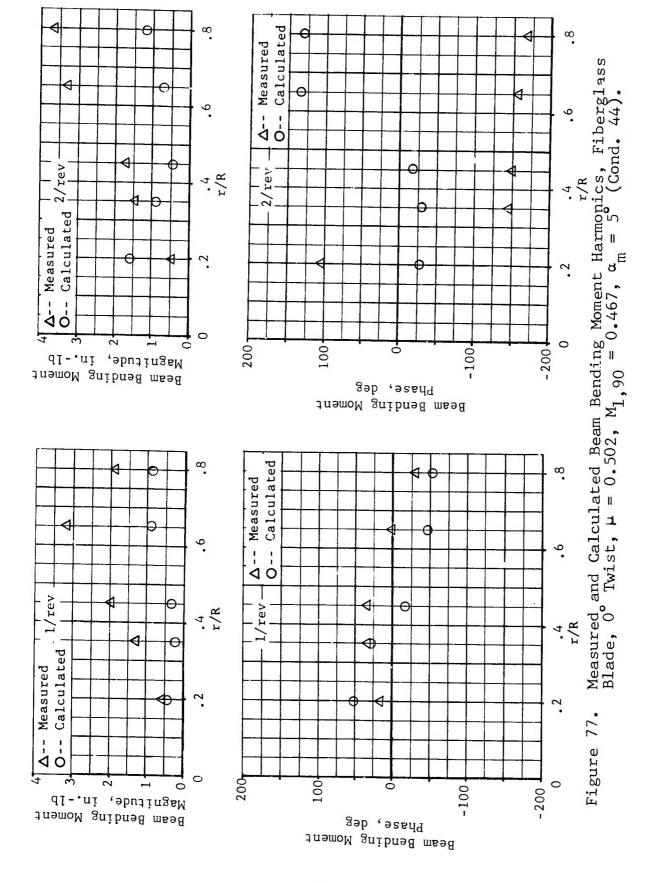
Measured and Calculated Beam Bending Moment Harmonigs, Fiberglass Blade, 0° Twist, μ = 0.399, $M_{1,90}$ = 0.434, $\alpha_{\rm m}$ = 0.5 (Cond. 25). Figure 75.

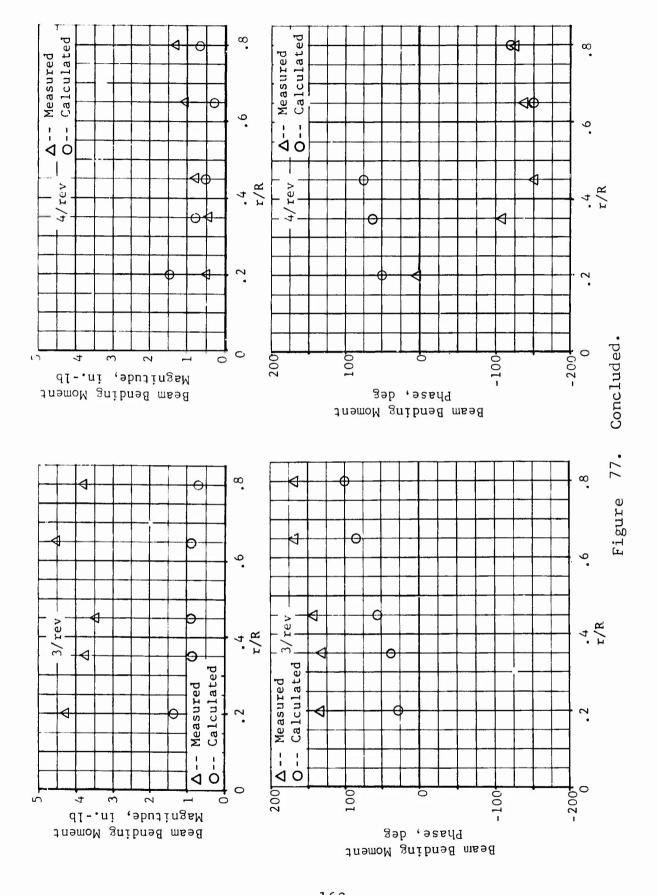
158

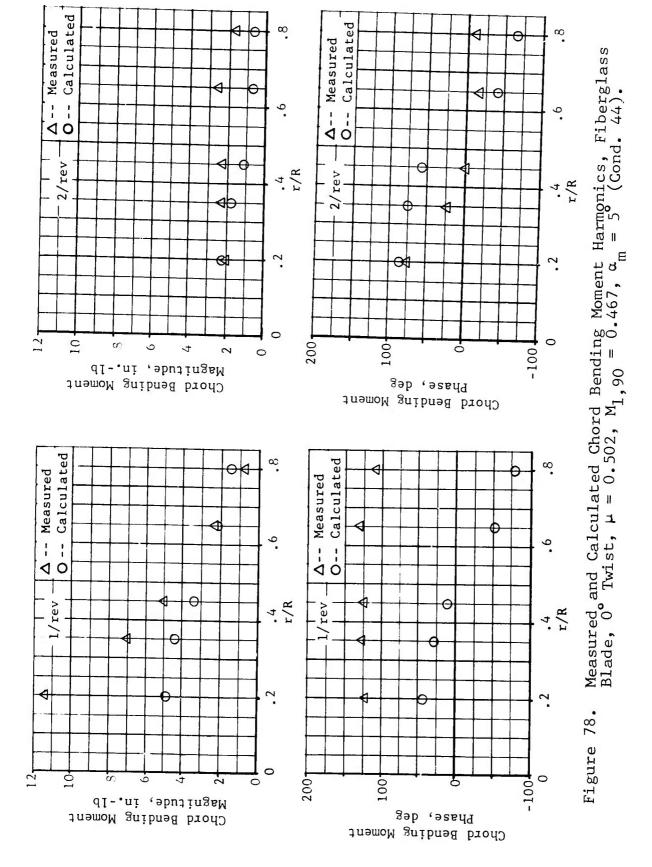




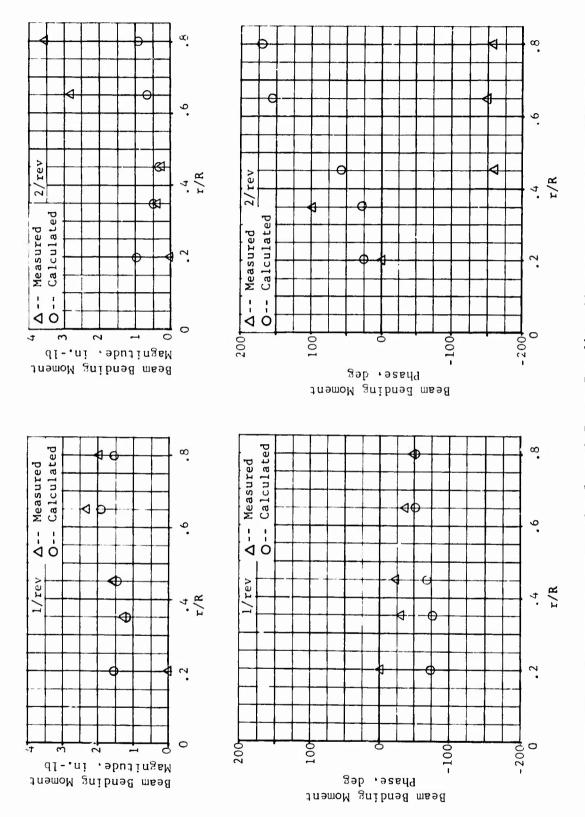




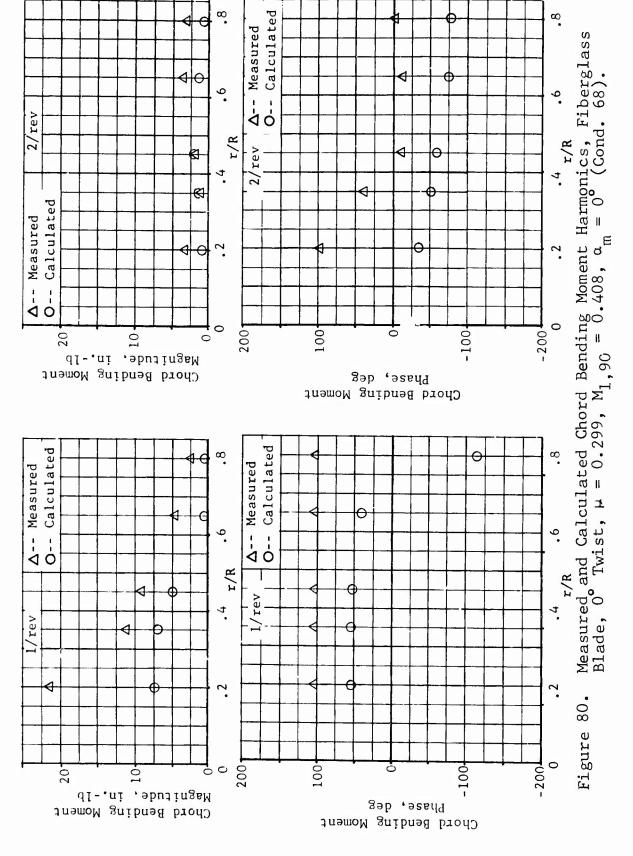


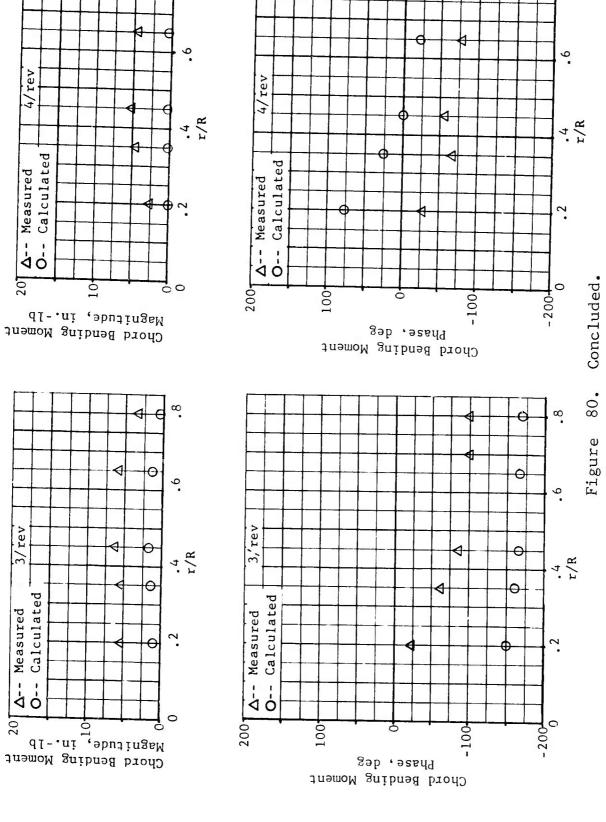


Chord Bending Moment

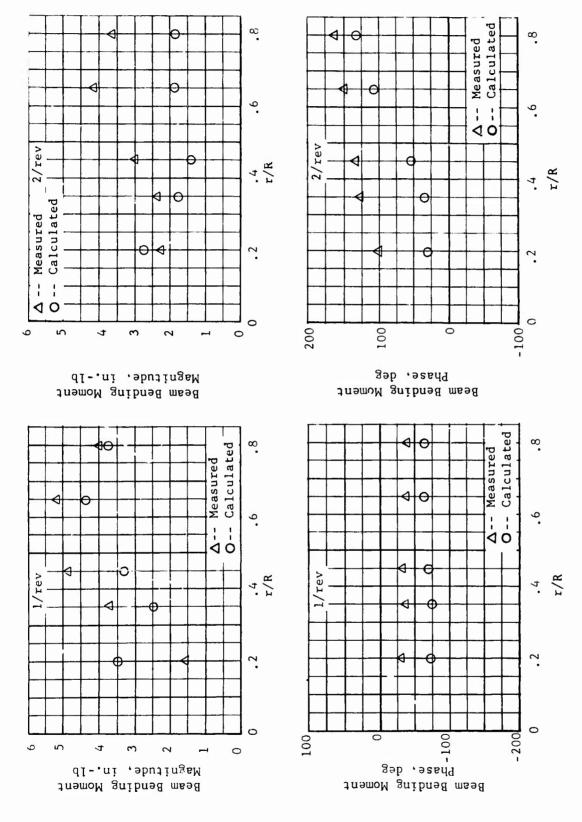


Measured and Calculated Beam Bending Moment Harmonics, Fiberglass Blade, 0 Twist, μ = 0.299, $M_{\rm I}$, $_{\rm 90}$ = 0.408, $_{\rm m}$ = 0 (Cond. 68). Figure 79.

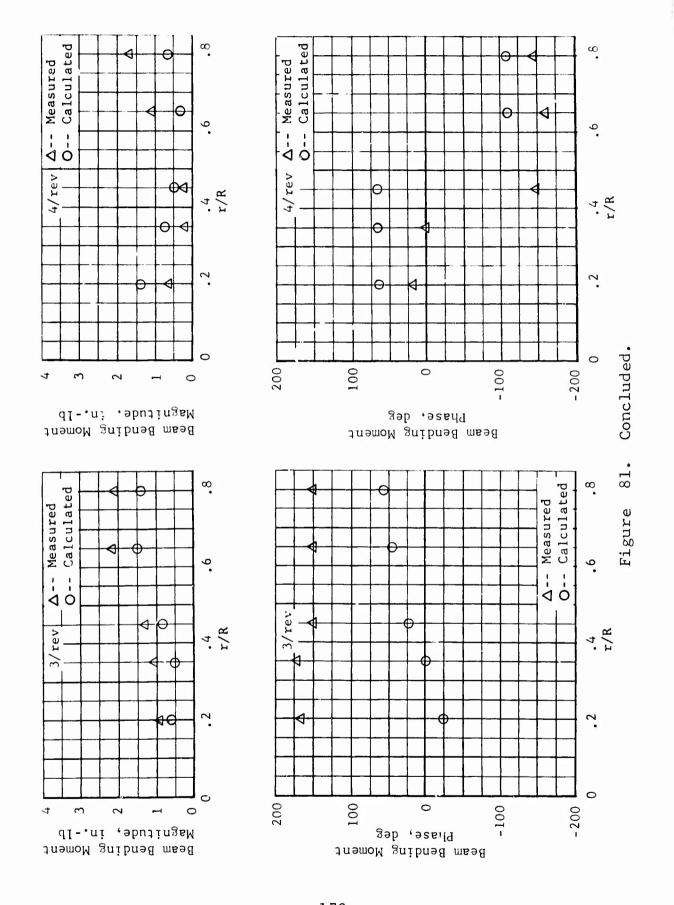


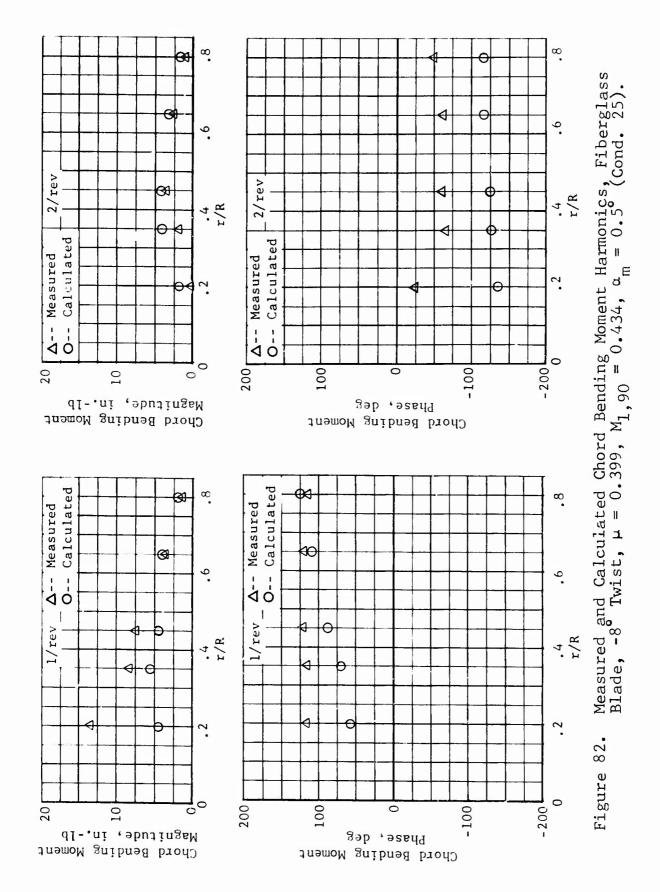


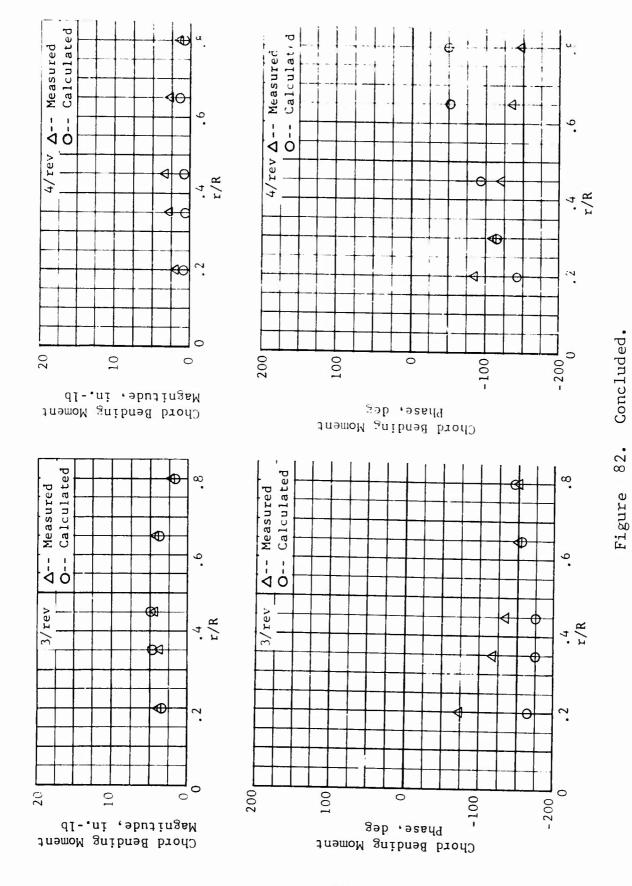
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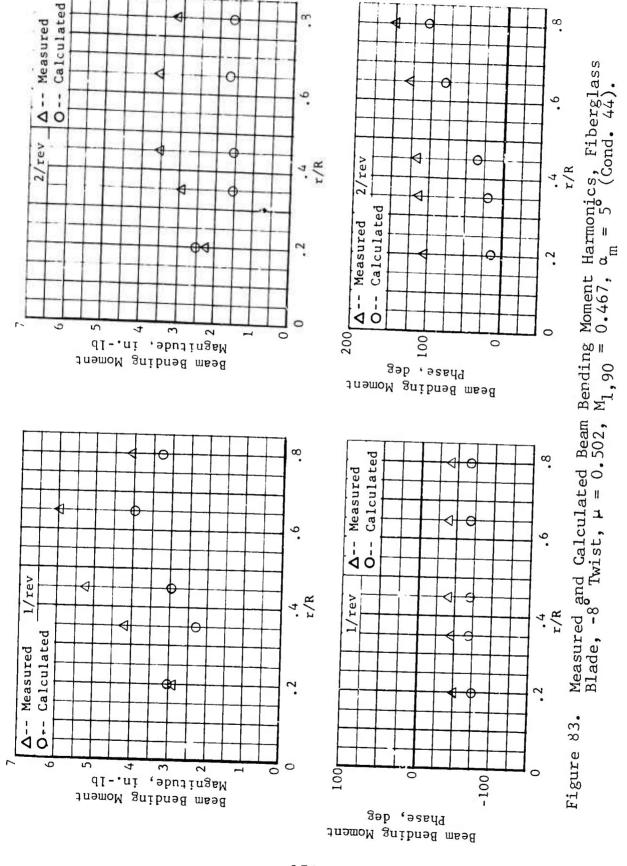


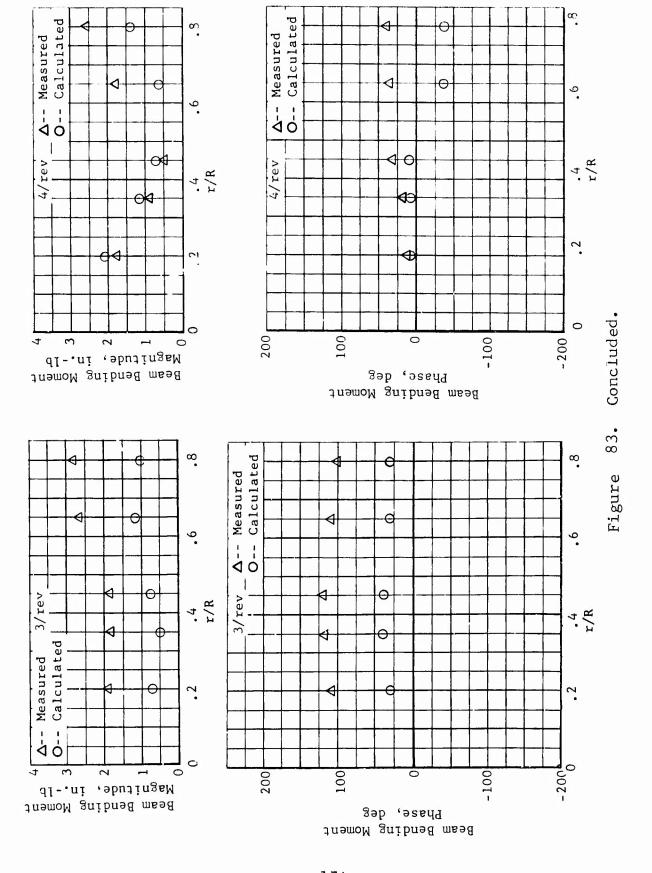
Measured and Calculated Beam Bending Moment Harmonics, Fiberglass Blade, -8 Twist, μ = 0.399, $M_{1,90}$ = 0.434, α_{m} = 0.5 (Cond. 25). Figure 81.

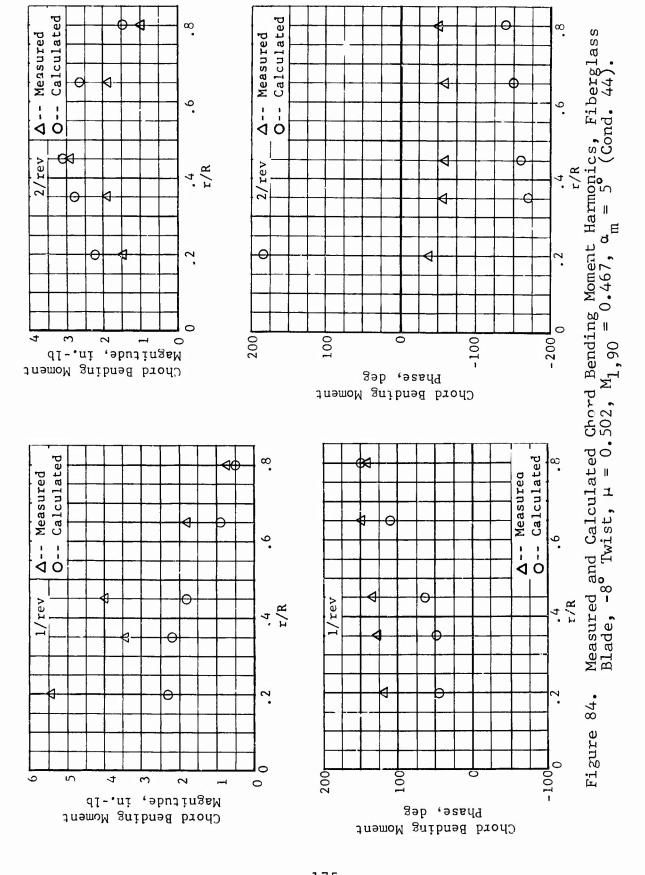


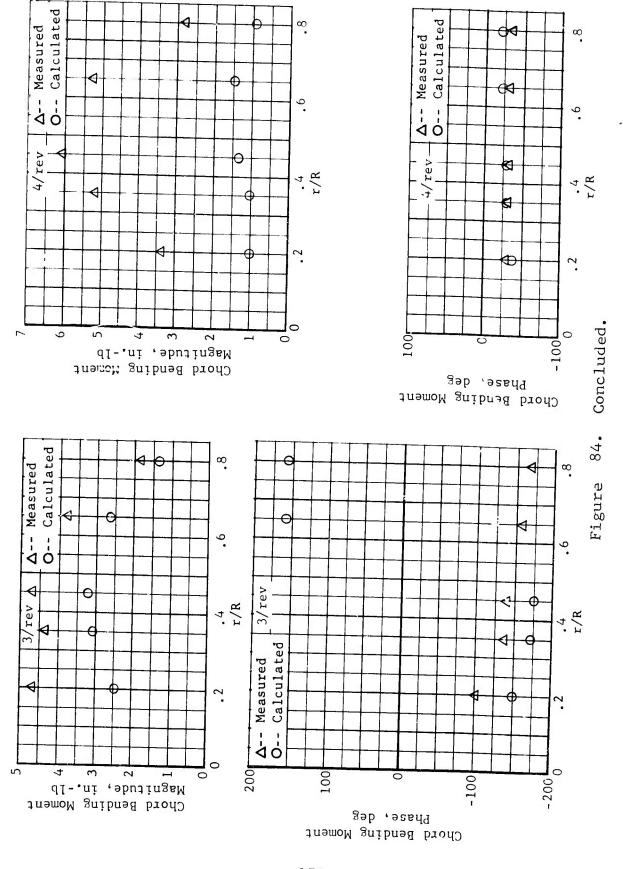


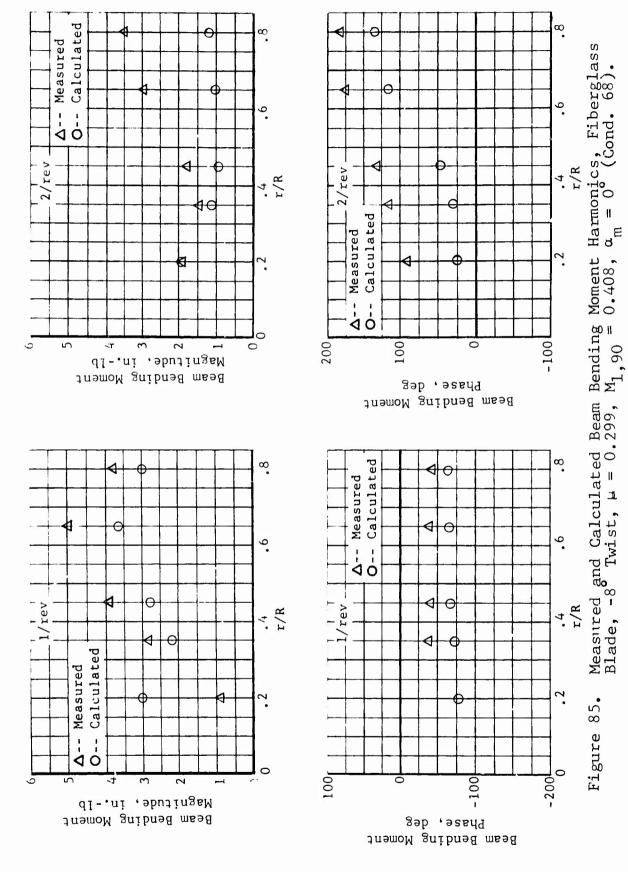


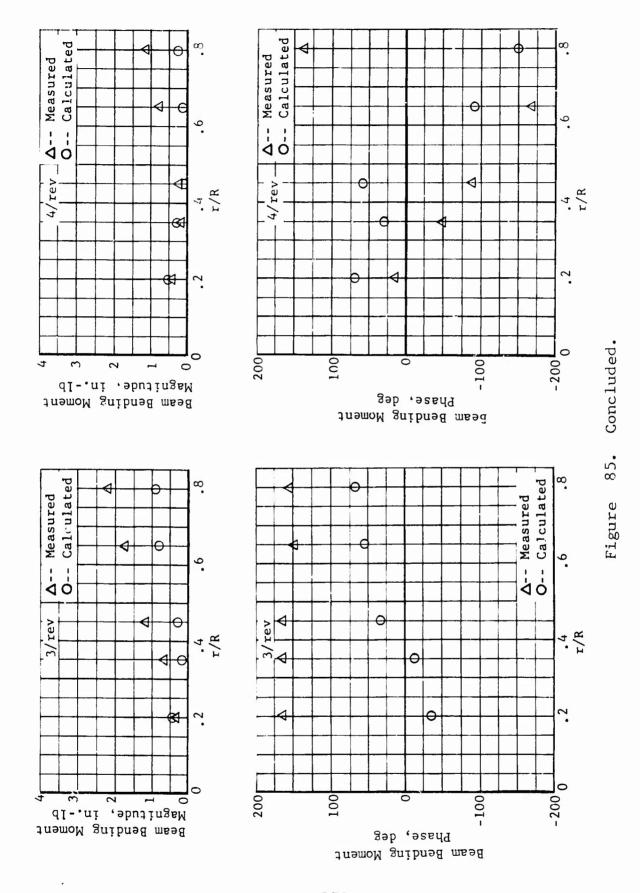


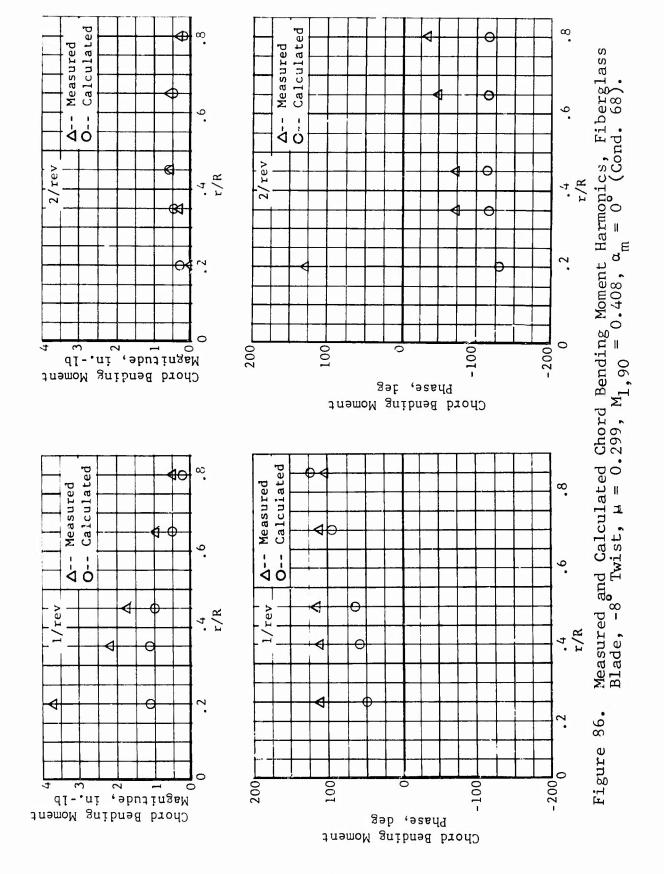


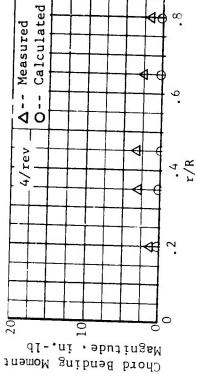


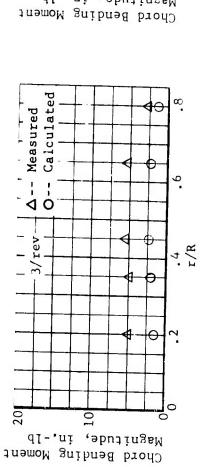


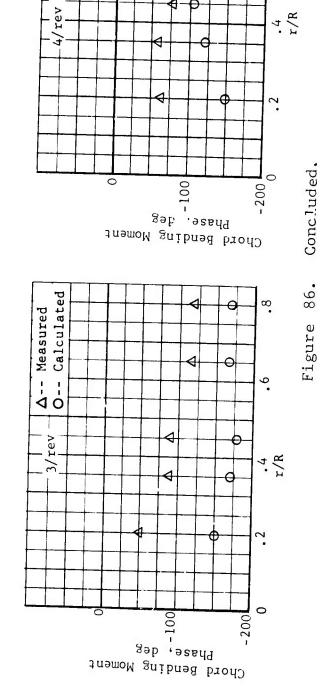






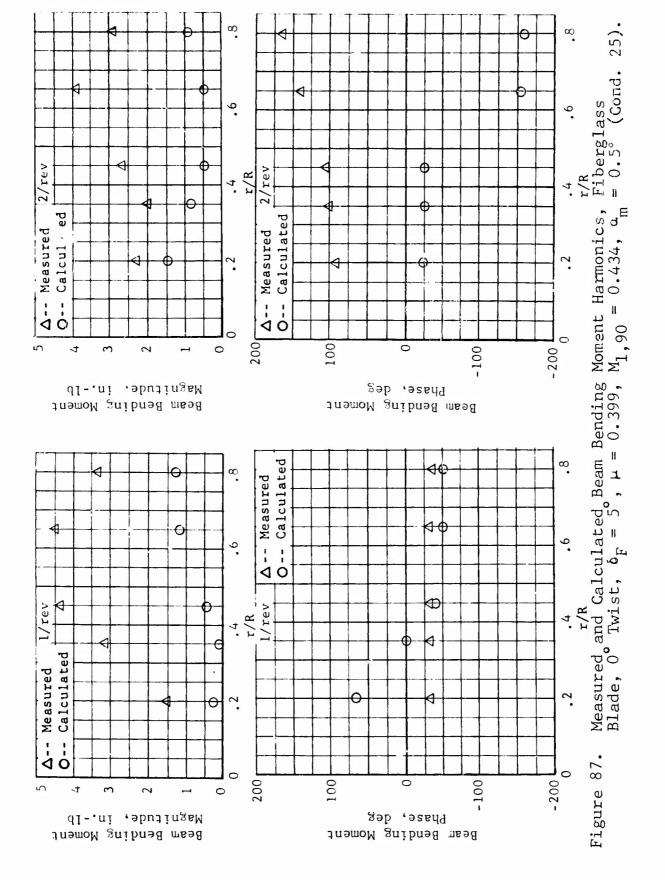


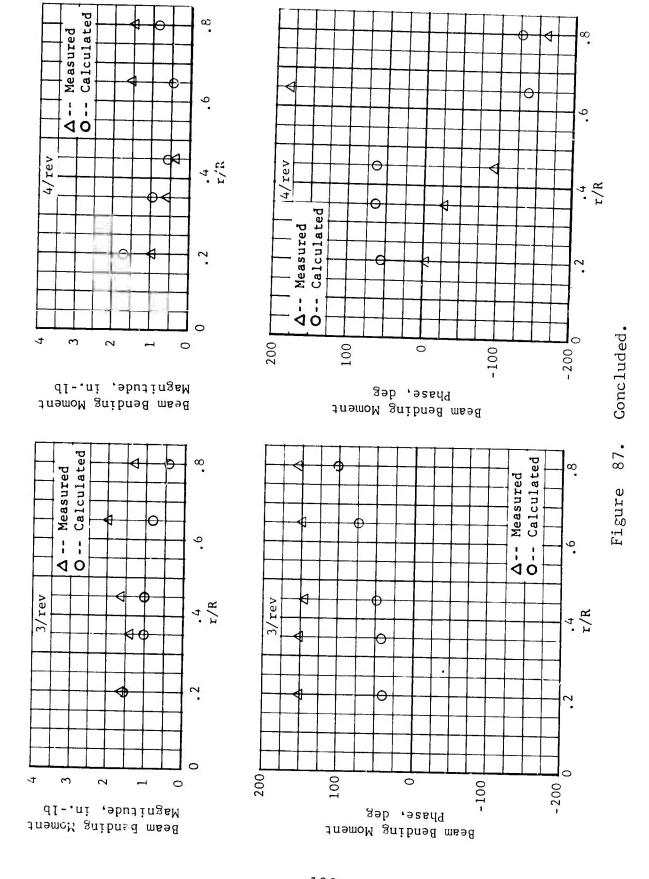


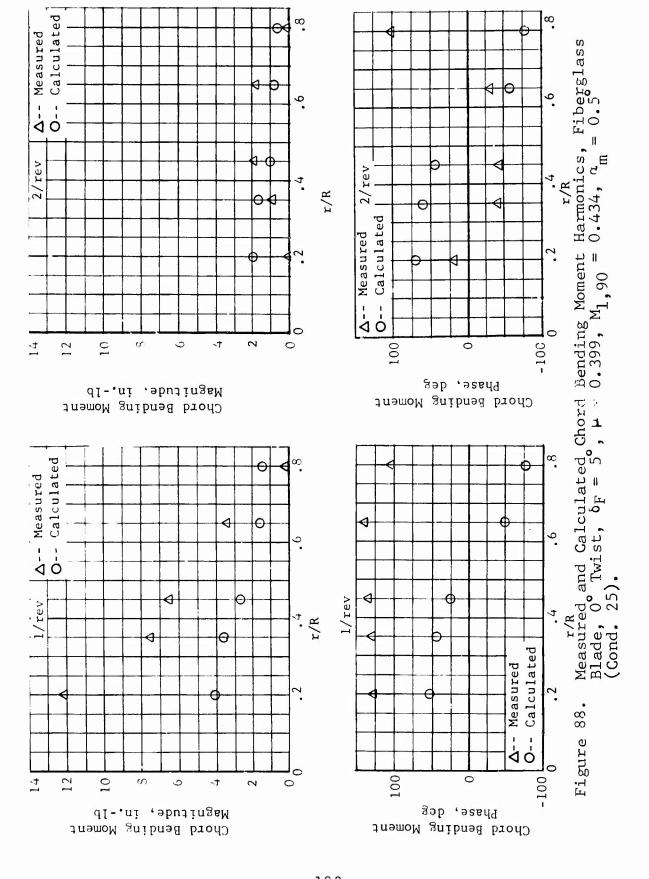


9.

Δ-- Measured O-- Calculated







100

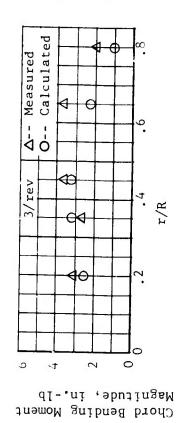
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Chord Bending Moment Phase, deg

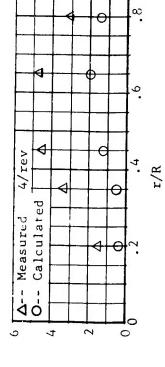
Measured Calculated

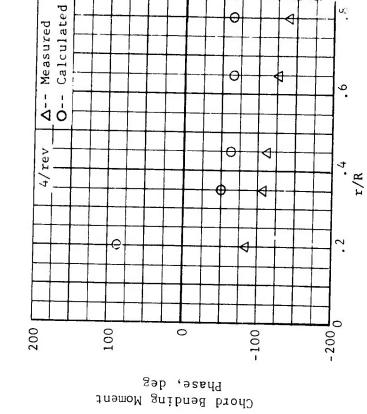
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3/rev



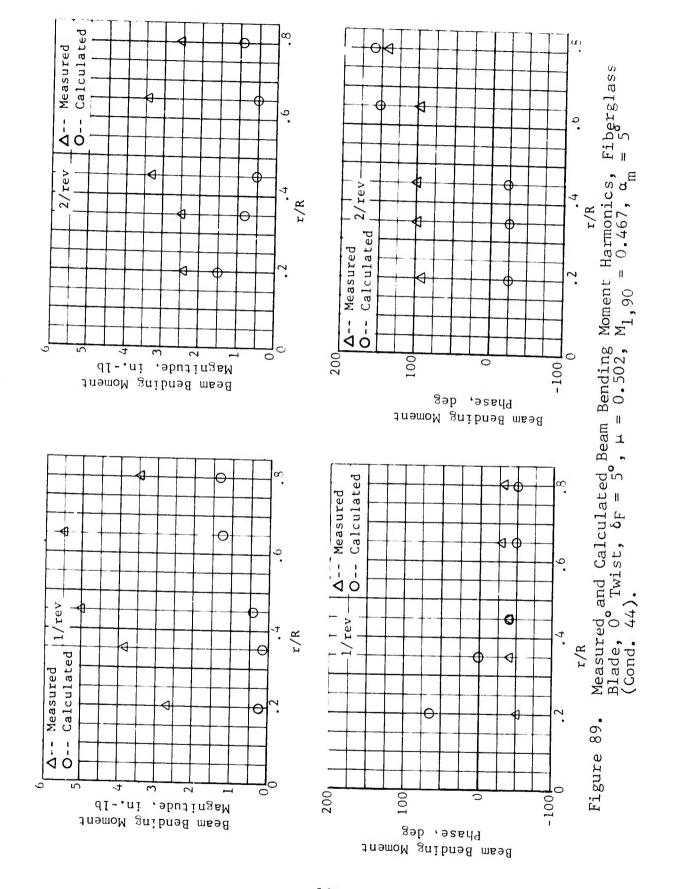
Chord Bending Moment Magnitude, in.-lb

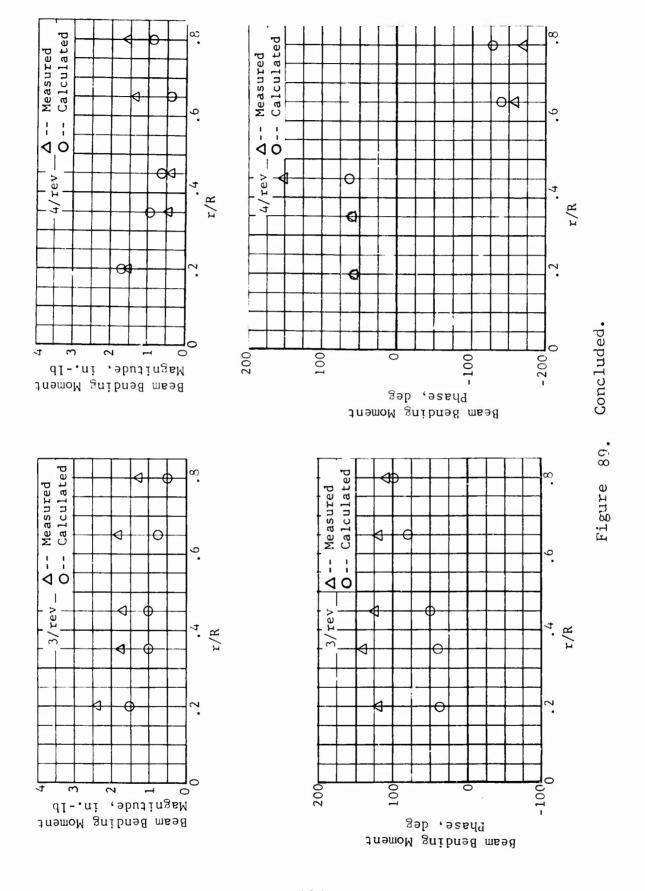


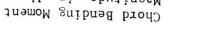


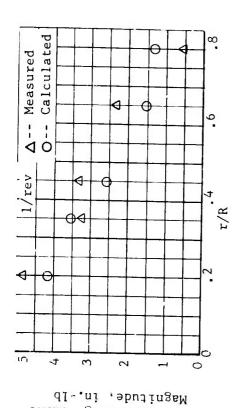


-200

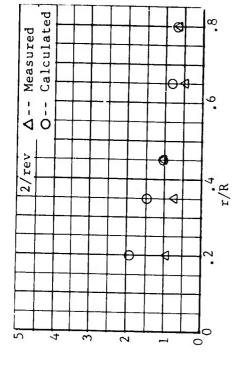








Magnitude, in.-lb Chord Bending Moment



Chord Bending Moment

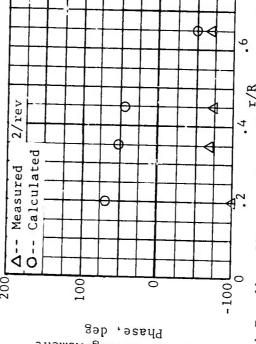


Figure 90.

Calculated

Δ-- Measured O-- Calculate

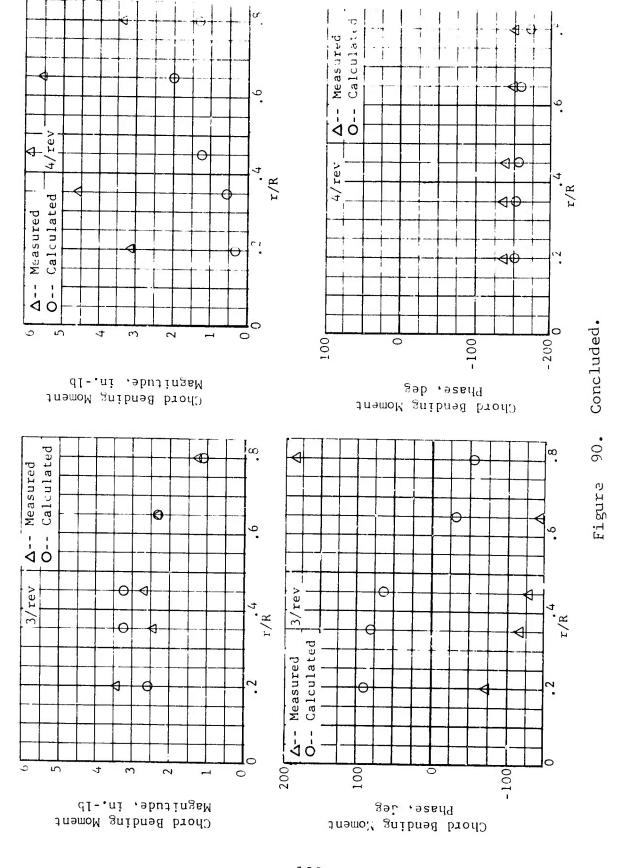
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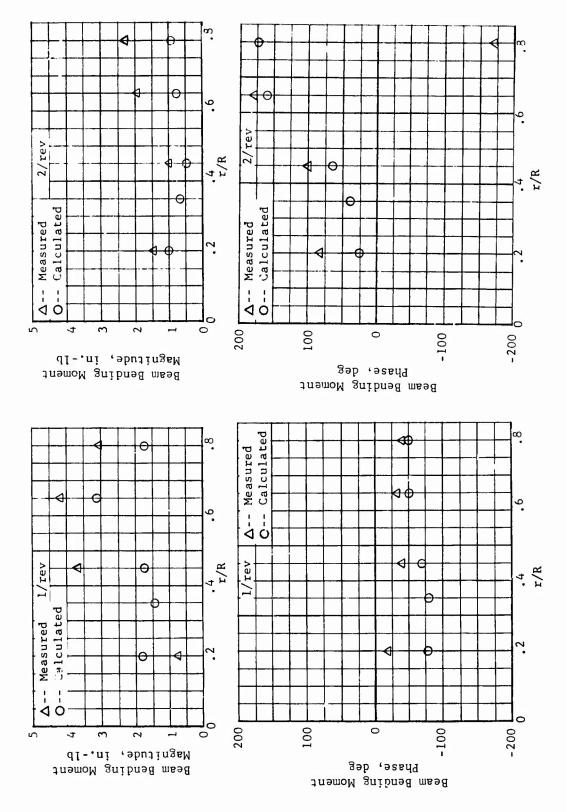
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Phase, deg

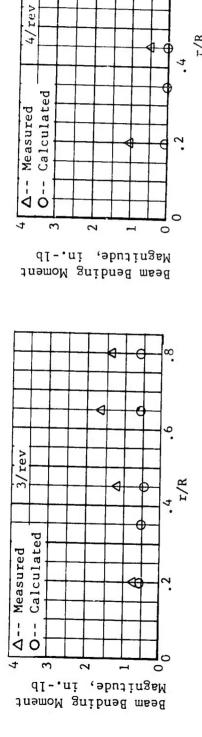
Chord Bending Moment

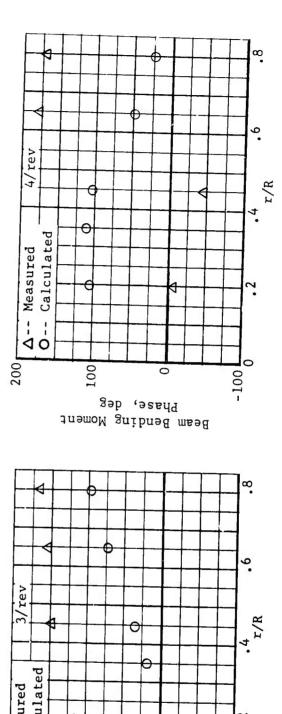
1/rev

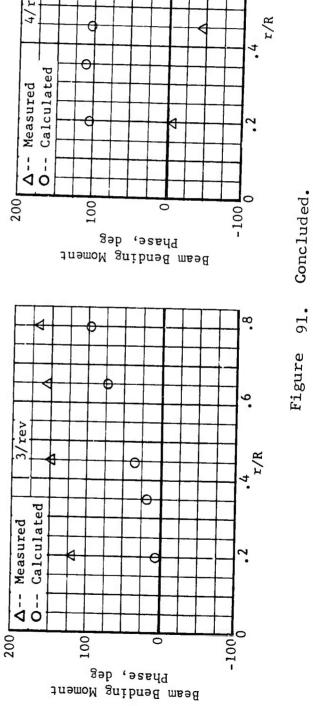


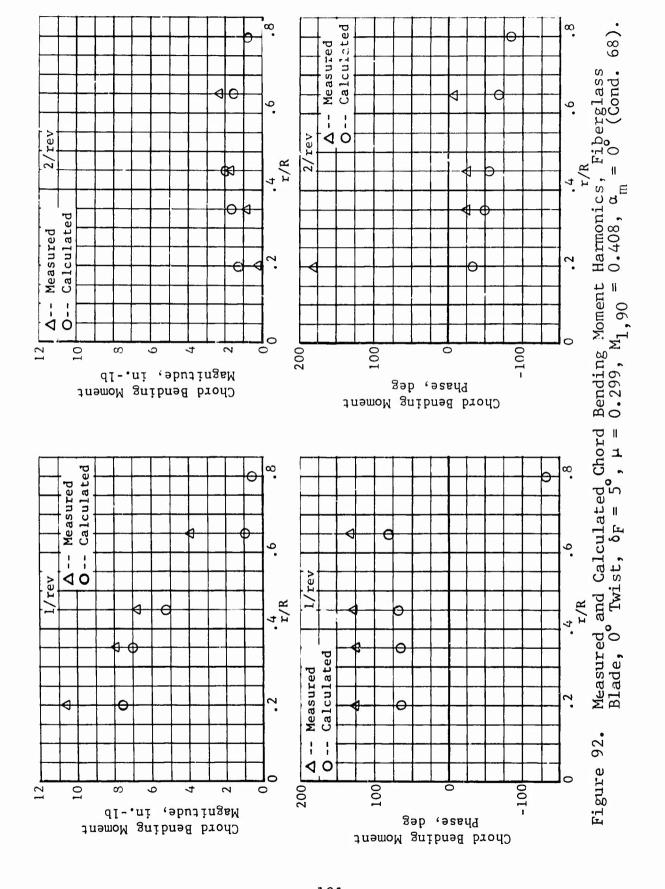


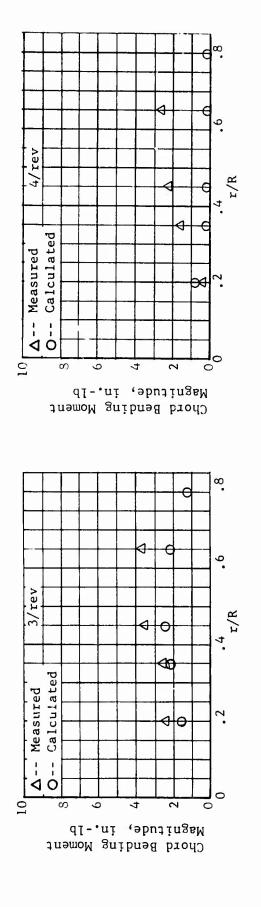
Measured and Calculated Beam Bending Moment Harmonics, Fiberglass Blade, 0° Twist, $\delta_F=5$, $\mu=0.299$, $M_{1,90}=0.408$, $\alpha_m=0$ (Cond. 68). Figure 91.

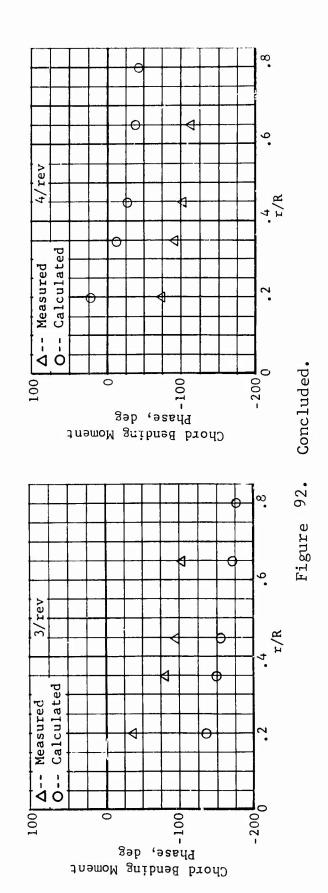


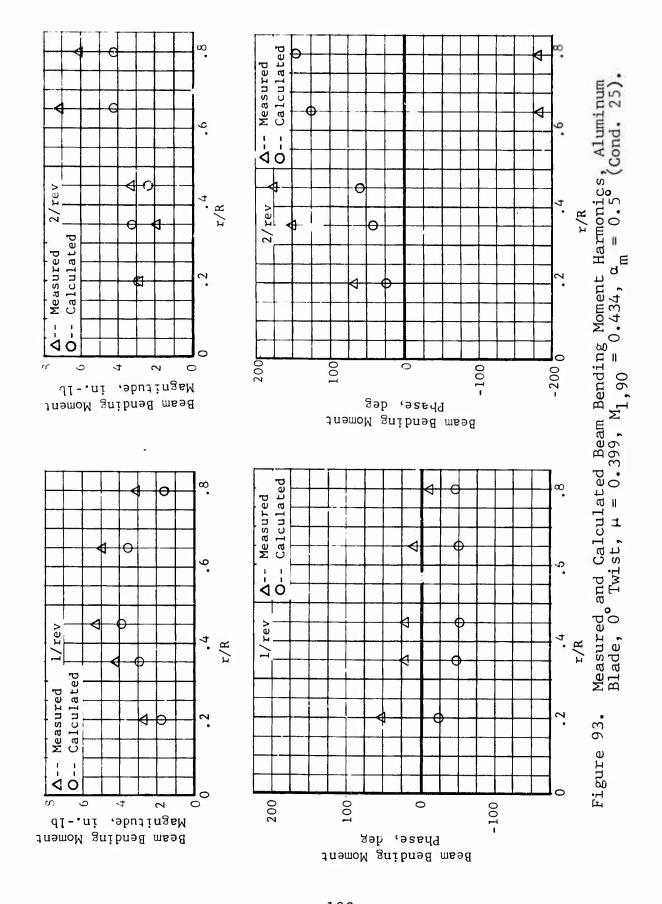


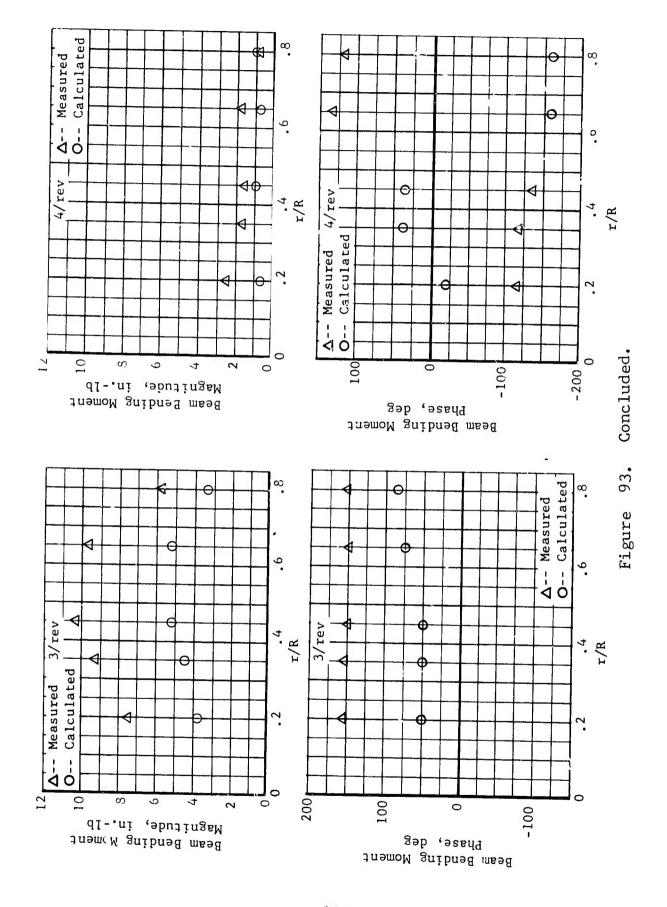


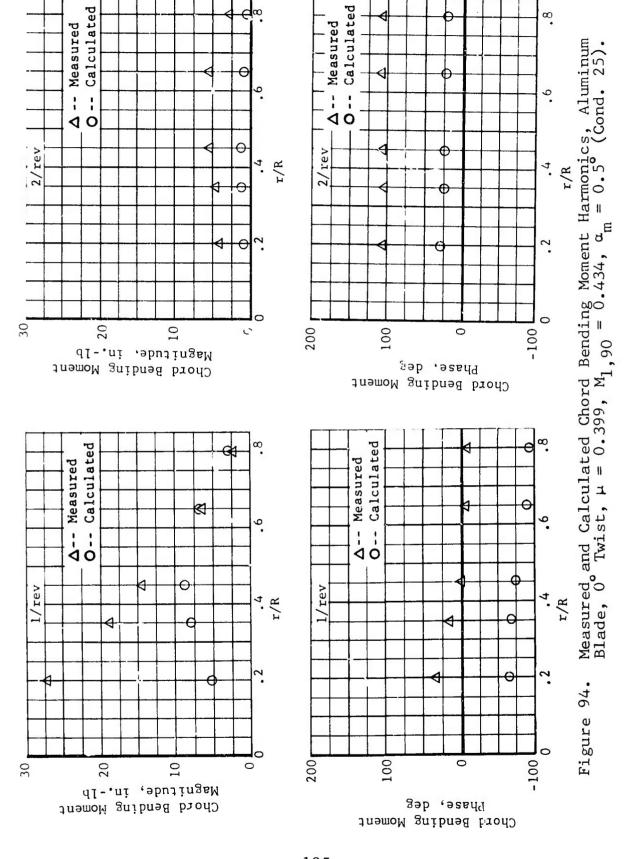


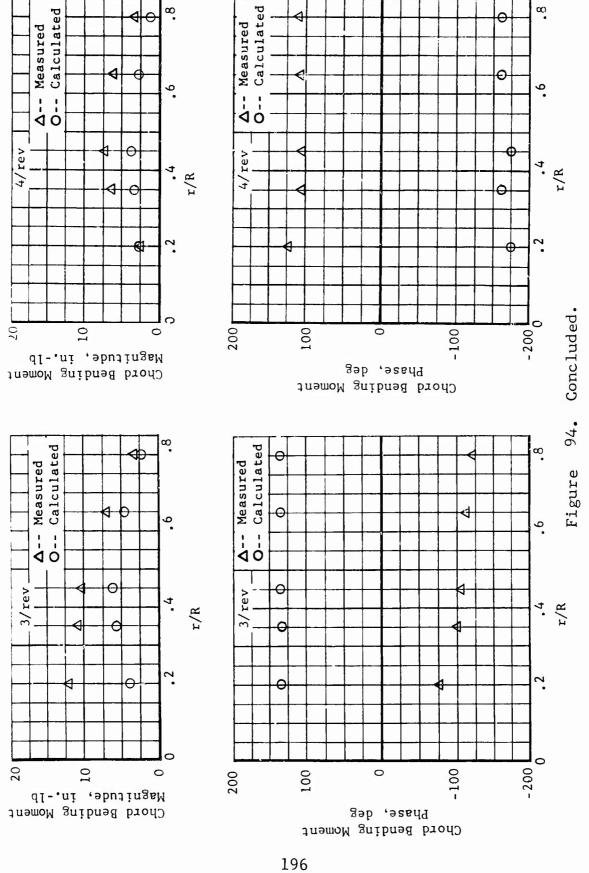


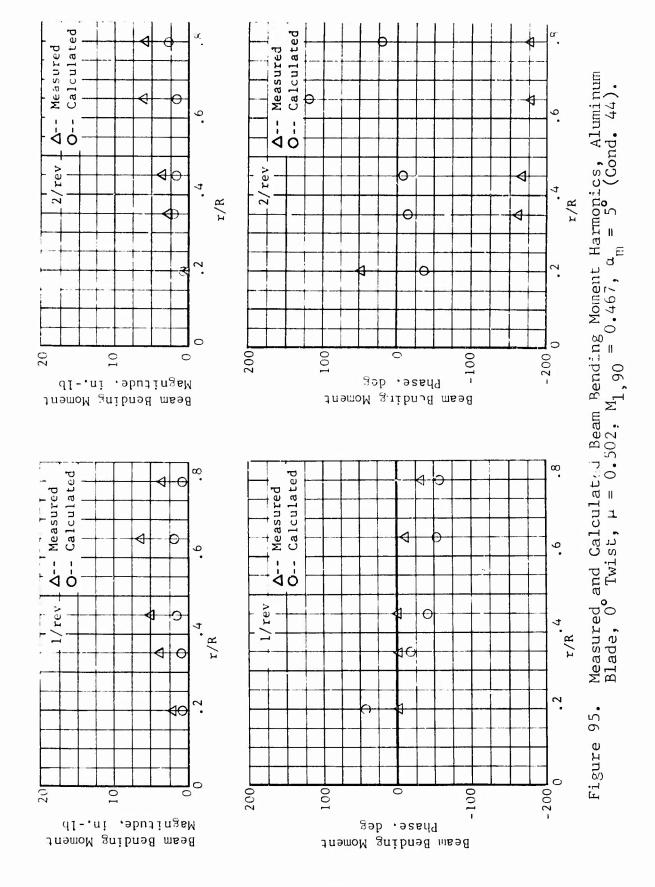








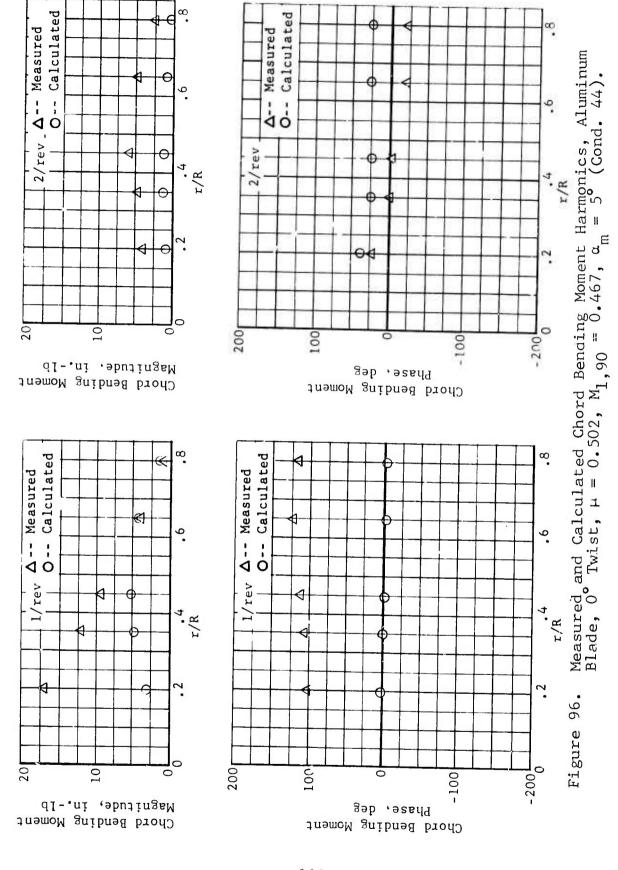


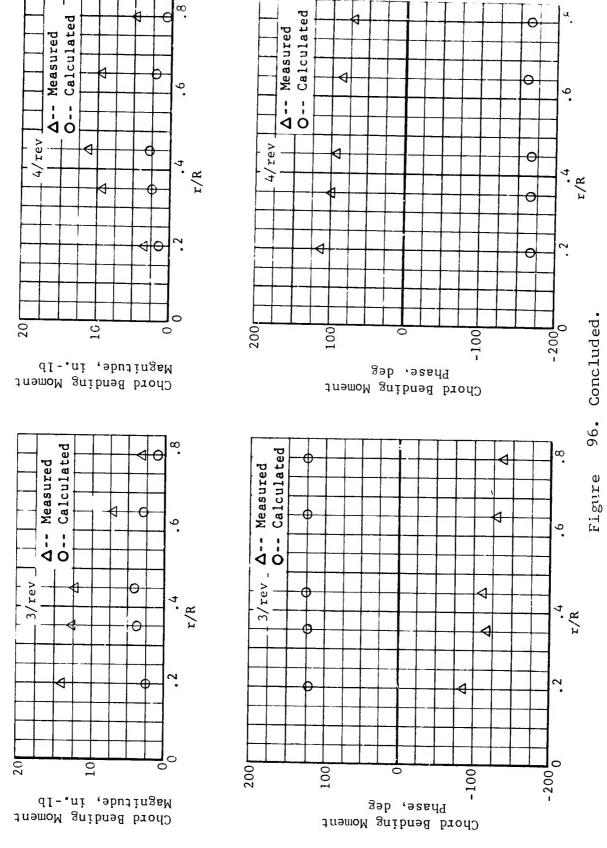


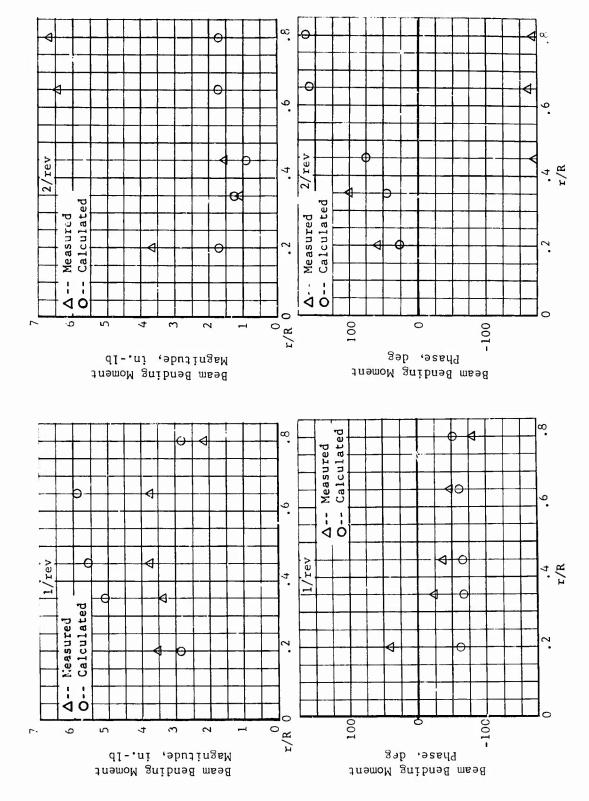
Concluded.

Figure

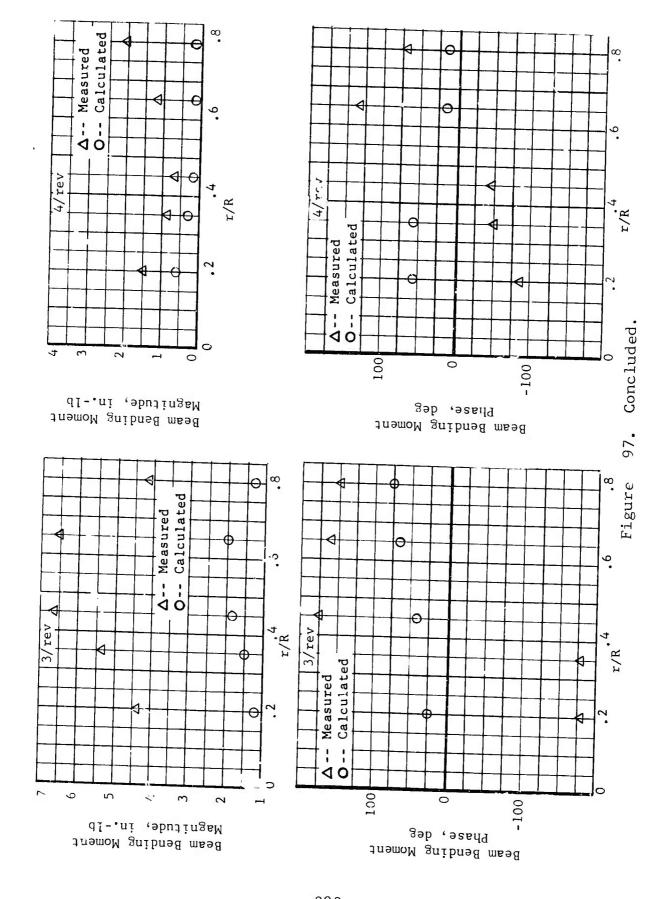
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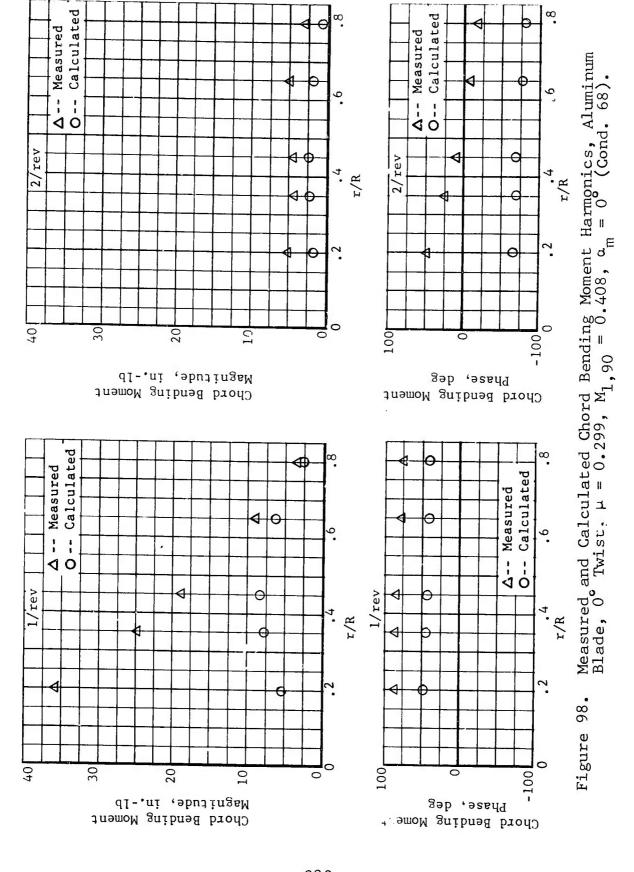






Measured and Calculated Beam Bending Moment Harmonics, Aluminum Blade, 0° Twist, u=0.299, $M_{1,90}=0.408$, $\alpha_{m}=0$ (Cond. 68). Figure 97.





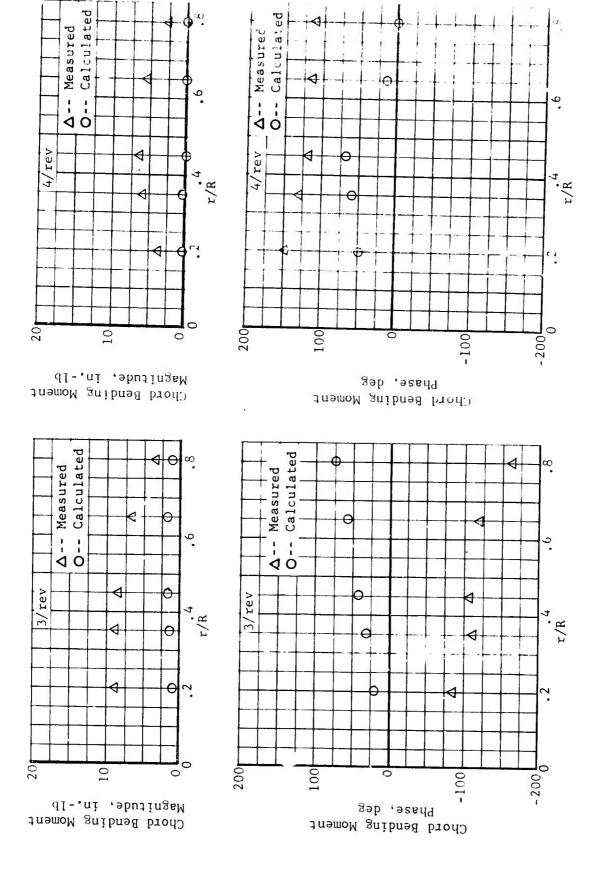


Figure 98. Concluded.

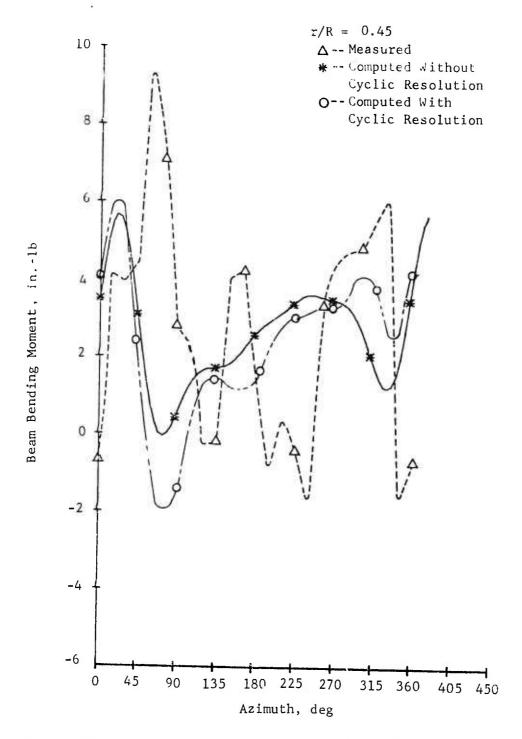


Figure ⁹⁹. Example of Effect of Cyclic Pitch Resolution Angle Change in Beam Bending Moment of Fiberglass Blade, 0° Twist, μ = 0.399, $M_{1,90}$ = 0.434, $\alpha_{\rm m}$ = 0.5° (Cond. 25).

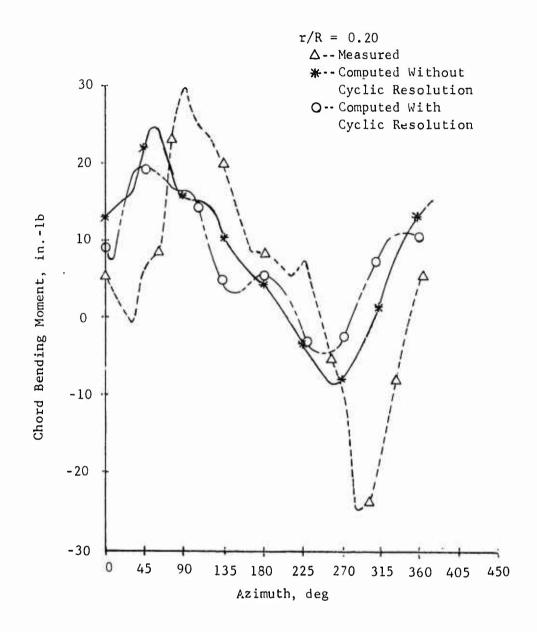
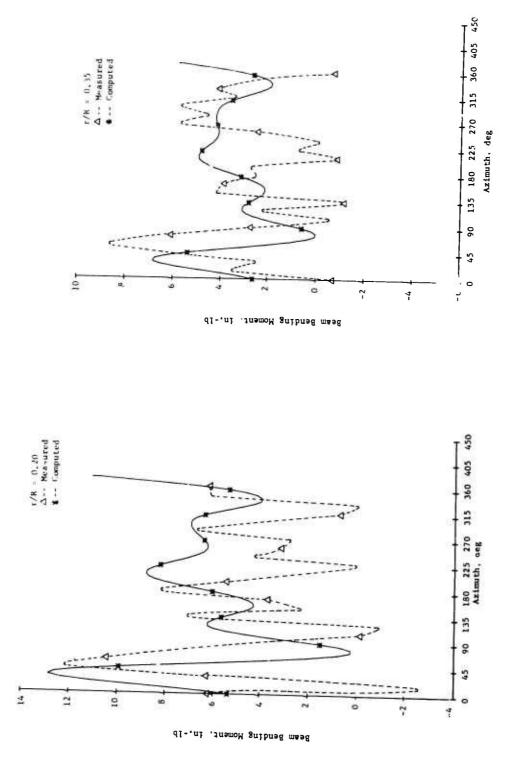
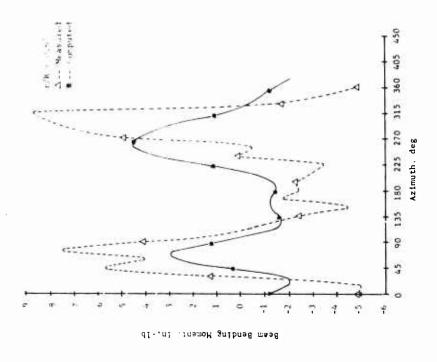


Figure 100. Example of Effect of Cyclic Pitch Resolution Angle Change on Chord Bending Moment of Fiberglass Blade, 0° Twist, μ = 0.399, $M_{1,90}$ = 0.434, α_{m} = 0.5° (Cond. 25).



Measured and Calculated Beam Bending Moment Time Histories, Fiberglass Blade, 0 Twist, μ = 0.399, $M_{1,90}$ = 0.434, $\alpha_{\rm m}$ = 0.5° (Cond. 25). Unsteady Aerodynamics Effects Activated. Figure 101.



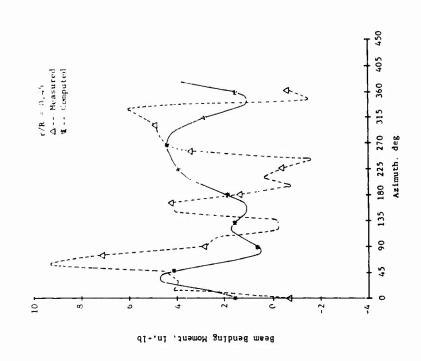


Figure 101. Continued.

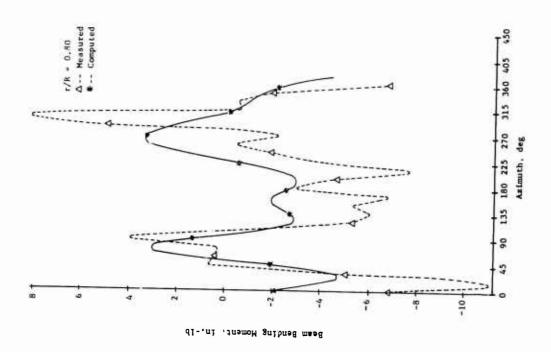
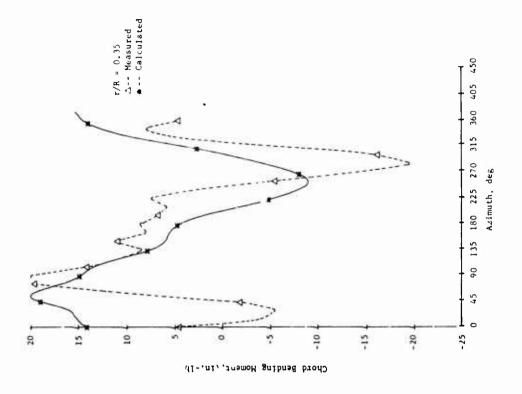


Figure 101. Concluded.



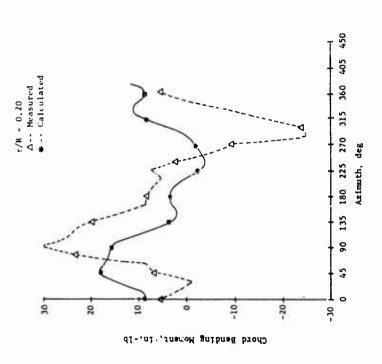
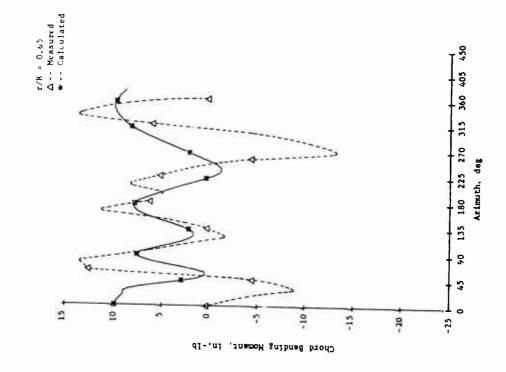


Figure 102. Measured and Calculated Chord Bending Moment Time Histories, Fiberglass Blade, $_{\rm U}^{\rm O}$ Twist, $_{\rm L}^{\rm H} = 0.399$, $_{\rm H}^{\rm H}_{\rm 190}^{\rm O} = 0.434$, $_{\rm M}^{\rm H}_{\rm 190}^{\rm O} = 0.5^{\rm O}$ (Cond. 25) Unsteady Aerodynamics Effects Activated.



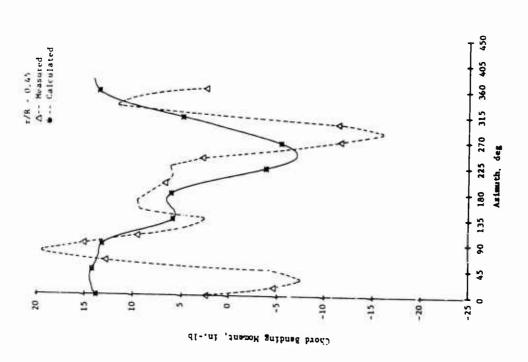


Figure 102. Continued.

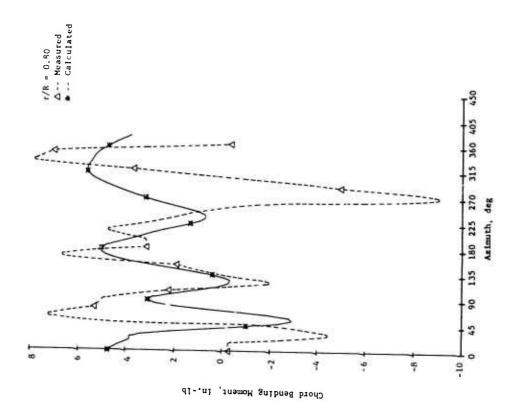


Figure 102. Concluded.

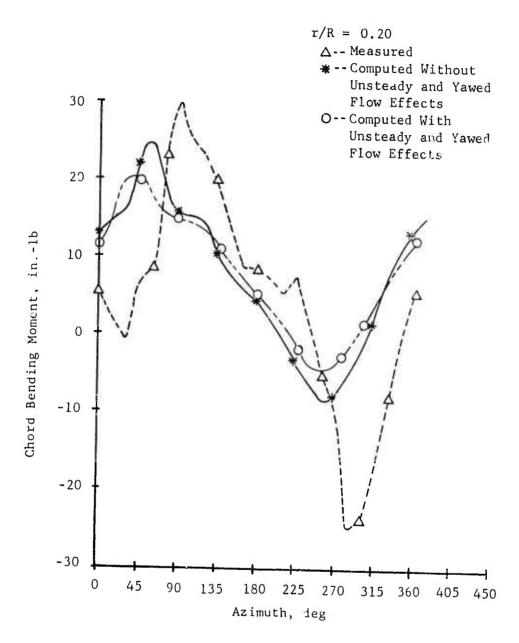


Figure 103. Example of Effect of Unsteady Aerodynamics and Yawed Flow Effects on Chord Bending Moment Fiberglass Blade, 0° Twist, μ = 0.399, $M_{1,90} = 0.434$, $\alpha_{m} = 0.5^{\circ}$ (Cond. 25).

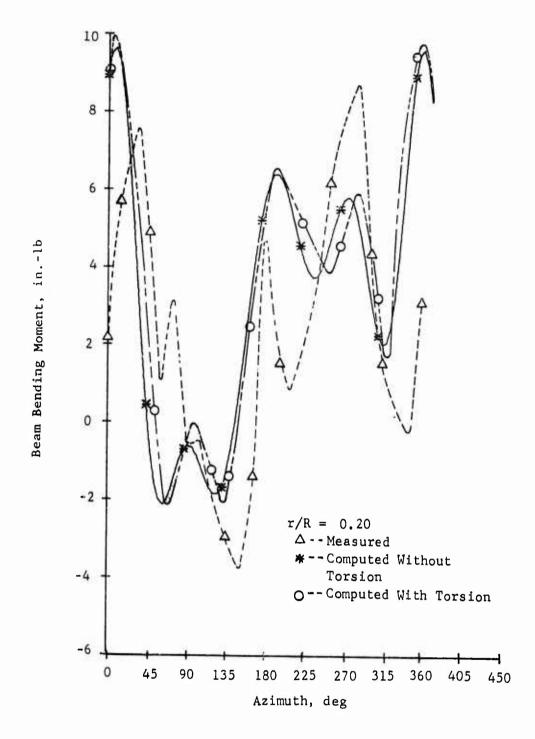


Figure 104. Example of Effect of Addition of Torsional Mode Shape Fiberglass Blade, -8° Twist, μ = 0.502, $M_{1,90}$ = 0.467, $\alpha_{\rm m}$ = 0.5° (Cond. 25).

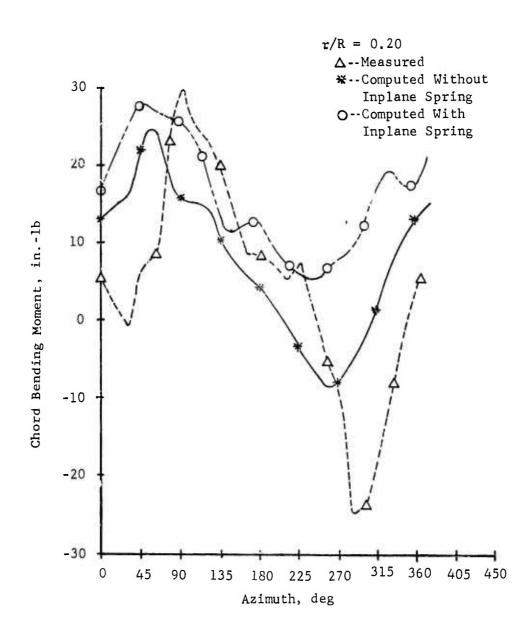


Figure 105. Example of Effect of Inplane Spring Fiberglass Blade, 0° Twist, μ = 0.399, $M_{1,90}$ = 0.434, $\alpha_{\rm m}$ = 0.5° (Cond. 25).

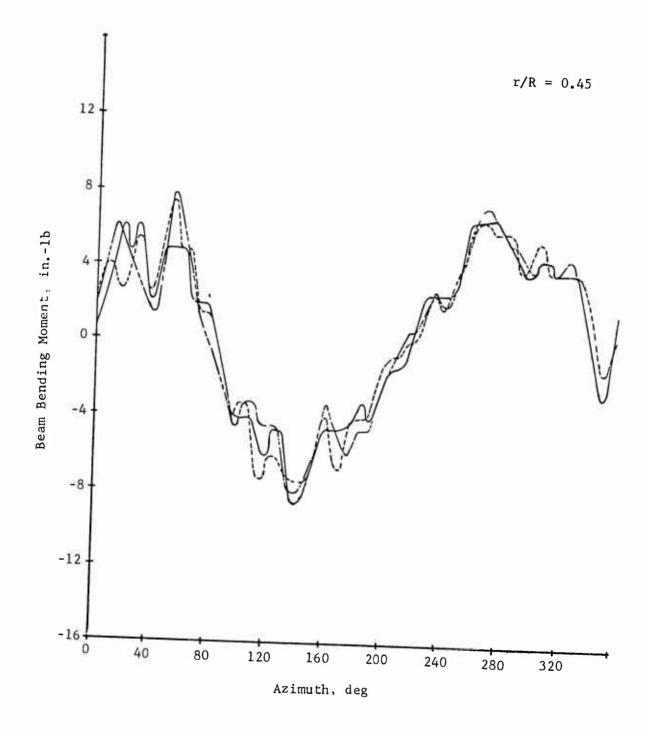


Figure 106. Three Successive Revolutions of Beam Bending Moment Time History, Fiberglass Blade, -8° Twist, $\mu = 0.399$, $M_{1,90} = 0.43$ /, $\alpha_{\rm m} = 0.5$ ° (Cond. 25).

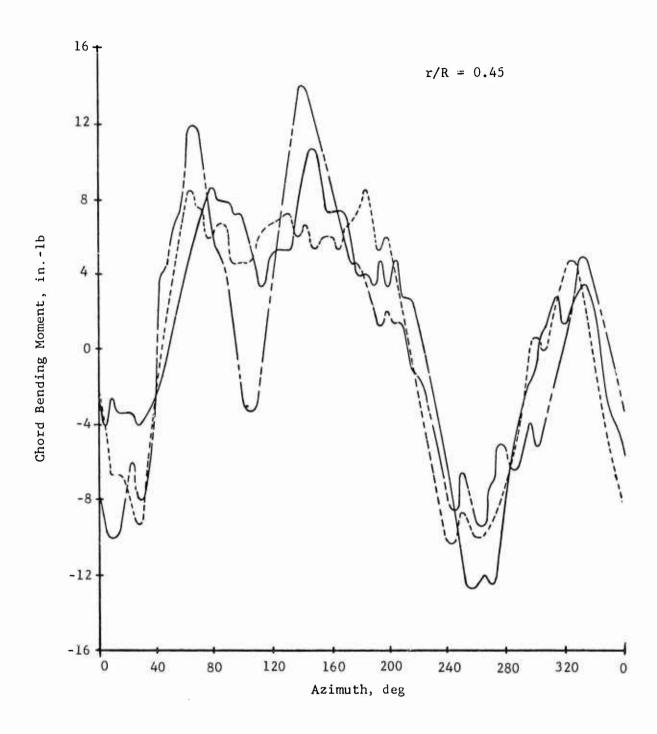


Figure 107. Three Successive Revolutions of Chord Bending Moment Time History, Fiberglass Blade, -8 Twist, μ = 0.399, $M_{1,90}$ = 0.434, $\alpha_{\rm m}$ = 0.5 (Cond. 25).

TABLE 1. H-34 FIBERGLASS MODEL ROTOR BLADE STIFFNESS PROPERTIES

Δr	$\mathtt{r}_{\mathtt{in}}$	$\mathtt{I}_{\mathbf{x}}$	Iy	J,
(in.)	(in.)	(in.4)	(in.4)	(in. ⁴)
.23	3.00	.466	2.68	2.37
.52	3.23	. 578	3.54	
.28	3.75	1.870	5.32	
.30	4.03	. 268	.268	
.45	4.33	1.600	1.600	2.37
.62	4.78	1.030	1.030	1.36
.63	5.40	.814	.814	1.36
.22	6.03	1.120	1,129	1.99
, 28	6.25	.330	.359	.52
• 54	6.53	.336	.332	. 50
. 56	7.07	.1907	.1497	. 36
.65	7.63	.0711	.0712	.0440
.125	8.28	.003148	.02190	.0070
.495	8.405	.00916	.01730	.00427
3.630	8.900	.001236	.01240	.00370
. 270	12.53	.001236	.01240	.00343
41.035	12.80	.001060	.01152	.00319
.320	53.835	.00057	.00625	.00174
.845	54.155	.00057	.00625	.00174

NOTE: The following values of E and G should be used to obtain bending and twisting stiffnesses for the fiberglass blades:

$$E = 2.50 \times 10^6 \text{ lb/in.}^2$$

 $G = 1.01 \times 10^6 \text{ lb/in.}^2$

TABLE 2. H-34 ALUMINUM MODEL ROTOR BLADE STIFFNESS PROPERTIES

Δr	rin	$^{\mathrm{I}}\mathrm{x}$	I _y	J
(in.)	(in.)	(in.4)	(in.4)	(in.4)
.23	3.00	.117	.670	.600
.52	3.23	.145	.885	
. 28	3.75	.468	1.330	
. 30	4.03	.0670	.0670	
.45	4.33	.400	.400	.600
.62	4.78	. 258	. 258	. 344
.63	5.40	. 204	. 204	. 344
.22	6.03	. 280	. 280	.503
. 28	6.25	.0825	.0898	.132
. 54	6.53	.0840	.0830	.127
.56	7.07	.0477	.0374	.0911
.65	7.63	.05456	.0574	.0367
.125	8.28	.002415	.0177	.00583
.495	8.405	.001504	.0140	.00356
3.630	8.90	.000948	.0100	.00308
.270	12.53	.000948	.0100	.00286
41.035	12.80	.000813	.00929	.00266
.320	53.835	.000437	.005041	.00145
.845	54.155	.000437	.005041	.00145

The following values of E and G should be used to obtain bending and twisting stiffnesses for the aluminum blade: NOTE:

 $E = 10.0 \times 10^6 \text{ lb/in.}^2$ $G = 4.00 \times 10^6 \text{ lb/in.}^2$

The values of I_x , I_y , and J between r = 8.28 in. and r = 53.835 in. have been corrected to reflect the stiffness test results for the aluminum blade.

TABLE 3. H-34 MODEL ROTOR BLADE LERTIA AND CENTER OF GRAVITY DATA

Δr (in.)	rin (in.)	w (lb/in.)	$(10^{-3} l_{\text{b-sec}}^{\text{pl}_{x}})$	$(10^{-3}lb-sec^2)$	Ycg (in.)
.23 .52 .28 .20 .10 .17 .14 .14 .62 .17 .07 .27 .12 .22 .23 .54 .56 .65 .125 .495 3.630 .270 40.135 .72 .18 .32 .845	3.00 3.23 3.75 4.03 4.23 4.33 4.50 4.64 4.78 5.40 5.57 5.81 6.03 6.25 6.53 7.07 7.63 8.28 8.405 8.90 12.53 12.80 52.935 53.655 53.835 54.155	.147 .147 .475 .149 .162 .180 .273 .343 .343 .295 .112 .169 .169 .048 .0822 .0588 .0414 .0176 .0081 .0094 .0106 .0121 .0202 .0178 .0276 .0044	.0036 .0036 .0801 .0801 .0801 .0928 .0892 .0645 .0177 .0193 .0111 .0042 .00037 .00025 .00013 .00014 .00018 .00034 .00034 .00034 .00034 .00039	.177 .177 .254 .254 .254 .266 .0892 .0892 .0645 .0177 .0199 .00955 .00504 .00314 .00268 .0086 .0089 .0114 .0221 .0221 .0221	.33 .30 .30 .27 .18 .14 .14 0.0

NOTES: 1. Mass moments of inertia are with respect to the local chord line and an axis normal to it at the feathering axis.

2. Mass moments of inertia include parts at the root that flap, lag, and pitch with the blade. Parts that flap and lag but do not pitch are excluded.

that flap and lag but do not pitch are excluded.

3. The flapwise position of the blade center of gravity is on the chord line for all blade stations.

TABLE 4. H-34 MODEL ROTOR BLADE MISCELLANEOUS DATA

Item	Parameter or Description	Value	Units
1	Radius	55.0	in
2	Blade Airfoil Chord Outboard of 8.9" Radial Station Blade Shank Chord Inboard of 8.9" Radial Station	2.69 l 1.19	in.
3	Blade Linear Twist From Center of Rotation to Tip Blade Sets a, c, d Blade Set b	0.0	deg deg
5	Blade Shear Center Locations Beamwise With Respect to Feathering Axis Chordwise With Respect to Feathering Axis	0.0	in.
6	Location of Blade Hinges Radial Station of Coincident Flapping and Lead-Lag Hinge Feathering Bearing Outboard End Radia Station Feathering Bearing Inboard End Radia Stations (The feathering, flapping and lag bearing axes intersect at the same poin.)	3.0 al 5.60	in. in. in.
7	Location of Lead-Lag Damper Rotary Damper on Blade Lead-Lag Hinge	e	
8	Pitch Flap Coupling Ratio	0.0	
9	Damping Coefficient of Lead-Lag Damper (Expressed as a damping moment about the hinge)	17.0	in lb- sec
10	Tabs or Flaps Blade Set c Deflection Over the Aft 20% the Airfoil Chord	of 5.0	deg

TABLE 4. H-34 MODEL ROTOR BLADE MISCELLANEOUS DATA (Cont.'d.)

Item	Parameter or Description	Value	Units
11	Pitch Control Geometry At 0° Collective and Cyclic Input: Distance Aft Along Flapping Hinge Axis	S	
	to Pushrod Upper End Radius on Swashplate of Pushrod Lower	1.43	in.
	End Distance of Plane of Swashplate Below	1.95	in.
	Plane of Flapping Hinges Angle on Swashplate Between Pushrod Lower End and Plane of Shaft and Lead-	6.31	in.
	Lag Axis	40.5	deg
	Pitch Control Spring Rate	21,000	in 1b/ rad
	Airfoil Section - NACA 0012		Lau

TABLE 5. H-34 FIBERGLASS MODEL ROTOR BLADE EQUAL SEGMENT STIFFNESS PROPERTIES

Station No.	(10 ⁶ 1b-in. ²)	(10 ⁶ 1b-in. ²)	GJ (10 ⁴ lb-in. ²)
1	1.7	2.59	194.4
2	1.7	2.59	194.4
3	.460	• 438	15.6
4	.00345	.0337	.396
5	.00292	.0302	.351
6	.00265	.0288	
7			• 322
8	1		
9			
10			
11			
12			
13			
11.			
15			
16			
17	q		ŀ
18	41		
19	.00265	0000	
20	.00283	.0288	• 322
20	•00194	.0212	. 238

TABLE 6. H-34 ALUMINUM MODEL ROTOR BLADE EQUAL SEGMENT STIFFNESS PROPERTIES

Station No.	EI _x (10 ⁶ lb-in. ²)	(10 ⁶ 1b-in. ²)	GJ (10 ⁴ 1b-in. ²)
1	1.70	2.59	196.3
2	1.70	2.59	196.3
3	.757	. 709	35.0
4	.0106	.109	1.30
5	.00896	.0975	1.67
6	.00813	.0930	1.07
7			1
8			
9			
10			
11			
12			
13			
14			
15			
16			
17			
18			
19	.00813	.0930	1.07
20	.00595	.0685	.793

TABLE 7. H-34 MODEL ROTOR BLADE EQUAL SEGMENT INERTIA AND CENTER OF GRAVITY DATA

Station No.	w (lb/in)	$(10^{-3} \frac{\text{pI}_{x}}{\text{1b-sec}^2})$	(10 ⁻³ 1b-sec ²)	Ycg (in.)
1	.261	.0904	. 209	0.0
2	.261	.0904	. 209	-0.178
3	.0905	.0311	.0311	0.0
4	.00989	.000207	.00725	1
5	.0105	.000148	.00960	
6	.0121	.000180	.0114	
7		1		
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10			•	
11				
12				!
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14				
15				Ì
16				
17				
18				
19	.0121	.000180	.0114	
20	.0140	.000223	.0144	0.0

TABLE 8. H-34 MODEL ROTOR BLADE MODE TYPES, FREQUENCIES, AND INERTIAS

Fiberglass Blade, 0° Twist

Mode No.	Mode N Type	atural Frequency ^w n (per rev)	Generalized Inertia (1b-ft ²)
1 2 3 4 5 6	B C B C B	1.045 0.305 2.588 3.171 4.381 7.538	0.00660 0.00664 0.00455 0.00554 0.00546 0.00614
	Fiberg	lass Blade, -8° T	Wist
1 2 3 4 5 6	B C B C B	1.045 0.305 2.594 3.164 4.387 7.556	0.00660 0.00664 0.00437 0.00535 0.00536 0.00589
	Alumi	num Blade, 0° Twi	st
1 2 3 4 5 6	B C B C B B	1.045 0.305 2.769 4.497 5.282 9.000	0.00661 0.00668 0.00495 0.00561 0.00593 0.00606
	Beamwise Mode Chordwise Mode		Speed = 730 RPM ive Pitch = 12°

TABLE 9. CORRELATION CRITERIA

A. Mean Load and Rotor Performance

Excellent	0/5
Good	5/10
Fair	10/15
Poor	15/

B. Overall Amplitude or Phase

Excellent	0/10
Good	10/20
Fair	20/30
Poor	30/

C. Harmonic Amplitude

Scale/Harmonic	1	2	3	4	5
Excellent	0/10	0/20	0/30	0/35	0/40
Good	10/20	20/40	30/60	35/70	40/80
Fair	20/30	40/60	60/90	70/105	80/120
Poor	30/	60/	90/	195/	120/

D. <u>Harmonic Phase</u>

Scale/Harmonic	1,2	3,4,5
Excellent	0/10	0/20
Good	10/20	20/40
Fair	20/30	40/60
Poor	30/	60/

Note: 10/15 implies $10 < q \le 15$, etc.

PRESENTATION AND GRADING OF POST TEST PERFORMANCE PARAMETERS TABLE 10.

Fiberglass Blade, -8° Twist, $\mu = 0.299$, $M_{1,90} = 0.408$

 $c_{L/\sigma_{meas}} = -0.00778 + 1.40 c_{L/\sigma_{comp}}$

 $C_{\rm P}/\sigma_{\rm meas} = 0.000771 + 0.755 C_{\rm P}/\sigma_{\rm comp}$

r = 0.977 $q_a = 39.7\%$ (poor) $q_b = 12.8\%$ (fair) $q_r = 3.4\%$ (excellent)

 $q_{\rm b}^{\perp} = 29.5\%$ (poor $q_{\rm r} = 2.5\%$ (excellent) r = 0.975 $q_a = 24.5\%$ (poor)

2.

Fiberglass Blade, -8° Twist, $\mu = 0.400$, $M_{1,90} = 0.435$

Lift

 $C_{\rm P}/\sigma_{\rm meas} = 0.000725 + 0.902 C_{\rm P}/\sigma_{\rm comp}$ $c_{L/\sigma_{meas}} = -0.00613 + 1.33 c_{L/\sigma_{comp}}$ r = 0.975 $q_a = 32.5\% \text{ (poor)}$ $q_b = 12.3\% \text{ (fair)}$ $q_r = 2.5\% \text{ (excellent)}$

r = 0.997 $q_a = 9.8\% (good)$ $q_b = 17.5\% (poor)$ $q_r = 0.3\% (excellent)$

Fiberglass Blade, -8° Twist, μ = 0.592, $M_{1,90}$ = 0.467 3

No curve fit was made because too few points were available for a statistical

TABLE 10. Continued

4. Fiberglass Blade, 0° Twist, μ = 0.299, $M_{1,90}$ = 0.408

Lift

 $C_{\rm P}/\sigma_{\rm meas} = 0.000876 + 0.685 \, C_{\rm P}/\sigma_{\rm comp}$ r = 0.945 $q_a = 31.5\%$ (poor) $q_b = 31.6\% \text{ (poor)}$ $q_r = 5.5\% \text{ (good)}$ $c_{\rm L}/\sigma_{\rm meas} = 0.0062 + 1.19 \, c_{\rm L}/\sigma_{\rm comp}$ r = 0.975 $q_a = 18.5\% (poor)$ $q_b = 11.3\% (fair)$ $q_r = 2.5\% (excellent)$

Fiberglass Blade, 0° Twist, with 5° Trailing Edge Flap, μ = 0.299, $M_{1,90}$ = 0.408 5

ift

 $c_{\rm P}/\sigma_{\rm meas} = 0.0000510 + 1.45 \, c_{\rm P}/\sigma_{\rm comp}$ r = 0.916 $q_a = 44.8\% \text{ (poor)}$ $q_b = 2.20\% \text{ (excellent)}$ $q_r = 8.4\% \text{ (good)}$ $C_L/\sigma_{meas} = 0.00291 + 1.264 C_L/\sigma_{comp}$ r = 0.992 $q_a = 26.4\% (poor)$ $q_b = 5.68\% (good)$ $q_r = 0.8\% (excellent)$

TABLE 11. H-34 MODEL ROTOR MEASURED AND CALCULATED LIFT AND POWER (CONDITIONS 25, 44, AND 68)

89	0.299	0.407	0.0	$c_{ m P}/\sigma$.00848	,00634	.00767	.00543	. 10565	.00562	.0103	67900.
9	0.	0.	•0	$_{\rm C_L/\sigma}$,0915	8060.	.0929	6160.	.0943	.0948	6760.	.0937
77	0.502	0.467	5.0	${ m C_{ m P}/\sigma}$.00746	.00748	.00592	.00515	.00590	66900.	.00805	.00758
7	0	0	5.	$^{\mathrm{C}\Gamma/\sigma}$.0518	.0488	.0507	6870.	.0522	.0496	.0504	.0487
25	0.399	0.434	0.5	$C_{\mathbf{P}}/\sigma$	62400.	90800.	.00692	.00509	09900	.00599	.00791	.00807
				${ m c}^{\Gamma/\sigma}$.0789	.0757	7620.	.0793	.0824	.0825	.0752	.0754
					Σ	O	Σ	O	Σ	O	Σ	O
Condition No.	ı	M, 90	E v		Fiberglass	blade O Twist	Fiberglass	blade -8 Twist	Fiberglass	$\begin{array}{ll} \text{Diage} \\ 0^{\circ} & \text{Twist} \\ \delta_{\text{F}} &= 5^{\circ} \end{array}$	Aluminum	blade O° Twist

M = Measured C = Calculated

MEASURED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, 0 TWIST $\mu=0.399$, M1,90 = 0.434, $\alpha_{\rm m}=0.5^{\rm o}$ (COND. 25). TABLE 12.

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	9	-1.22	•	•	• 2	4.	9.0	0.0	0	0.5	1.2		٥				?	• 2	33	0.3	•2	0.6	~
•	IJ	0.24	9	•	•		•	•		•	•	_	Ŋ	•	• 2	8	S	.3	5	3	4.	94.0	. 1
	4	-0-33) .	0.0	0.0	1.0	.2	J. 8	0.0	1.1	0.0	MOMENT(IN-LBF	4	2.	5	5.3	0.3	5.8	9.0	9.	1.2	-2.2C	4.
		-1.10	7 . 7	0.0	3.5	0.7	2.5	0.7	2.3	1.0	2.4	CHORD MUM	3	3.9	1.0	7.2	1.6	7.7	0.0	6.	2.6	-4.75	ထ
	2	-0.92	λ. α	4.0	4 · i	0.1	1.2	0.0	0.8	1.6	-	ED	2		8	9.	• 6	0	7	1.	• 4		۲.
	7	-1.08	3	2		0	9.	.3		0	4.		-	5	4.	3.2	1.6	6.7	3.1	9.5	4.8	16.59	7.6
	2	0.0	•	.	•	•	•	•	•	0	•		つ		•	•	•	•	•	0.0	•	0.0	4.44
	STA/HARM	SIS SOS	COS	-	\Box		\circ	+	\Box		\Box		STA/HARM	BOX SIN	500	NIS \$59	COS	45% SIN	COS	35% SIN	COS	20.8 SIN	ن

TABLE 13. CALCULATED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS RLADE, 0° TWIST $\mu = 0.399$, M₁,90 = 0.434, $\alpha_{\rm m} = 0.5$ ° (GOND. 25).

COMPUTED REAM MCMFNT (IN-LBF)

7	000	0.02 0.01 0.02	000		٠ ·	40	-0.14	000	C
9	0.0	-0.03 -0.03 -0.03	2000		6 5	5.60	$C \circ C$. 2	0.0
ĸ	• • • • • • • • • • • • • • • • • • •	0.01	1004		ທູ	9.	0.29	010	0.3
7	C. 11.	-0.15 -0.04 -0.04	1000	MJWFNT(IN-LBF	4 0.8	30	1.82	44	2.0
К	. 4	0.41 0.97 0.40	1300		3	1.4	-2.68 -2.15 -3.79	2.3	2.1 1.9
۴,	. 6 %	-1.32 0.75 0.56	140	COMPUTED	2 1.2	3.21.8	7.43 -7.98	. 2	2.5
- 4	C	0.40 0.00 0.00 0.00 0.00	- H 0 4		F4 <u>U</u>	. 7.	1.46 3.73 4.74	7	C 4
r		ייר לינ מיי מיי				د د. د د	4.67 c.c	78.8	6.75
AdvH/VIS	NIS 259	452 CTN	1 2		MIS ZEE	# U	N15 737	낁	115 ETZ

TABLE 14. MEASURED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, 0° TWIST $\mu = 0.502$, $M_{1,90} = 0.467$, $\alpha_{m} = 5.0^{\circ}$ (COND. 44).

				MEASURED	BEAM MOME	MOMENT (IN-LBF)			
STA/HARM	AARM	0	Ħ	2	ю	4	'n	9	7
80%	ZIS	0.0	-0.92	-0.82	-0.20	-0.92	0.17	77.0-	C.21
653	SIS	0.0	-0.06	-3.53	0.50	-0.62	0.03	-0.04	-2.32
	COS	2.45	3,19	-3.12	-4.53	-0.83	0.22	0.03	-C.43
453	SIN	0.0	1.09	-0.89	1.84	-0.31	-0.22	0.45	-0.55
	COS	3.48	1.61	-1.49	-2.94	-0.73	-0.04	-0.50	1.75
35%	SIN	0.0	0.72	-0.89	2.33	-0.15	-0.68	-0.20	-C.CB
	COS	3.55	1.10	-1.16	-2.89	-0.35	-0.35	-0-12	0.71
20%	SIN	0.0	0.14	0.46	30.8	J).0-	-1.01	-0.61	C.28
	COS	3.98	0.53	-0.12	-3.01	0.45	-0.96	1.38	-2.72

STA/HARM	1AR M	0	7	7	m	4	'n	9	7
80%	SIN	0.0 1.48	6.62	-0.39 1.55	-4.37	-4.C8	0.45	0.49	0.87
65%	SIN	0.0	1.73	-0.69	-8-36	-7.49	0.77	-0.45	1.47
45%	SIN	0.0	4.13	-0.03	-7.41	-7.68	94.0	40.0	
358	SIN	3.12	-2.86 5.72	2.17	-0.17	-0.70	1.48	0.29	C.49 -C.37
20%	COS	3.19	-4.01 9.86	2.06	2.23	0.40	1.01	0.31	0.07 -2.04
	cos	4.77	-5.82	0.62	5.92	1.18	-0.03	-0.04	0.55

MEASURED CHGRD MOMENT(IN-LBF)

CALCULATED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, 0 TWIST $\mu = 0.502$, $M_{1,90} = 0.467$, $\alpha_{\rm m} = 5.0^{\circ}$ (GOND. 44). TABLE 15.

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	9	0.02	э	0.0	J J.	0.0	0	ن. ن.	0.0	0.0		9	• 2	٦.	• 2	⁻•	0	ů.	0.0	0.1	-0-18	0.2
•	'n	-0.17	0.0	0.0	1.0	0	.2	0	4.	0	_	Ŋ	0	5	-	. 7	7.	-	٠,	• 2	60°0	0
107_N1 1 1 N	4	-0.57	0.2	0.2	3	~	3	4	40	9.	MUMENT (IN-LBF	4	-	0.7	1.5	1.1	5.	2.0	.3	40	0.32	<u>.</u>
SEAR HORENININ LIN-LO	М	0.70	6.	0.	8	4.	.7	• 6	0.	Ò	CHORD MUM	ю	0.3	0.7	0.7	1.7	1.2	2.6	1.3	2.6	-1.13	2.2
01101100	2	0.71	5	.5	0.1	5	3	30	9.	5	COMPUTED CHORD	C1	• 6	.3	• 5	5	0	5	Φ.	• 4	2.31	• 2
	٦	-0.74	• 6	• 5	• 1	3	7.	7.	3	• 2		-	• 6	0,3	. 7	• 4	8	3	.2	\$	3.41	.5
	0	0.0	0	•	•	•	•		•	•		0	•	•	0	•	0	•	3	•	3.0	•
	STA/HARM	80% SIN										STA/HARM	-	0	-	0	-	0	-	0	22% SIN	\circ

TABLE 16. MEASURED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, 0° TWIST $\mu = 0.299, \ M_{1,90} = 0.408, \ \alpha_{m} = 0 \text{ (COND. 68)}.$

(IN-LBF)
1)
MOMENT (
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				MEASUKED	DEAM RORE	ACARNI LINILOR			
ST	STA/HARM	O	-	2	8	4	5	9	7
Ö	BOS SIN		4	1.0	0.1	2.32	-		ω,
	ں	1	1.3	3.4	1.7	ŝ		•	. 7
65	94 S	7		1.2	0.0	1.	• 6	•	• 1
	ں	?	1.8	2.5	2.1	0	0	•	۲.
45	S)	?	•	0.0	0.1	. 7	.2	•	• 1
	COS	۳ •	1.4	.2	1.8	2	.2	•	5•
35	53 SIN	3.0	-0.61	0.34	-0.21	5.	6.21	0.08	-C.C2
	ن	<i>(</i> ,)	• 1	0	1.3	4.	0	•	0,3
2	NIS SIN		0	•	0	•	•	•	
	CCS		•	•	•		•	•	•
				MEASURED	CHORD MOM	MOMENT(IN-LBF	F)		
ST	STA/HARM	0	7	2	m	4	S	9	7
80	8	•	4		3.3	ထ	6	- 2	4.
i	ن	•	0	6	0.3	0.0	•2	0	8
65	S	C	3	• 6	6.0	. 2	3	0	•6
	COS	3.26	-1.31	3.31	62.0-	1.20	0.57	0.15	7
45	<i>∨</i>	•	8.9	0	6.4	α,	8	3	•
		•	3	.7	0.8	.2	• 5	0	S
35	9 6 1	0.0	0.9	• 6	6.	•	4.	0	î.a
		14.0	3.0	.7	2.	4.	.	0	•
77	94 S	0.0	0.9	6.	• 9	40	4.	0.3	1.C
		•	5.7	4.	ω.	0		•	0

TABLE 17. CALCULATED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, 0° TWIST $\mu = 0.299$, M1,90 = 0.408, $\alpha_{\rm m} = 0$ ° (COND. 68).

	J	COMPUTED BEAM		MOMENT(IN-LBF	_		
7		2	3	4	'n	9	7
-1.22		90.0	0.57	-0.C4	-0.08	-0.02	ر د د
1.02		-0.94	-0.12	0.11	0.05	-0.02	-G.Ol
-1.55		0.23	0.58	0.00	-0.05	-0.02	Û• ℃
1.12		-0.68	0.07	0.05	0.02	-0.02	10.01
-1.39		0.34	C.27	90.0	0.04	00.0	10.00
6.55		0.17	0.35	-0·01	-0.04	00.00	00·0-
-1.20		0.34	0.12	30.0	6.07	0.01	10.U-
0.25		0.47	0.42	-C.1C	-0·0e	0.01	Or
-1.51		0.47	6.04	0.14	0.13	0.03	-C.C1
J. 36		0.95	0.63	-0.17	-0.10	0.03	0.03

	7	-C.C	Co	50.0-	C.11	1.5	0.03	31.5	-0.02	15	10.0x
	9	0.03	0.10	0.05	0.13	0.05	0.01	0.34	90.0-	0.03	-0.13
(:	Ŋ	-0-04	0.15	-0.04	0.21	0.62	0.12	0.05	50.0	0.07	-C.05
MOMENT(IN-LBF	4	-0.12	0.38	-0-12	0.59	0.10	94.0	0.21	5.57	9-25	50.0
CHORD MOME	ĸ	-0.07	-0.79	-0.29	-1.47	-0.63	-1.66	-0.71	-1.47	-0.66	-1.00
сомритер сноко	2	-0.92	0.14	-1.59	0.51	-1.51	1.00	-1.19	1.09	-0.62	1.03
	7	- j. 6¢	-3.30	0.52	55	4.37	3.69	5.39	4.01	2+.0	4.17
	0	0.0	1.51	0.0	3.49	ن. ن	3.43	3.0	3.84	ე• c	4.60
	STA/HARM	AIS SEE				45% SIN				213 SIN	COS

MEASURED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, -8 TWIST $\mu = 0.399$, $M_{1,90} = 0.434$, $\alpha_{\rm m} = 0.5^{\circ}$ (COND, 25). TABLE 18.

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			MEASURED	STAT MUMI	MOMENI (IN-LB)	-		
STA/HARM	0	-	2	m	4	S	9	7
-	•	• 6	0	. 1	0.8	0	φ,	1.7
3	•	6.	4.	1.7	1.4	m	•2	0.0
N18 859	0.0	-3,33	2.23	1.16	-0.24	0.37	0.07	-6.13
00	•	6.	4.	1.8	1.1	S	0	0.1
-	•	8	2.2	• 6	0.1	0	.3	
5	•	6.	1.9	1.0	0.2	0	0.1	0.
-	•	.2	6.		0.0	n	0	
0	•	6.	1.3	6.	.2	~	0.0	
_	•	8	2.2		3	0	0.5	1.7
0	•	.	0.5	ထ	9	n	4.	• 2
			MEASURED	CHORD MOM	MOMENT (IN-LBF	(F)		
STA/HARM	0	7	7	e	4	ß	9	2
-	•	4.	6.	0	C.	0	6	J.
00	•	•	6.	1.8	1.3	5		•
I	0	3.0	• 2	2.0	2.C	3	3	•
00	•	8	1.6	3.7	2.0	.2	3.5	6.1
-	0	6.5	4	2.8	2.8	4.	0.0	0.0
0	•	6.	1.7	3.4	1.5	7.	0	C.1
	0	7.6	1.8	0	2.7	0	0.0	7
	•	1.	0	2.1	6.	8	0	0.2
20% SIN	0.0	12.14	-0.19	-3.87	-	0.62	-0.18	-C.24
0	•	6.1	9.	0		.2	2	9

CALCULATED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, -8 TWIST $\mu = 0.399$, $M_{1,90} = 0.434$, $\alpha_{\rm m} = 0.5^{\circ}$ (COND. 25). TABLE 19.

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1					0.0 -3.08					
2	1.29	-1.28	1.58	-0.67	1.21	0.82	0.95	1.32	1.33	2.38
3	1.31	0.64	1.23	0.74	0.40	0.51	0.05	0.37	-0.16	0.52
4	-0.70	-0.26	-0.38	-0.10	0.42	0.24	69.0	0.36	1.29	0.68
5	-0.29	-0.54	-0.16	-0-15	0.17	0.11	0.27	0.20	0.50	0.39
9	0.01	-0.01	00.0	-0.01	10.0-	00.0	-0.01	0.01	-0.02	0.01
-	-0.01	00.0	00.0-	00.0	00.0	00.0-	0.01	00.0-	0.01	-0.01

COMPUTED CHORD MOMENT(IN-LBF)

				CORPOIL	ביים היים היים היים היים היים היים היים		•		
STA/ HARM	HARM	0	-	2	æ	4	Ŋ	9	7
808	NIS	0.0	1.17	-1.40	96.0	-0,54	-0.33	0.12	0.02
	CUS	1.45	-0.83	-0.93	-1.66	0.45	0.18	-0.03	0.02
65%	SIN	0.0	2.91	-2.61	1.17	-0.91	94.0-	0.14	0.02
	cos	2.99	99.0-	-1.73	-3.17	0.56	0.25	-0.05	0.02
453	SIN	0.0	4.63	-2.84	0.11	06.0-	-0.21	-0.04	-0.02
	560	4.09	1.34	-2.15	-3.65	-0.05	0.04	-0.03	-0.01
35%	NIS	0.0	4.73	-2.41	-0.56	69.0-	-0.01	-0-13	-0.03
	COS	4.46	2.29	-1.92	-3.25	-0.38	-0.08	-0.02	-0.03
20%	SIN	0.0	4.10	-1.55	-1.07	-0.47	0.15	-0.21	-0.05
	cos	4.77	2.84	-1.55	-2.25	-0.72	-0.23	00.0-	-0.05

TABLE 20. MEASURED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, -8 TWIST $\mu = 0.502$, $M_{1,90} = 0.467$, $\alpha_{\rm m} = 5.0^{\circ}$ (COND. 44).

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٥	0.03	.31	ú•ù3	0.09	-0.23	-j.18	-0.18	-0.15	0.12	0.24
Ŋ	-6.61	-0·13	-0.30	-0.15	67.0-	-0.23	0.14	-0.14	0.15	-0.55
4	-1.37	-2.16	-1.05	-1.43	0.39	-0.24	0.51	0.33	1.27	1.18
m	2.61	-1.21	2.33	-1.39	1.05	-1.04	1.50	-1.35	1.66	-0.95
2	1.45	-2.86	2.64	-2.36	3.02	-1.80	2.41	-1.70	2.14	-0.81
r - 4	-2.67	3.14	-3.69	4.73	-5.34	4.02	-2.68	3.04	-2.21	1.04
0	0.0	-0.76	J.J	-0.35	0.0	J.44	0.0	J. 25	7.0	2.30
STA/HARM		CCS	SIN	. 500	N:IS	COS	SIN	COS		

MEASURED CHORD MOMENI(IN-LBF)

7	C.21 C.12	C . 45	C-27 - J-62	1 1 1 1 1 1 1 1 1 1 1	-0.54 0.11
9	-3.24	-0.43 -0.12	-0.09	0.08 0.41	0.20 0.30
ī	-0.08 0.62	-1.03	1.56	-t.16 0.95	0.43 -0.39
4	-2.1C -1.85	-4.65 -3.30	-5.16	14.56	-3.14 -1.52
£	-0.27 -1.80	-0.86	-2.35	-2.83	-4.56 -1.07
2	48 °C-	-1.68 0.77	-2.61 1.30	-1.61 0.92	-0.92 1.09
m	0.48	1.05	2.80	2.83 -2.05	4.74 -2.70
n).c	0.0 0.14)).51	J.58	3.37
STA/HARM	SIN COS		45% SIN		

CALCULATED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, -8 TWIST $\mu = 0.502$, $M_{1,90} = 0.467$, $\alpha_{\rm m} = 5.0^{\circ}$ (COND. 44). TABLE 21.

CUMPUTED BEAM MUMENT(IN-LBF)		
EAM MUMENT (IN-LB	í.	
EAM MUN		
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EAM MUN	_	
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STAZHARM	С	-	2	Υ	4	ſΛ	9	7
NIS RIN	G.	-3.01	1.53	5.67	-0.75	-0.21	47,000	ĩ
	-1.41	1.45	-0.63	0.82	-5.91	-0.22	0.01	
CCS	1.0-C	20 ° C	1.79	J. 78	-0.41	-0-11	-0.02	l
458 SIN	0.0	-2.03	1.24	0.04	0.00	-0-14	000	; ; ; ; ; ; ; ; ; ; ; ; ; ; ; ; ; ; ;
25.7 35.7 CTS)•32 	1.14	1.04	0.58	い。ひょう	Ú. 10	-0.07 -0.01)) ((
	ر ا ال ۳		ວ•ອດ ວິດ ວິດ	0.39	c.73	0.22	0.03	(· · ·)
212 477) · ·	0 0 0	1.35	0.40	ر. ۳ ۳	Ů.18	-3.62	1 .
		76.71	1.1	0.00	1.38	0.41	70.0	10.0
	•		7.36	2.61	1.67	C.3¢	50.p-	10.01
			COMPUTED CHCRD	HCAD NJWE	MJMENT (IN-LBF	<u></u>		
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,	0 0	00.00	C • 0 - 1	-0.ce	-3.16	21.0	1.4
-	15.47	-1.15	-1.25	37			ر د د
١.	;	1 (1	r) •)	0.43	0.04	0.0
•	00.0	-1.38	0.74	-1.42	-1.23		
2.34	-0.05	-2.24	75 6-	,		•))
-		1 (10.1	70.5	0000	し、これ	10.01
•	1.04	96.0-	-0.02	-1.21	-11-13		
-	44	-2 04			1	0	(· · ·
) (•	06.7	13.78	して・した	0.02	-0.03	1
•	1.14	-0.51	-C.46	[3] <u> </u>	7.7		1
Ü		1,5) (10.0	10.0	47.01	30.01
•	0 + • 1	-2.13	かつ・カー	-0.7	-).14	70.0-	·
	V3-1	70.0	מכרו				
00	1 (1)	•	0000	10.40	0.0	-0.53	53.1
0,40	7 · (C	-2.22	-2.36	17.71	-(32	000	
					10.0	VO • 0	ر.

TABLE 22. MEASURED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, -8° TWIST $\mu = 0.299$, M1,90 = 0.408, $\alpha_{\rm m} = 0$ ° (COND. 68).

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5	0.34 0.34 0.034 0.03 0.03 0.03 0.01 0.01 0.02
4	0.75 -0.89 -0.22 -0.77 -0.24 -0.61 -0.61
8	0.50 -2.03 -1.65 -0.32 -0.70 -0.39
2	0.09 -3.52 0.45 -2.98 1.28 -1.19 -0.71
H	-2.54 -3.21 -3.77 -2.57 -2.57 -1.78 -1.78 0.26 0.82
O	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0
STA/HARM	80% SIN COS 65% SIN COS 45% SIN COS 20% SIN COS COS COS

MEASURED CHORD MOMENT(IN-LBF)

	-	2	K	7	u	
•		ı	1	r	n	
2.19		-1.06	-2.49	-1.45	6.5	Ì
-0.65		1.29	-1.65	10.24	0 0	0
4.46		- 7 - 44	16.24			0
1 78		1 77	000	70.7	07.01	20.0-
		7 - 7	67.6	87.0	0.92	0.11
40.0		16.7-	-5.13	-3.2C	-0-16	0.31
-3.42		1.19	-2.10	1.68	0.97	XC. OI
16.42		-1.71	-4.78	-7-67	-102	0 -
-3.79		0.43	-6.41		70.0	0 7 0
17 42			4 6	1 7 0 1	- ·	10.01
00.1		T+ • 0	07.4-	71.1	Ó.06	-0.17
-6.43		-0.38	2.63	73.6	0.12	3.12

TABLE 23. CALCULATED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, -8° TWIST μ = 0.299, $M_{1,90}$ = 0.408, α_{m} = 0° (COND. 68).

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STA/HARM	٠,	त्व	2	m	1	3	Э	7
NIS SUP	ິດ . ເ	-2.69	0.70	C.91		-5-12	50.00) •)
CUS .	-2•42 J•J	1.39 -3.33	0.94	0.24	0.017	.0.10 -0.07	- 0.0 .0.0 .0.1	
COS	-1.49	1.62	-0.56	0.32	50.0	-0.06	00.0-	
ATS 記され CUS	1.27	1.04	0.83	0.21 0.29	0.0 • • • • • • • • •	0.07	10.01)) ((
35% SIN		-2.15	0.71	40.01	0.31	i. 11	-0.02	
COS	2.43	0.63	9.6 °C	0.25) (()	J. CB	J. J	
218 SIN	Ú• Ú	-2.97	1.05	-0.23	Ú•€	Ú•Žt	7	1) •)
COS	5.19	0.64	1.72	0.08	0.10	0.15	10.0-) • ()
			THE	HALLAIDINAMEN TABLET HERE	1 1 1 1 1 1	ū		
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STA/HAKM	Ö	7	2	÷٦	4	5	,O	7
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2	-1.24 -0.63 -2.31 -1.12 -2.53 -1.29 -2.23 -1.09
1	1000428446 2000043 2000043
Ö	0408080404 0000004 0000004 001106
STA/HAKM	824 SIN 623 SIN 608 608 608 608 354 SIN 608 225 SIN 608

MEASURED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, 0° TWIST, $\delta_F = 5^\circ$, $\mu = 0.399$, M₁,90 = 0.434, $\alpha_m = 0.5^\circ$ (COND. 25). TABLE 24.

LBF)
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MUMENT
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7	1.00 1.00 1.00 1.00 1.00 1.00 1.00 1.00	200 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 -
9	0.090 0.29 0.11 0.19 0.37 -0.37 -0.37 -0.06 0.69	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
Ŋ	-0.08 -0.61 -0.41 -0.11 -0.17 -0.02 -0.75	5 -0.01 -0.26 -0.31 -0.31 -0.05 -0.05 -0.05
4	B -0.41 1 -1.41 5 -0.62 4 -1.50 2 -0.34 3 -0.65 5 -0.26 9 0.91 MUMENT(IN-LBF	-1.95 -2.33 -2.90 -2.90 -2.04 -1.01 -1.01
શ	-1.21 -1.21 -1.74 -1.33 -1.33 -1.39 -1.39 CHORD MUM	w 0041-8m4008
2	0.688 -2.79 2.48 -3.02 2.47 -0.94 1.97 -0.56 2.30 -0.10	2 0.01 -1.05 -1.05 -1.35 -1.35 -0.63 0.73
1	-2.00 -2.67 -2.33 -1.74 -1.74 -1.28	1 0.23 -0.06 2.06 4.72 -4.72 -4.72 -4.74 -7.82
၁	0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.0	0 000000000000000000000000000000000000
STA/HARM	503 653 653 603 605 453 81N 203 203 203 81N 60S	814/HARM 824 SIN 654 SIN 655 SIN 605 424 SIN 605 224 SIN 605

CALCULATED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, 0° TWIST, $\delta_F = 5$ °, $\mu = 0.399$, $M_{1,90} = 0.434$, $\alpha = 0.5$ ° (COND. 25). TABLE 25.

	L
(1N-L3F)	•
BEAM MCMENT	ľ
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STA/HARM	.)	-	7	٣	4	rð.	9	7
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	•	(D • T	0.50	74.0	-0.65	-11.23	30	
	0.52	70.0	-0 - 84			1	0.0	1000
				71.0	10.01	11.0-	20.0	ر. ر•
	0	つん・1	0.22	C. 74	-0.20	-()	20 00	
	1 . Ó 8	0.0	67.6-	100) -	7 7 7	0000	Tゥ・フー
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	3.02	(C)	07.0	07 (0 1	70.0	(• (L
	,) '	1	0.0	C. NO.	20.0	10.01	
	• • •	ンつ・ つ	-0.35	C.74	0.83	36) ·
	3.40	6.11	01 (0		7	10.0	7) • ,
3		7 7 0 7	0.19	C . O	い。ケル	0.06	-0.02	1
VIC +77)• (0.45	-0.58	40.	1 44			•
700	5.76		0	1 1) • •	0 + • 0	30.0 0	
)		7 7 0	1.38	1.51	10 A	0.13	,,, C. I.	

COMPUTEL CHORD MUMENT(IN-LBF)

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STA/HARM	Ð	н	2	30	4	u i	Ó	7
85 SIN	.7	-1.33	(7.0-	()		1		
	1.63	08.30	0 0	A	17.1	-0.20	0.07	0,01
		1000 L	0 1	かつ・T I	ひ・ひ4	C. 58	0.12	() ()
) \	17.1	19.01	-3.61	-1.7è	-0.23	3.10	10.1
	((-)	L . J	0.43	-2.25	J. 6c	0.80	3.16	1 (2)
2000 2000) · (₽T•T	69.0	-1.23	-1.62	00.0	40.0	
	3.74	2.50	0.71	-3.03	6.61	Ú.29	0.02	
22.0) r	7.40	1.38	-1.37	-3.38	0.22	-0.01	, i
20 #CZ) · · ·	KO • 7	0.13	-2.94	4.0°€	-0.07	-0.07	1
_		* ` ` `	1.85	-1.25	Ü•3¢	0.35	50.0-	0)
7		† † • † †	99.0	-2.30	()·()	-0.42	-0.14	10.01

MEASURED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, 0° TWIST, $\delta_F=5^\circ$ $\mu=0.502$, M₁,90 = 0.467, $\alpha_m=5.0^\circ$ (COND. 44). TABLE 26.

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MEASIRED	֓֝֜֜֜֜֜֜֜֜֜֜֜֓֓֓֓֜֜֜֜֜֓֓֓֓֓֜֜֜֜֓֓֓֓֜֜֜֜֓֓֓֜֜֜֜
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6 7	-0.28 -0.25 -0.06 -0.75	.01	.14	.01	90.	.14	.22	.22	-07		6 7	-0.14 0.26	.30 -0.	.14 0.	.32 -0.	.04 0.	.14 -0.	0- 90	.40 0.	00 00	62
'n	-0.27	-0.40	0.07	-0.15	0.15	0.25	-0.31	0.31	76-0-	()	ľ	4	S	5	_	5	2	-0.39	Œ	9	ď
4	-0.71	9.	• 1	Ç	6	4.		6.	.2	ENT (IN-LBF)	4	-2.02	-2.65	-3.76	-4.05	-4.34	-3.97	-3.68	-2.80	-2.70	-1 44
m	1.22	1.61	77.0-	1.38	-1.04	1.32	-1.24	1.90	-1-44	CHORD MOMENT	W	.3		6	• 2	6	(4)	-1.80	• 6	4.	C
2	1.35	0	• 5	.2	5	4.	5	6	0	MEASURED	2	•	•		•	•	•	-0.68	•	•	
-	-1.82 2.98		•	•			•				1							1.12			
0	0.0	•		•	•		•	•	•		0	•	•	•	•	•	•	0.0	•	•	
STA/HARM	BOX SIN	65% SIN	COS	45% SIN	COS	35% SIN	ر،	20% SIN	COS		STA/HARM	BOX SIN	COS	65% SIN	300	45% SIN		35% SIN	COS	20% SIN	1

Σ	0	-	2	Ŋ	4	ľ	•	
Z	0.0	-0.56	0.37	0.39	-2.02	-0.41	-0.14	
SO	0.14	60.0	-0.55	-1-13	-2.65	0.52	0.30	
Z	0.0	0.52	-0.43	-0.37	-3.76	-0.58	-0.14	
ŝo	0.05	-2.26	0.21	-2.28	-4.05	1.11	-0.32	
Z	0.0	1.01	-1.00	-1.32	-4.34	-0.52	-0.04	
Sü	0.35	-3.20	0.42	-2.33	-3.97	1.21	0.14	
ZI	0.0	1.12	-0.68	-1.80	-3.68	-0.39	90.0	
CS	1.41	-3.05	0.34	-1.63	-2.80	0.84	0.40	
Z	0.0	2.21	66.0-	-3.41	-2.70	-0.62	00.00	
0.5	0.20	-4.36	-0.11	00.0-	-1.66	0.55	0.63	
	### TA/HARM			0 1 0.0 -0.56 0.14 0.09 0.0 0.52 0.05 -2.26 0.0 1.01 0.35 -3.20 0.0 1.12 1.41 -3.05 0.20 4.36	0.0 0.56 0.37 0.14 0.09 0.55 0.0 0.52 0.43 0.05 -2.26 0.21 0.0 1.01 -1.00 0.35 -3.20 0.42 0.0 1.12 0.68 1.41 -3.05 0.34 0.20 4.36 -0.11	0.0	0.0	0.0

CALCULATED BEAM AND CHORD BENDING MOMENTS, TARIF 27

H H H H H H H H COLOR NO.		FIRENGLAIED FIRENGLASS	BLADE BLADE BLADE 1,90 1,90 1,22 1,22 1,48 1,22 1,48 1,23 1,49 1,58 1,38 1,38 1,36 1,49 1,58 1,58 1,58 1,58 1,58 1,58 1,58 1,58	3E AM C. O.		(COND.		7 000000000000000000000000000000000000
N CO	• •	-I.27 1.09	9 4	2.2	8	0.80		0.03
SI	• •	0.30	• 6	1.1	57	0.58		0.06
SI SI		1.09	9 4 9	22.0	ν 80	0.23		-0.03 0.08 0.02
254 SIN COS COS COS SIN COS	0.00 0.00 0.00 0.00	2 2 4 3 8 8 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9	0.71 1.38 0.73 1.85	-3.03 -3.03 -1.37 -2.94	0000	00.00	0.02 -0.01 -0.07	0.03
၂ ၂	•	2.44	•	6	0	-0.45		-0-04

TABLE 28. MEASURED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, 0° TWIST, $\delta_F=5$ ° $\mu=0.299$, M1,90 = 0.408, $\alpha_m=0$ ° (COND. 68).

IN-LBF)
MOMENT (
BEAM
MEASURED

I	0.0	1-1.98	2 22	3 0.24 -1.37	0.28	0.25	6 -0.14 1.24	0.76
NIS 249	000	3.49 -2.37	1.91	0.63	-1.61	0.17	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	-0.24 -0.61
358 SIN COS	000	0.0	004	0.0			000	0.0
	4.18	0.40	0.21	0.38	8 1.06 MOMON TANK	-	0.78	1.23
STAZHARM	0	Ħ	MEASURED 2	(1)	6N 1 1 1 1 6 6 6 6 6 6 6 6 6 6 6 6 6 6 6	2	9	7
80% SIN	0.0	0.0	0.0	000	0.0	0.0	0.0	0.0
65% SIN	0.0	2.93	2.35	-3.67	-2.42 -1.12	0.22	0.55	0.03
45% SIN COS	0.0	5.41	1.52	-3.59	-2.21	79.0	0.19	0.18
35% SIN COS	0.0	6.44	0.40	-2.59	-1.61	0.52	0.02	0.06
20% SIN	0.0	9.48	0.02	1.98	0.38	0.26	0.79	-0.55

TABLE 29. CALCULATED BEAM AND CHORD BENDING MOMENTS, FIBERGLASS BLADE, 0° TWIST, $\delta_F = 5$ $\mu = 0.299$, $M_{1,90} = 0.408$, $\alpha_m = 0$ ° (COND. 68).

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	٠	000000000000000000000000000000000000000		9	0.00 0.02 0.03 0.03 0.03 0.06 0.06
•	5	0.04 0.03 0.03 0.04 0.06	F)	'n	0.14 0.10 0.17 0.17 0.05 0.05 0.14
MOMEN I IN-LEF	4	0.01 0.02 0.02 0.02 0.04 0.07 0.01	CHORD MOMENT(IN-LBF)	4	0.12 0.12 0.20 0.09 0.19 0.03 0.03
באון שכא	ю	0.57 0.07 0.59 0.17 0.32 0.47 0.18 0.52	CHORD MOM	m	-0.08 -1.21 -0.44 -2.17 -1.06 -2.26 -1.22 -1.90 -1.16
	2	0.09 0.25 0.25 0.37 0.37 0.47 0.49	COMPUTED	2	-0.91 0.13 -1.60 0.52 -1.60 1.08 -1.30 1.20 -0.73
	-	-1.32 1.11 -1.70 1.23 -1.60 0.61 -1.43 0.28 -1.74		-	-0-47 -0-39 0-94 0-10 4-96 2-04 6-46 6-88
	0	0.0 0.0 0.0 0.0 2.56 0.0 3.33		0	0.0 1.77 0.0 3.08 0.0 3.21 0.0 3.14 0.0
	STAZHARM	803 SIN COS 653 SIN 453 SIN 203 SIN COS 203 SIN COS		STAZHARM	803 SIN COS 652 SIN COS 352 SIN COS 202 SIN COS COS COS

MEASURED BEAM AND CHORD BENDING MOMENTS, ALUMINUM BLADE, 0° TWIST μ = 0.399, M₁,90 = 0.434, $\alpha_{\rm m}$ = 0.5° (COND. 25). TABLE 30.

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9	-1.72 0.99 -0.25 1.57 -0.42 -0.05 -0.05		٥	0.2	324	0.09 -0.35 0.49 -0.15
5	00.82 00.886 00.886 00.004 00.004 10.886	_	'n	24.00	877	-5.29 6.25 -2.56 4.30
4	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	MOMENT (IN-LBF	4	3. 1. 2. C. 3. C.	2.2	5.44 -3.14 1.75 -1.92
R	1.62 1.3.62 1.8.85 1.8.97 1.8.97 1.8.28 1.8.28	CHORD MOM	m	ω. Ο ιύ α	2.4	-11.02 -0.57 -11.68 3.26
2	-0.49 -6.14 -0.01 -7.11 0.32 -3.28 0.82 -1.76 2.74	MEASURED	2	26.4	W - 4	1.46 4.50 3.07 3.20
-	-1.82 2.49 -1.44 4.72 -0.63 -0.23 4.26 1.24		7	41.0	2.3	18.45 -4.61 26.67 -5.71
0	2.56 2.24 2.24 2.24 3.00 8.11		C		• • •	3000
STA/HARM	803 SIN COS 653 SIN 653 SIN 253 SIN 203 SIN COS COS		STA/HARM	80% SIN COS	i ma	35% SIN COS 20% SIN COS

CALCULATED BEAM AND CHORD BENDING MOMENTS, ALUMINUM BLADE, 0° TWIST, μ = 0.399, $M_{1,90}$ = 0.434, $\alpha_{\rm m}$ = 0.5° (COND. 25). TABLE 31.

(1A-1AF)	
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STA/HARM	HARM	0	-	2	m	4	n	0	
808	SIN	3.0	-1.61	2.07	3.46	-0.61	-1.46	-0.01	
	COS	-1.03	09.0	-3.64	-0.24	-1.6	-2.78	-0.64	l
653	215	0.0	-3.53	3.35	5.19	-0.20	-1.20	-0.19	١,٠٠
	cos	1.68	0.43	-2.56	0.96	62.0-	-2.38	-0.54	C • 1,
454	SIN	0.0	-3.87	2.92	40.4	1.0€	C.65	-0.10	
	COS	7.53	1.04	1.65	2.48	0.63	96.0	0.10	17.01
353	SIN	7•7	-2.87	2.13	3.90	1.45	1.32	J. 10	C . 13
	COS	3.28	1.05	2.49	2.42	1.16	2.14	0.37	-C-13
23%	SIN	0.0	-1.31	1.20	3.36	1.55	1.94	ù.62	- C • C 4
	COS	8.82	1.25	2.46	1.96	1.65	3.23	0.51	-1.15

COMPUTED CHORD MUMENT(IN-LBF)

STA/HARM	4A R.M	C	٦	2	8	4	S	9	7
808	NIS		1.40	-0.49	1.32	-3.42	-4.65	30.0)·
5 5	SIN	2.44 0.0	3.03	-0.00	20.7-	-1.43 -0.63	-0.41 -1.26	0.05 70.0-	ト・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・・
	CUS		0.30	0.23	-4.15	-2.93	-0.68	0.15	かつ・こー
45%	N I S		4.09	-1.47	3.3>	-1.C1	-1.53	-O.08	47.1
	COS		8.11	0.57	-5.38	-3.74	-j.66	÷7•0	71.0-
35%	NIS		3.99	-1.39	3.14	-0.51	-1.38	-0.00	サッ・ ウ
	COS		7.45	0.61	-5.02	-3.46	-0.54	0.24	-c.12
2.2 %	ZIS		3.05	-0.95	2.16	-0.58	-0.69	-:•02	r.C2
	CUS		4.45	0.53	-3.43	-2.32	-v.28	0.18	VO. 1-

MEASURED BEAM AND CHORD BENDING MOMENTS, ALUMINUM BLADE, 0° TWIST $\mu = 0.502$, M1,90 = 0.467, $\alpha_{\rm m} = 5.0^{\circ}$ (COND. 44). TABLE 32.

				MEASURED	MEASURED BEAM MOMENI(IN-LBF)	NICIN-LBF	۸.		
STA/HARM	AARM	O	1	2	М	4	Ŋ	9	7
406	NIS	0.0	-1.79	-0.51	3.89	0.23	-1.43	-0.66	C-22
	CGS	3.20	3.15	-6.19	-5.95	-0.80	-0.14	-0.48	0.61
05%	NI S	0.0	-1.12	-0.84	7.16	0.44	-2.28	-0.51	C.14
	cos	5.76	6.41	-6.33	-9.20	-1.30	-0.94	-0.31	0.27
45%	SIN	0.0	-0.04	-1.12	9.70	-0.31	-0.21	0.14	-6.87
	COS	04.6	5.25	-3.94	-8.98	-1.73	0.05	-0.24	-0.25
35%	SIN	0.0	-0.05	-1.18	6.39	-0.59	1.26	-0.17	-C.10
	COS	9.62	3.89	-2.82	-8.82	-1.42	00.0	-0.14	-C.10
20%	SIN	J.C	0.00	0.58	7.98	-1,42	1.83	0.30	C • 54
	COS	8.64	2.45	0.41	-7.67	-0.5E	-0.73	0.96	-0.27

	7	05.0	C.65	1.73	1.69	1.77	1.01	1.11	C.40	-6.57	-0.53
	٥	-2.25	0.45	-4.21	0.94	-3.80	1.64	-2.16	1.40	0.93	-0.12
F)	'n	-5.96	-3.06	-12.37	-5.95	-15.84	-7.54	-14.93	-6.12	-8.90	-3.28
MEASURED CHORD MOMENT(IN-LBF)	4	4.73	0.24	9.72	0.12	11.39	-0.53	9.42	-1.50	3.01	-1.52
CHORD MOM	8	-2.66	-2.06	-6.53	-3.78	-12.00	-3.76	-12.30	-3.44	-14.13	0.56
MEASURED	2	-0.54	2.75	-0.71	4.99	-0.25	6.19	0.59	5.54	2.18	3.92
	1	1.01	-0.55	3.45	-2.38	8.77	-3.84	11.72	-3.65	16.59	-4.41
	0	0.0	2.05	0.0	3.60	G • O	4.55	0.0	5.61	0.0	5.79
	STA/HARM	BCS SIN				45% SIN					

CALCULATED BEAM AND CHORD BENDING MOMENTS, ALUMINUM BLADE, 0° TWIST $\mu = 0.502$, $M_{1,90} = 0.467$, $\alpha_{m} = 5.0^{\circ}$ (COND. 44). TABLE 33.

	7)
	9	0.00 0.01 0.00 0.00 0.00 0.00 0.00 0.00	0.00 0.06
-	n	0-1-0-1-0-1-0-1-0-1-0-1-0-1-0-1-0-1-0-1	0.77
MOMENT (IN-LBF	1	00-00-00-00-00-00-00-00-00-00-00-00-00-	1.34
BEAM MOME	Ю	20 8 1 1 2 0 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	3.33
сомритер	7	1.77 -2.56 1.58 -1.08 -2.03 -0.52	-0.64 0.98
	-4	-1.12 -1.8c -1.45 -1.1c -1.4c	0.32
	10)	1 1 1 6 0 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9	J.J.
	STA/HARM	818 金石台 803 名 42名 803 名 42名 803 名 818 803 名 803 A 80	SIN

STAZHARM	Ð	-	2	m	4	ιC	9	7
		70.0-	0.35	1.08	-0.43	-0.32	0.13) • • • •
) () ()		0.00	2.21	76.01	99-0-	0.28	
424 SIN	0.0		0.84	2.87	-1.18 -2.75	0 - 0 - 0 - 0 - 0 - 0 - 0 - 0 - 0 - 0 -	0.36	((() () In ()
	0.0	v () v	1.25	2.67	12.65	0.52	0.33	ر د • • • ۲
	2.0	0.24	0,53	1.85	-0.73	0.37	0.23	0.0

COMPUTED CHURD MOMENT(IN-LBF)

TABLE 34. MEASURED BEAM AND CHORD BENDING MOMENTS, ALUMINUM BLADE, 0° TWIST $\mu = 0.299$, $M_{1,90} = 0.408$, $\alpha_{\rm m} = 0$ ° (COND. 68).

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				MEASURED	BEAM MUME	MUMENI (IN-LBF			
STA/	STA/HARM	0	т	2	3	4	Ŋ	ð	7
808	S	•	• 1	0.9	0	٠ د	1.6	1.1	ر. ن
		•	3	6.5	9.		1.4	0.0	J. C
65%	SIN	O.O	-2.76	-1.91	2.27	0.78	-1.53	-0.71	
	0	•	4.	6.1	6.2	9	1.5	0.0	1.5
453	SI	•	2.2	0.1	7.	4.	• 5	ú.l	ر. د.
		^	3.0	1.5	6.5	(n	4.	0.3	٠ •
358	S	•	• 2	1.0	0.2	0.7	.	0.4	-
	0	•	.	0.3	5.3	5	'n	0.1	~
20%	_	•	4	3.1	0.3	1.5	ဆ	1.0	٠
			• 6	8	4.3	~	.2	• 9	. 2
				MEASURED	CHORD MOM	MOMENT (IN-LBF	F)		
STA/HAR	HARM	O	٦	7	e n	4	'n	٥	7
808	-	•	4.	4.	2.		7.	0.4	5
	0	•	ထ	6.	2.3	1.6	ω,	0.2	7.
859	NIS	0.0	8.96	-0.60	-5.59		-3.63	-0.68	1.18
	0	•	1.4	.8	3.6	5.9	1.3	0.4	•
45%	\vdash	C	8.7	5	8.1	4.7	9.	0.7	. 7
	0	•	1.7	3	2.6		1.1	9.0	٠,
358	-	0	4.8	0	8.9	3.2	3.8	0.6	د.
	\circ	•	.7	1	2.4	φ.	1.0	4.0	π)
20%	-	•	5.8	0	9.1	•	•2	0.2	•
	\Box	12.32	.5	6.	0.1	6.	0.3	0.3	7.

TABLE 35. CALCULATED BEAM AND CHORD BENDING MOMENTS, ALUMINUM BLADE, 0° TWIST $\mu = 0.299$, $M_{1,90} = 0.408$, $\alpha_{\rm m} = 0$ ° (COND. 68).

LBF)
I-NI)
MOMENT
BEAM
CUMPUTED

STA/HARM 80% SIN 65% SIN 65% SIN 20% SIN 20% SIN 20% SIN 80% SIN 65% SIN 65% SIN COS COS		0 2 7 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	1	CUMPUTED (CUMPUTED (C.48)	3 1.35 0.23 1.86 0.80 1.32 1.31 (.91 1.26 0.56 1.10 -0.70 -0.70 -1.44	MOMENT(IN-LBF 00.021 00.021 10.021 10.031 00.034 00.039 00.039 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001 10.001	E C C C C C C C C C C C C C C C C C C C	000000 0000000 00000000000000000000000	
35% S C 20% S	- O - O		1 × 2 × 4	2.3 0.8 1.5 0.6	1.0	0000	2000	-2	0 (((

LIST OF SYMBOLS

A _n	Harmonic coefficient of cosine terms
a	Vertical intercept of regression line
B _n	Harmonic coefficient of sine terms
Ъ	Slope of regression line
C^{D}	Drag coefficient
C _D /σ	Rotor drag coefficient
$c_{\mathtt{L}}$	Lift coefficient
C _L	Rolling moment coefficient
$c_{L_{max}}$	Maximum lift coefficient
c _m	Pitching moment coefficient
c _n /o	Yaw moment coefficient
C _P /σ	Rotor power coefficient
C _{Pi} /o	Induced power coefficient
C _{Pp} /σ	Parasite power coefficient
C _Q /o	Rotor torque coefficient
$C^{\Gamma} \backslash o$	Rotor lift coefficient
$C^{\Lambda} \setminus a$	Rotor side force coefficient
E	Modulus of elasticity, 1b/in. ²
I	Area moment of inertia, in. 4
$\mathtt{I}_{\mathtt{EQ}}$	Equivalent area moment of inertia, in.4
L	Segment length, in.
L	Rotor lift, 1b
М	Bending moment magnitude, in1b
М	Mach number

Advancing tip Mach number
Quality factor
Blade radius, in.
Multiple correlation coefficient
Blade radial location, in.
Reynolds number
time, sec
Blade segment weight distribution, 15/in.
Distance from blade segment quarter chord to blade segment center of gravity, in. (positive forward)
Angle of attack, deg
Mast angle of attack, deg
Tip path plane angle of attack, deg
Flap angle on trailing edge flap airfoil, deg
Advance ratio
Blade segment mass moment of inertia in out-of- plane direction, 1b-sec2
Blade segment mass moment of inertia in in-plane direction, 1b-sec ²